

# Information topology and probabilistic graphical models

Juan Pablo Vigneaux  
*IMJ-PRG - Université Paris 7*

August 8, 2017

- 1 Introduction
- 2 Information structures
- 3 Information cohomology
- 4 Extension problems

# Outline

- 1 Introduction
- 2 Information structures
- 3 Information cohomology
- 4 Extension problems

# Minimal background

Shannon (1948): information content of a random variable

$X : \Omega \rightarrow \{x_1, \dots, x_n\}$  is

$$S_1[X](P) = - \sum_{k=0}^n \mathbb{P}(X = x_i) \log_2 \mathbb{P}(X = x_i) = \mathbb{E}_P \left\{ \log \left( \frac{1}{P(X)} \right) \right\}. \quad (1)$$

where  $\mathbb{P}$  is a probability on  $\Omega$ . The function  $S_1$  is called entropy.

# Minimal background

Shannon (1948): information content of a random variable

$X : \Omega \rightarrow \{x_1, \dots, x_n\}$  is

$$S_1[X](P) = - \sum_{k=0}^n \mathbb{P}(X = x_i) \log_2 \mathbb{P}(X = x_i) = \mathbb{E}_P \left\{ \log \left( \frac{1}{P(X)} \right) \right\}. \quad (1)$$

where  $\mathbb{P}$  is a probability on  $\Omega$ . The function  $S_1$  is called entropy.

Information is related to **uncertainty**.

- 1 If  $P(X = x_i) = 1$  for certain  $i$ , then  $S_1[X] = 0$ .
- 2 Uniform distribution on  $\{x_1, \dots, x_n\}$  implies  $S_1[X]$  maximal.

# Minimal background

Shannon (1948): information content of a random variable

$X : \Omega \rightarrow \{x_1, \dots, x_n\}$  is

$$S_1[X](P) = - \sum_{k=0}^n \mathbb{P}(X = x_i) \log_2 \mathbb{P}(X = x_i) = \mathbb{E}_P \left\{ \log \left( \frac{1}{P(X)} \right) \right\}. \quad (1)$$

where  $\mathbb{P}$  is a probability on  $\Omega$ . The function  $S_1$  is called entropy.

Information is related to **uncertainty**.

- 1 If  $P(X = x_i) = 1$  for certain  $i$ , then  $S_1[X] = 0$ .
- 2 Uniform distribution on  $\{x_1, \dots, x_n\}$  implies  $S_1[X]$  maximal.

Shannon recognized an important relation:

$$S_1[X, Y] = S_1[X] + S_1[Y|X].$$

Where  $S_1[Y|X] = \mathbb{E}_P(S_1[Y](P|_X))$ . (It looks like  $0 = X.f[Y] - f[XY] + f[X]$ .)

Havrda - Charvát (1967), Tsallis (1988):  $\alpha$ -entropy, defined as

$$S_\alpha[X](P) = c_\alpha \left( \sum_{k=1}^n P(X = x_k)^\alpha - 1 \right), \quad (2)$$

where  $\alpha \in (0, \infty) \setminus \{1\}$  and  $c_\alpha$  is some constant. Typical choices give  $S_\alpha[X] \rightarrow S_1[X]$  when  $\alpha \rightarrow 1$ .

Havrda - Charvát (1967), Tsallis (1988):  $\alpha$ -entropy, defined as

$$S_\alpha[X](P) = c_\alpha \left( \sum_{k=1}^n P(X = x_k)^\alpha - 1 \right), \quad (2)$$

where  $\alpha \in (0, \infty) \setminus \{1\}$  and  $c_\alpha$  is some constant. Typical choices give  $S_\alpha[X] \rightarrow S_1[X]$  when  $\alpha \rightarrow 1$ .

It satisfies a similar cocycle relation (stay tuned).

# Our purpose

To introduce a generalized notion of *statistical space*.  
Entropies appear as cocycles for a suitably defined cohomology on this space: information cohomology.

# Our purpose

To introduce a generalized notion of *statistical space*.  
Entropies appear as cocycles for a suitably defined cohomology on this space: information cohomology.

'A theory of "shape" for information.'

# Our purpose

To introduce a generalized notion of *statistical space*.

Entropies appear as cocycles for a suitably defined cohomology on this space: information cohomology.

‘A theory of “shape” for information.’

We will see that this space is the natural ground for some probabilistic problems with geometrical flavour.

# Outline

- 1 Introduction
- 2 Information structures**
- 3 Information cohomology
- 4 Extension problems

For any “good” space  $X$ , the category  $\text{Sh}(X)$  contains basically the same topological information as  $X$  and should be seen as  $X$  disguised as a topos (Moerdijk).

Grothendieck, Verdier,... (SGA IV): generalized the definition of sheaves to allow cases not covered by usual topology.

Our topos: presheaves on a small category  $\mathcal{S}$  such that...

Given a set  $\Omega$ , introduce the category of “finite observables”  $\mathcal{O}(\Omega)$ :

- objects: finite partitions.
- arrows:  $X \rightarrow Y$  if  $X$  refines  $Y$ .

## Definition

An **information structure**  $\mathcal{S}$  is a full subcategory of  $\mathcal{O}(\Omega)$  such that

- 1  $\text{Ob}(\mathcal{S})$  contains  $\mathbf{1} := \{\Omega\}$ .
- 2 If  $Y \leftarrow X \rightarrow Z$  in  $\mathcal{S}$ , then  $Y \times Z$  (the product in  $\mathcal{O}(\Omega)$ ) is in  $\text{Ob}(\mathcal{S})$ .

$X : \Omega \rightarrow E_X = \{x_1, \dots, x_n\}$  r.v.  $\leftrightarrow$  Partition  $\{X = x_i\}_{i=1}^n$

$(Y, Z) : \Omega \rightarrow E_Y \times E_Z$   $\leftrightarrow$  Product of partitions  $Y \times Z$   
 $\omega \mapsto (Y(\omega), Z(\omega))$

# Structure sheaf

For each  $X \in \text{Ob}(\mathcal{S})$ , the set

$$\mathcal{S}_X := \{Y \mid X \rightarrow Y\}$$

has the structure of a monoid, with binary law  $(Y, Z) \mapsto YZ := Y \times Z$ .

## Definition

The **structure sheaf**  $\mathcal{A}$  is the sheaf of algebras  $X \mapsto \mathcal{A}_X := \mathbb{R}[\mathcal{S}_X]$  (the monoid algebra).

# Family of examples: Graphical models

$$[n] := \{1, \dots, n\}$$

Set  $\Omega = \prod_{i \in [n]} E_i$  and let  $X_i$  be the projection on the  $i$ -th component.

For each  $I \subset [n]$ ,  $X_I := \prod_{i \in I} X_i$ . Then the abstract simplex  $\Delta([n])$  can be seen as an information structure.

# Family of examples: Graphical models

$$[n] := \{1, \dots, n\}$$

Set  $\Omega = \prod_{i \in [n]} E_i$  and let  $X_i$  be the projection on the  $i$ -th component.

For each  $I \subset [n]$ ,  $X_I := \prod_{i \in I} X_i$ . Then the abstract simplex  $\Delta([n])$  can be seen as an information structure.

Any simplicial subcomplex  $K$  of  $\Delta([n])$  also defines a structure  $\mathcal{S}_K$ .

# Family of examples: Graphical models

$$[n] := \{1, \dots, n\}$$

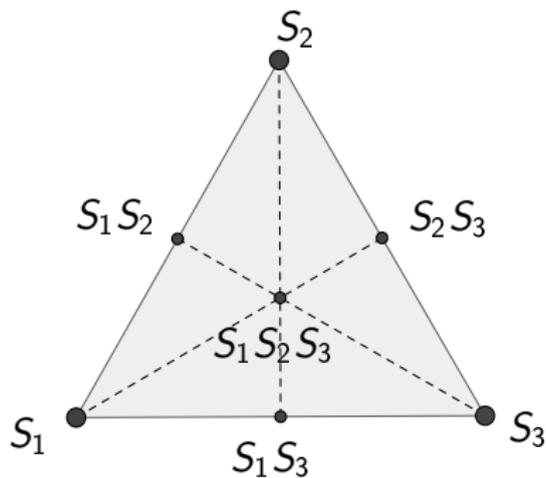
Set  $\Omega = \prod_{i \in [n]} E_i$  and let  $X_i$  be the projection on the  $i$ -th component.

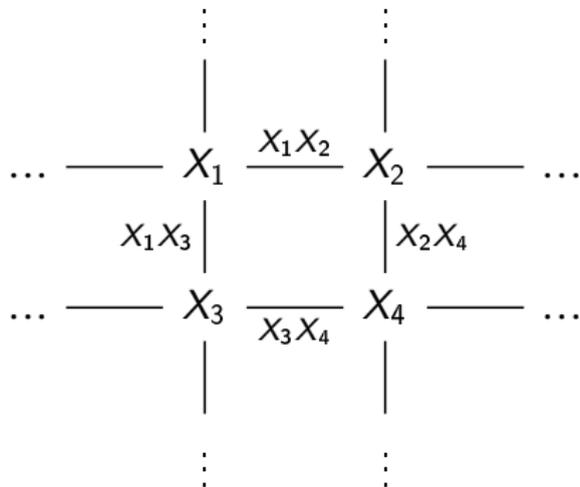
For each  $I \subset [n]$ ,  $X_I := \prod_{i \in I} X_i$ . Then the abstract simplex  $\Delta([n])$  can be seen as an information structure.

Any simplicial subcomplex  $K$  of  $\Delta([n])$  also defines a structure  $\mathcal{S}_K$ .

## Examples:

- Ising model: Fix a lattice  $\Lambda \subset \mathbb{Z}^d$ . If each  $X_i$  represent the "spin" on a site of  $\Lambda$ , and we consider  $X_i X_j$  each time that  $(i, j) \in \Lambda$ , we obtain an information structure  $\mathcal{S}_K$  where  $K = \Lambda$  (1-dim. complex).
- More general: Factor graphs.





For each  $X \in \text{Ob}(\mathcal{S})$ , set

$$\Delta(X) = \left\{ p : X \rightarrow [0, 1] \mid \sum_{x \in X} p(x) = 1 \right\}. \quad (3)$$

Note that  $\Delta(X) \cong \{(p_0, \dots, p_n) \in \mathbb{R}^n \mid p_i \geq 0 \text{ and } \sum p_i = 1\}$  whenever  $E_X = \{x_0, \dots, x_n\}$ .

For each  $X \in \text{Ob}(\mathcal{S})$ , set

$$\Delta(X) = \left\{ p : X \rightarrow [0, 1] \mid \sum_{x \in X} p(x) = 1 \right\}. \quad (3)$$

Note that  $\Delta(X) \cong \{(p_0, \dots, p_n) \in \mathbb{R}^n \mid p_i \geq 0 \text{ and } \sum p_i = 1\}$  whenever  $E_X = \{x_0, \dots, x_n\}$ . To each arrow of refinement  $\pi : X \rightarrow Y$ , it corresponds an operation called marginalization,  $\Delta(\pi) \equiv \pi_* : Q_X \rightarrow Q_Y$ , given by

$$\forall y \in Y, \quad \pi_* p(y) = \sum_{x \in \pi^{-1}(y)} p(x). \quad (4)$$

Notation:  $Y_*$  instead of  $\pi_*$  if  $\pi$  clear from context.

## Definition

A **probability functor**  $Q: \mathcal{S} \rightarrow \mathit{Sets}$  associates:

- To each  $X \in \mathit{Ob}(\mathcal{S})$  a subset  $Q_X$  of  $\Delta(X)$  stable under conditioning by variables  $Y \in \mathcal{S}_X$ ;
- To each  $\pi: X \rightarrow Y$ , the map  $Q(\pi) = \Delta(\pi)|_{Q_X}$ .

Simplicial families are always stable under conditioning.

# An important presheaf

For each  $X$ , define

$$F(Q_X) := \{f : Q_X \rightarrow \mathbb{R} \mid f \text{ measurable}\}. \quad (5)$$

For each arrow  $\pi : X \rightarrow Y$ , there is a map  $\pi^* : F(Q_Y) \rightarrow F(Q_X)$ ,  $f \mapsto f \circ \pi_*$ .

For each  $\alpha > 0$ , define an action of  $\mathcal{A}_X$  on  $F(Q_X)$  such that

$$\forall Y \in \mathcal{S}_X, \quad (Y.f)(P) = \sum_{y \in E_Y} P(Y=y)^\alpha f(P|_{Y=y}). \quad (6)$$

The corresponding  $\mathcal{A}_X$ -module is denoted  $F_\alpha(Q_X)$ .

	Differential	Algebraic	Statistical
Space	Open( $M$ ) for $M$ manifold	Spec( $R$ ) for ring $R$	Information structure $\mathcal{S}$
Structure sheaf	$C^0(U)$	$R_p$	$\mathcal{A}_X$
Sheaves of modules	$\Omega^k(U)$	...	$F_\alpha(Q_X)$
Action	$C^0(U)$ acts on $\Omega^k(U)$ by multiplication		$\mathcal{A}_X$ acts on $F_\alpha(Q_X)$ by conditioning.

# Outline

- 1 Introduction
- 2 Information structures
- 3 Information cohomology**
- 4 Extension problems

# Information cohomology: Definition

The information topos is the ringed topos  $(\text{PSh}(\mathcal{S}), \mathcal{A})$ . We are particularly interested in:

$\text{Mod}(\mathcal{A}) =$  category of presheaves  $M: \mathcal{S} \rightarrow \mathcal{A}\mathcal{B}$  such that, for all  $X \in \text{Ob}(\mathcal{S})$ ,  $\mathcal{A}_X$  acts on  $M(X)$ , functorially.

# Information cohomology: Definition

The information topos is the ringed topos  $(\text{PSh}(\mathcal{S}), \mathcal{A})$ . We are particularly interested in:

$\text{Mod}(\mathcal{A}) =$  category of presheaves  $M: \mathcal{S} \rightarrow \mathcal{A}\mathcal{b}$  such that, for all  $X \in \text{Ob}(\mathcal{S})$ ,  $\mathcal{A}_X$  acts on  $M(X)$ , functorially.

This is an abelian category (kernels and cokernels are computed over each  $X$ ).

# Information cohomology: Definition

The information topos is the ringed topos  $(\text{PSh}(\mathcal{S}), \mathcal{A})$ . We are particularly interested in:

$\text{Mod}(\mathcal{A}) =$  category of presheaves  $M: \mathcal{S} \rightarrow \mathcal{A}\mathcal{b}$  such that, for all  $X \in \text{Ob}(\mathcal{S})$ ,  $\mathcal{A}_X$  acts on  $M(X)$ , functorially.

This is an abelian category (kernels and cokernels are computed over each  $X$ ).

Let  $\mathbb{R}_{\mathcal{S}}$  be the presheaf that associates to each  $X \in \text{Ob}(\mathcal{S})$  the abelian group  $\mathbb{R}$  with trivial  $\mathcal{A}_X$  action (for  $s \in \mathcal{S}_X$  and  $r \in \mathbb{R}$ , take  $s \cdot r = r$ ).

# Information cohomology: Definition

The information topos is the ringed topos  $(\mathcal{PSh}(\mathcal{S}), \mathcal{A})$ . We are particularly interested in:

$\text{Mod}(\mathcal{A}) =$  category of presheaves  $M: \mathcal{S} \rightarrow \mathcal{A}\mathcal{b}$  such that, for all  $X \in \text{Ob}(\mathcal{S})$ ,  $\mathcal{A}_X$  acts on  $M(X)$ , functorially.

This is an abelian category (kernels and cokernels are computed over each  $X$ ).

Let  $\mathbb{R}_{\mathcal{S}}$  be the presheaf that associates to each  $X \in \text{Ob}(\mathcal{S})$  the abelian group  $\mathbb{R}$  with trivial  $\mathcal{A}_X$  action (for  $s \in \mathcal{S}_X$  and  $r \in \mathbb{R}$ , take  $s \cdot r = r$ ).

The functor  $\text{Hom}(\mathbb{R}_{\mathcal{S}}, -)$  is left exact, its associated derived functors are  $\text{Ext}^n(A, -)$ , for  $n \geq 0$ .

## Definition

The **information cohomology** groups with coefficients in  $F$  are

$$H^n(\mathcal{S}, F) := \text{Ext}^n(\mathbb{R}_{\mathcal{S}}, F).$$

# Information cohomology: Computation

The existence of a projective resolution  $0 \leftarrow \mathbb{R}_{\mathcal{S}} \leftarrow B_{\bullet}$  (via the bar construction) implies that information cohomology can be computed as the cohomology of the differential complex  $(\text{Hom}(B_{\bullet}, F), \delta)$ .

In particular,

$$H^1(\mathcal{S}, F_{\alpha}(Q)) = \ker\{\delta : \text{Hom}(B_1, F_{\alpha}(Q)) \rightarrow \text{Hom}(B_2, F_{\alpha}(Q))\}. \quad (7)$$

(Since  $\text{im } \delta_0$  is trivial.)

$B_1(X) := \mathcal{A}_X$ -module freely generated by the symbols  $[Y]$  with  $Y \in S_X$ ,  
and

The existence of a projective resolution  $0 \leftarrow \mathbb{R}_{\mathcal{S}} \leftarrow B_{\bullet}$  (via the bar construction) implies that information cohomology can be computed as the cohomology of the differential complex  $(\text{Hom}(B_{\bullet}, F), \delta)$ .

In particular,

$$H^1(\mathcal{S}, F_{\alpha}(Q)) = \ker\{\delta : \text{Hom}(B_1, F_{\alpha}(Q)) \rightarrow \text{Hom}(B_2, F_{\alpha}(Q))\}. \quad (7)$$

(Since  $\text{im } \delta_0$  is trivial.)

$B_1(X) := \mathcal{A}_X$ -module freely generated by the symbols  $[Y]$  with  $Y \in S_X$ ,  
and

$$(\delta f)[X|Y] = X.f[Y] - f[XY] + f[X]. \quad (8)$$

Let  $f \in \text{Hom}(B_1, F_\alpha(Q))$ . Whenever  $X \rightarrow Y \rightarrow Z$ ,

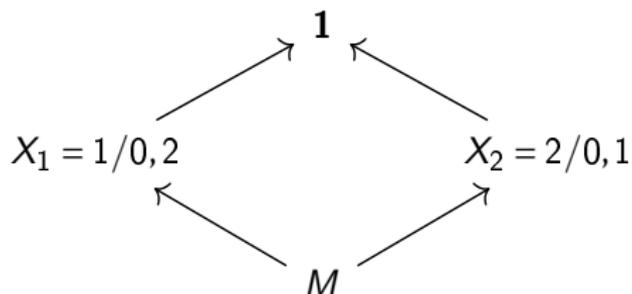
$$\begin{array}{ccc}
 [Z] & B_1(Y) \xrightarrow{f_Y} F_\alpha(Q_Y) & f_Y[Z] \\
 \downarrow & \downarrow & \downarrow \\
 [Z] & B_1(X) \xrightarrow{f_X} F_\alpha(Q_X) & f_X[Z] = \pi^* f_Y[Z]
 \end{array}$$

Equivalently:

$$f_X[Z](P_X) = f_Z[Z](Z_* P_X). \quad (9)$$

# Particular case

Let  $\Omega = \{0, 1, 2\}$ . Structure



A cocycle is given by three local functions:

$$f[X_1](p_0, p_1, p_2) = f[X_1](p_1, p_0 + p_2)$$

$$f[X_2](p_0, p_1, p_2) = f[X_2](p_2, p_0 + p_1)$$

$$f[X_1 X_2](p_0, p_1, p_2)$$

They verify

$$0 = X.f[Y] - f[XY] + f[X]$$

$$0 = Y.f[X] - f[XY] + f[Y]$$

## Particular case (continued)

The equations above give

$$X.f[Y] - f[Y] = Y.f[X] - f[X]. \quad (10)$$

Therefore, we look for two functions  $f_1, f_2$  that verify: for all  $(p_0, p_1, p_2) \in \Delta^2$ ,

$$\begin{aligned} (1-p_2)^\alpha f_1\left(\frac{p_0}{1-p_2}, \frac{p_1}{1-p_2}\right) - f_1(1-p_1, p_1) \\ = (1-p_1)^\alpha f_2\left(\frac{p_0}{1-p_1}, \frac{p_2}{1-p_1}\right) - f_2(1-p_2, p_2). \end{aligned} \quad (11)$$

Solutions: multiples of the corresponding entropy

$$s_\alpha(x) = \begin{cases} -x \log x - (1-x) \log(1-x) & \text{if } \alpha = 1 \\ \frac{1}{1-\alpha} (x^\alpha + (1-x)^\alpha - 1) & \text{otherwise} \end{cases}$$

## Theorem

*Under appropriate non-degeneracy hypotheses*

$$H^1(\mathcal{S}, F_\alpha(Q)) \cong \prod_{c \in H_0^{CW}(\mathcal{S}^*)} \mathbb{R} \cdot S_\alpha^{(c)}$$

*where  $c$  represents a connected component of  $\mathcal{S}^* = \mathcal{S} \setminus \mathbf{1}$  and*

$$S_\alpha^{(c)}[X] = \begin{cases} S_\alpha[X] & \text{if } X \in \text{Ob}(c) \\ 0 & \text{if } X \notin \text{Ob}(c) \end{cases}$$

# Extension of algebras

$\text{Ext}^n(\mathbb{R}_{\mathcal{S}}, F_{\alpha}(Q))$  encodes the different ways of constructing an **split** extension of algebras

$$0 \rightarrow F_{\alpha}(Q) \rightarrow E \rightarrow \mathcal{A} \rightarrow 0. \quad (12)$$

In fact, these are always congruent to

$$0 \rightarrow F_{\alpha}(Q) \rightarrow F_{\alpha} \times \mathcal{A} \rightarrow \mathcal{A} \rightarrow 0. \quad (13)$$

and the splitting is given by a morphism of presheaves algebras  $d: \mathcal{A} \rightarrow F_{\alpha} \times \mathcal{A}$  such that

$$(d[Y], Y) \bullet (d[X], X) = (d[YX], YX) \Leftrightarrow (d[Y] + Y \cdot d[X], YX) = (d[YX], YX). \quad (14)$$

Only solution: the entropy.

This transformation of products (successive measurements) into a sum (information) correspond to the third axiom of Shannon's characterization (Theorem 2 in his paper) and we see now that it suffices in generic situations.

But why are we interested in this property?

$X : \Omega \rightarrow E_X = \{x_0, x_1, \dots, x_s\}$  r.v. and  $\pi : X \rightarrow Y$ .

Take  $N \in \mathbb{N}$  and  $N(0), \dots, N(s)$  such that  $\sum N(i) = N$ ; define  $\nu(i) = N(i)/N$ .

From  $(x_0 + \dots + x_s)^N = (\sum_{y_i} (x_{j_1(i)} + \dots + x_{j_k(i)}))^N$ , we deduce that

$$\log \binom{N}{N(0), \dots, N(s)} = \log \binom{N}{NY_* \nu(0), \dots, NY_* \nu(t)} + \sum_{i=0}^t \log \binom{NY_* \nu(i)}{N(j_1(i)), \dots, N(j_k(i))} \quad (15)$$

If we take the limit  $N \rightarrow \infty$  imposing  $N(i)/N \rightarrow \mu_i$ , we obtain

$$S(\mu) = S(Y_* \mu) + \sum_{i=0}^t Y_* \mu(i) S(\mu | Y = y_i). \quad (16)$$

# Outline

- 1 Introduction
- 2 Information structures
- 3 Information cohomology
- 4 Extension problems**

# Frustration

A problem from statistical mechanics:

Consider the Ising model  $\mathcal{S}_\Lambda$ ; over each edge  $e = \{i, j\}$  of  $\Lambda$ , prescribe the law  $p_e \equiv p_{i,j} \in \Delta(X_e)$  (local interactions). These must be compatible i.e. for each segment

$$i \text{ --- } j \text{ --- } k$$

in  $\Lambda$ , they must verify

$$(X_j)_* p_{i,j} = (X_j)_* p_{j,k}. \quad (17)$$

Equivalently:  $p$  must be a section of  $\Delta: \mathcal{S}_\Lambda \rightarrow \mathcal{S}Sets$ .

Problem: when does it exist  $q \in \Delta(X_\Lambda)$  such that, for all  $e \in \Lambda$ ,

$$(X_e)_* q = p_e? \quad (18)$$

-  P. Baudot and D. Bennequin, *The homological nature of entropy*, *Entropy*, 17 (2015), pp. 3253–3318.
-  I. Csiszár, *Axiomatic characterizations of information measures*, *Entropy*, 10 (2008), pp. 261–273.
-  M. Gromov, *In a search for a structure, part 1: On entropy*, Preprint available at <http://www.ihes.fr/gromov>, (2012).
-  J. Havrda and F. Charvát, *Quantification method of classification processes. concept of structural a-entropy*, *Kybernetika*, 3 (1967), pp. 30–35.
-  C. Shannon, *A mathematical theory of communication*, *Bell System Technical Journal*, 27 (1948), pp. 379–423, 623–656.