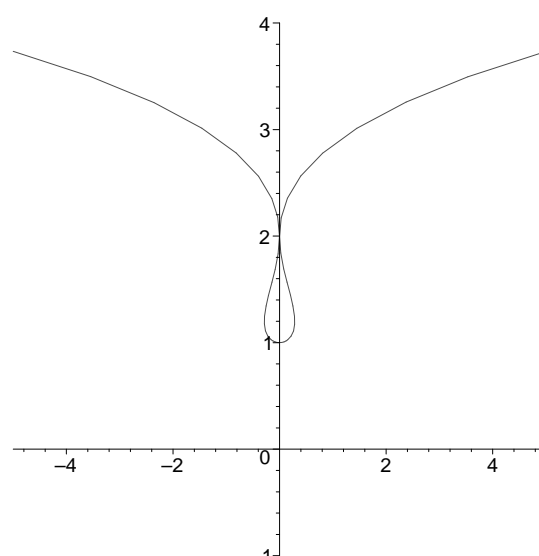


```
[ > interface(screenwidth=120);
[ > with(LinearAlgebra):
[ > P:=x^4+x+1;irreduc(P);

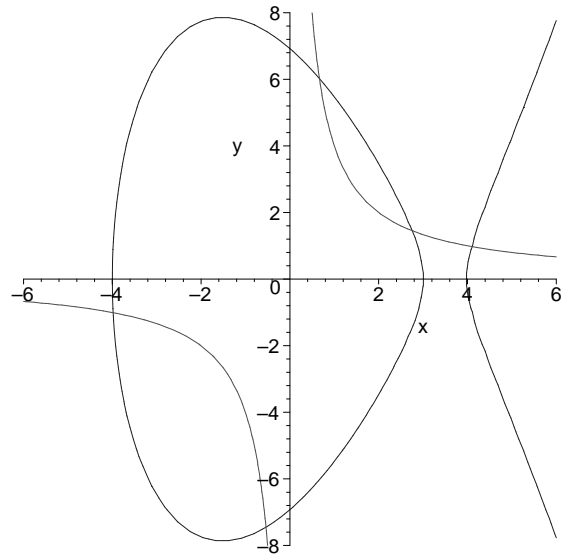
      P:=x^4+x+1
      true
[ > A:=1/d*add(a[i]*x^i,i=0..degree(P)-1);
      A:= $\frac{a_0+a_1x+a_2x^2+a_3x^3}{d}$ 
[ > H:=d*A;
      H:= $a_0+a_1x+a_2x^2+a_3x^3$ 
[ > M:=Matrix([seq([seq(coeff(rem(A*x^i,P,x),x,j),i=0..degree(P)-1)
, j=0..degree(P)-1)]);
      M:= $\begin{bmatrix} \frac{a_0}{d} & -\frac{a_3}{d} & -\frac{a_2}{d} & -\frac{a_1}{d} \\ \frac{a_1}{d} & \frac{a_0-a_3}{d} & -\frac{a_3+a_2}{d} & -\frac{a_2+a_1}{d} \\ \frac{a_2}{d} & \frac{a_1}{d} & \frac{a_0-a_3}{d} & -\frac{a_3+a_2}{d} \\ \frac{a_3}{d} & \frac{a_2}{d} & \frac{a_1}{d} & \frac{a_0-a_3}{d} \end{bmatrix}$ 
[ > cp:=CharacteristicPolynomial(M,x):
[ > re:=resultant(subs(x=y,P),d*x-substit(x=y,H),y):
[ > #le poly caract est 1/d^(deg P) * resultant: verification:
[ > expand(d^(degree(P))*cp-re);
      0
[ > P:=x^4+1;
      P:=x^4+1
[ > A:=x^2:H:=A;
      H:=x^2
[ > M:=Matrix([seq([seq(coeff(rem(A*x^i,P,x),x,j),i=0..degree(P)-1)
, j=0..degree(P)-1)]);
      M:= $\begin{bmatrix} 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$ 
[ > cp:=CharacteristicPolynomial(M,x):
[ > re:=resultant(subs(x=y,P),x-substit(x=y,H),y):
[ > #le poly caract est 1/d^(deg P) * resultant: verification:
[ > expand(cp-re);
      0
```

```
[ > #le poly min est une puissance de:
[ > gcd(re,diff(re,x));
      1+x^2
[ > MinimalPolynomial(M,x);#ils sont egaux.
      1+x^2
[ > XT:=t*(t^2-1)^2;YT:=t^2+1;
      XT:= $t(t^2-1)^2$ 
      YT:= $t^2+1$ 
[ > eq:=resultant(XT-x,YT-y,t);
      eq:= $x^2+16-48y+56y^2-32y^3+9y^4-y^5$ 
[ > with(plots):with(plottools):
Warning, the name changecoords has been redefined
Warning, the name arrow has been redefined
[ > dessin1:=plot([XT,YT,t=-2..2],color=red):
[ > #le fait de faire display apres permet d'ajuster l'echelle plus
facilement
[ > display(dessin1,view=[-5..5,-1..4]);
```



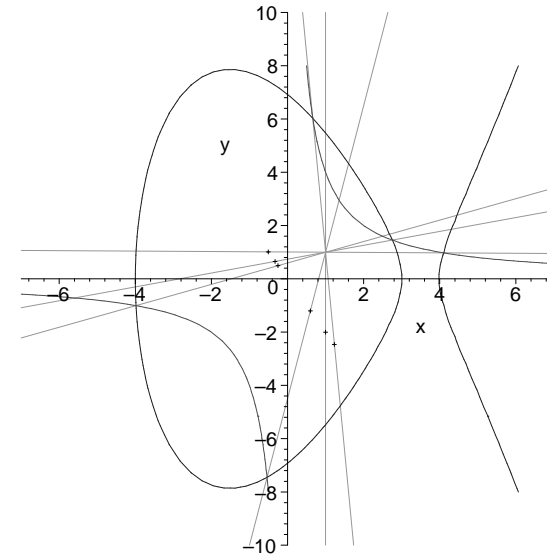
```
[ > C1:=x*y-4;C2:=y^2-(x-3)*(x^2-16);
      C1:= $yx-4$ 
      C2:= $y^2-(x-3)(x^2-16)$ 
[ > d1:=implicitplot(C1,x=-7..7,y=-8..8,color=red,numpoints=2000):
[ > d2:=implicitplot(C2,x=-6..7,y=-8..8,color=blue,numpoints=2000):
```

```
> display(d1,d2,view=[-6..6,-8..8]);
```

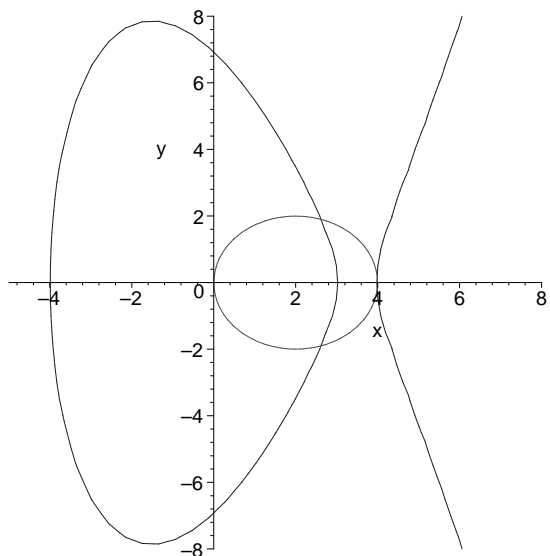


```
> #On elimine y
> eqx:=resultant(C1,C2,y);
      eqx:=-48 x^2-x^5+16 x^3+3 x^4+16
> factor(eqx,real); # on obtient 5 points reels.
-1.(x+3.981892356)(x+0.5365997443)(x-0.6633796231)(x-2.749235551)
(x-4.105876927)
> #c'est de degre 5 car le centre de projection (0,1,0) est
solution.
> resultant(subs(y=2*x,C1),subs(y=2*x,C2),x);#il n'est pas nul
      6112
> #NB: A=(1,1) n'est pas sur la droite y=2x. Bt=(t,-2t)
> #eq param de la droite (ABt): x=1+l(t-1),y=1+l(-2t-1)
> C1t:=subs(x=1+l*(t-1),y=1+l*(-2*t-1),C1);
      C1t:=(1+l(-2 t-1))(1+l(t-1))-4
> C2t:=subs(x=1+l*(t-1),y=1+l*(-2*t-1),C2);
      C2t:=(1+l(-2 t-1))^2-(-2+l(t-1))((1+l(t-1))^2-16)
> #la projection est donn{\'e}e par les points de coordonn{\'e}e
(t,2t) o{\u} t
> #racine de:
> p2:=resultant(C1t,C2t,1);
      p2:=-14699 t^6+25716 t^5+1779 t^4-15116 t^3-624 t^2+2496 t+448
> # car c'est l'intersection de y=2x avec la droite passant par
```

```
(1,1)
[ > #et le point a l'infini de Oy qui etait bien dans C1 inter C2
[ > with(plottools):
[ > sol:=solve(p2*1.0);
      sol:=1.,-0.5062528649,-0.3273837129,-0.2487685675,0.6001057333,1.231806181
[ > pil:=seq(point([sol[i],-2*sol[i]],color=black),i=1..6):
[ > d1:=seq((line([1-10*(sol[i]-1),1-10*(-2*sol[i]-1)], [1+10*(sol[i]
]-1),1+10*(-2*sol[i]-1)],color=green)),i=1..6):
[ > display(d1,d2,pil,d1,view=[-7..7,-10..10]);
```



```
> C1:=(x-2)^2+y^2-4;
      C1:=(x-2)^2+y^2-4
> C2:=y^2-(x-3)*(x^2-16);
      C2:=y^2-(x-3)(x^2-16)
[ > d1:=implicitplot(C1,x=-1..5,y=-3..3,color=red,numpoints=1000):
[ > d2:=implicitplot(C2,x=-5..8,y=-8..8,color=blue,numpoints=1000):
[ > display(d1,d2,view=[-5..8,-8..8]);
```



```
[ solx[3]
[ > #soit reel ce qui explique pourquoi le dessin ne nous donnait
[ que 4 points.
[ >
```

```
[ > #On elimine y
[ > eqx:=resultant(C1,C2,y);
[
[      eqx:=(2x2+20x-48-x3)2
[ > factor(eqx,real); # on obtient 5 points reels.
[      (x+4.605551275)2(x-2.605551275)2(x-4)2
[ > factor(eqx);#On voit qu'il faut introduire le discriminant.
[      (x-4)2(x2+2x-12)2
[ > factor(eqx,sqrt(13));
[      (x+1+sqrt(13))2(x+1-sqrt(13))2(x-4)2
[ > eqred:=gcd(eqx,diff(eqx,x));
[      eqred:=-2x2-20x+48+x3
[ > solx:=[solve(eqred)];
[      solx:=[4,-1+sqrt(13),-1-sqrt(13)]
[ > soly:=seq(gcd(subs(x=solx[i],C1),subs(x=solx[i],C2)),i=1..3);
[      soly:=y2,18-6sqrt(13)+y2,18+6sqrt(13)+y2
[ > #les ordonn{\ 'e}es des points d'abscisse solx[i] sont:
[ > seq(solve(soly[i]),i=1..3);
[      0,0,sqrt(-18+6sqrt(13)),-sqrt(-18+6sqrt(13)),sqrt(-18-6sqrt(13)),-sqrt(-18-6sqrt(13))
[ > #On constate que pour solx[3] les ordonn{\ 'e}es des points de C1
[ inter
[ > # C2 yant cette abscisse sont complexes conjuguees bien que
```