

Cyclotomic Root Systems

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En hommage à Serge Bouc – mais sans catégories ni foncteurs

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Variations on an old work of Gabi Nebe

A joint work with Ruth Corran and Jean Michel

A few words about motivation

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One can classify the root systems \mathcal{R} and then classify the Weyl groups $G(\mathcal{R})$. Or proceed the opposite way: it's what we did for cyclotomic root systems and their (cyclotomic) Weyl groups.

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and s is the automorphism of V defined by

$$s(v) = v - \langle v, \alpha^\vee \rangle \alpha$$

whenever $\alpha \in L_s$ and $\alpha^\vee \in M_s$ are such that $\langle \alpha, \alpha^\vee \rangle = 1 - \zeta_s$.

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- 34 exceptional irreducible groups in dimension 2 to 8.
Their field of definition (all subfields of “small” cyclotomic fields) have the remarkable property that all their rings of integers are principal ideal domains.

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There is a $\text{Aut}(\mathcal{R})/G(\mathcal{R})$ -invariant natural pairing

$$(P_{\mathcal{R}}/Q_{\mathcal{R}}) \times (P_{\mathcal{R}^\vee}/Q_{\mathcal{R}^\vee}) \rightarrow k/\mathbb{Z}_k.$$

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Proposition

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Then the Cartan matrix of \mathcal{S} determines \mathcal{R} up to genera.

Name	Diagram	Cartan matrix	Orbits	\mathbb{Z}_k	connection index
G_{31}		$\begin{pmatrix} 2 & i+1 & 1-i & -i & 0 \\ 1-i & 2 & 1-i & -1 & -1 \\ i+1 & i+1 & 2 & 0 & -1 \\ i & -1 & 0 & 2 & 0 \\ 0 & -1 & -1 & 0 & 2 \end{pmatrix}$	s	$\mathbb{Z}[i]$	1
G_{32}		$\begin{pmatrix} 1-\zeta_3 & \zeta_3^2 & 0 & 0 \\ -\zeta_3^2 & 1-\zeta_3 & \zeta_3^2 & 0 \\ 0 & -\zeta_3^2 & 1-\zeta_3 & \zeta_3^2 \\ 0 & 0 & -\zeta_3^2 & 1-\zeta_3 \end{pmatrix}$	s	$\mathbb{Z}[\zeta_3]$	1
G_{33}		$\begin{pmatrix} 2 & -1 & 0 & 0 & 0 \\ -1 & 2 & -1 & -\zeta_3^2 & 0 \\ 0 & -1 & 2 & -1 & 0 \\ 0 & -\zeta_3 & -1 & 2 & -1 \\ 0 & 0 & 0 & -1 & 2 \end{pmatrix}$	s	$\mathbb{Z}[\zeta_3]$	2
G_{34}		$\begin{pmatrix} 2 & -1 & 0 & 0 & 0 & 0 \\ -1 & 2 & -1 & -\zeta_3^2 & 0 & 0 \\ 0 & -1 & 2 & -1 & 0 & 0 \\ 0 & -\zeta_3 & -1 & 2 & -1 & 0 \\ 0 & 0 & 0 & -1 & 2 & -1 \\ 0 & 0 & 0 & 0 & -1 & 2 \end{pmatrix}$	s	$\mathbb{Z}[\zeta_3]$	1

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and the corresponding reflecting lines are

$$L_s = kv_s \text{ with } v_s = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{and} \quad L_t = kv_t \text{ with } v_t = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \\ M_s = kv_s^\vee \text{ with } v_s^\vee = (2, 0) \quad \text{and} \quad M_t = kv_t^\vee \text{ with } v_t^\vee = (-1, 1).$$

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