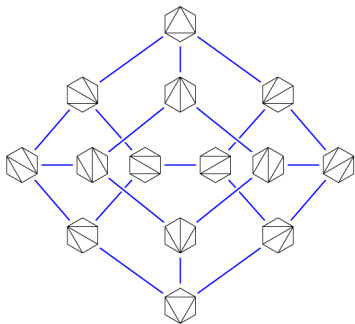


Geometry of Log-Concave Density Estimation

Bernd Sturmfels

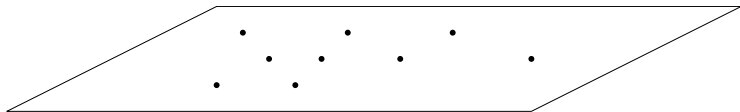
MPI Leipzig and UC Berkeley



joint paper with *Elina Robeva* and *Caroline Uhler*

Weighted Density Estimation

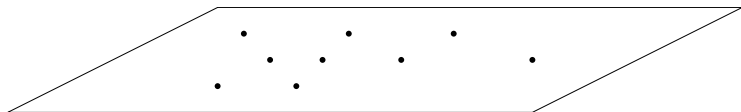
Given data: a point configuration $X = \{x_1, \dots, x_n\} \in \mathbb{R}^d$
with weights $w = (w_1, \dots, w_n)$, where $w_1, \dots, w_n \geq 0$, $\sum w_i = 1$.



These are i.i.d. samples from an unknown probability distribution p on \mathbb{R}^d . How to estimate p ?

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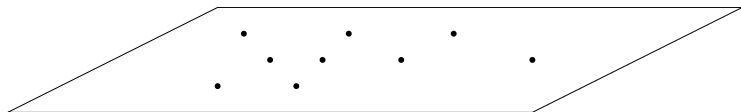


These are i.i.d. samples from an unknown probability distribution p on \mathbb{R}^d . How to estimate p ? Use **maximum likelihood estimation**, i.e. maximize the logarithm of the probability of observing the data:

$$\begin{aligned} & \text{maximize}_p \quad \sum_{i=1}^n w_i \log(p(x_i)) \\ & \text{s.t.} \quad p \text{ is a density} \end{aligned}$$

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Q: Does this optimization problem make sense?

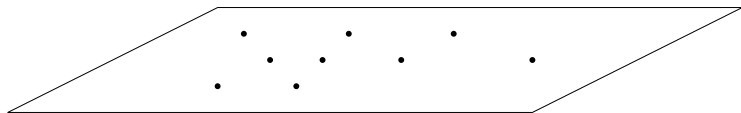
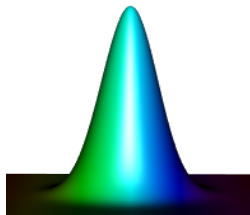
A: No, because we can choose p arbitrarily close to $\sum_{i=1}^n w_i \delta_{x_i}$.

Estimating Model Parameters

Assume that p is a d -dimensional **Gaussian distribution**:

$$p(x) = \frac{1}{(2\pi \det(\Sigma))^d} \cdot \exp\left(-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu)\right).$$

Mean $\mu \in \mathbb{R}^d$ and covariance matrix $\Sigma \in \text{Sym}_2(\mathbb{R}^d)$ are unknown.



MLE is easy: $\hat{\mu} = \sum_{i=1}^n w_i x_i$ and $\hat{\Sigma} = \sum_{i=1}^n w_i (x_i - \hat{\mu})(x_i - \hat{\mu})^T$.

Non-Parametric Statistics

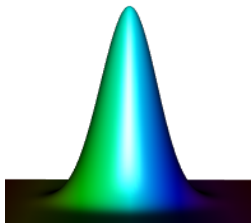
We do **not** assume a model with finitely many parameters.

The fewer assumptions the better.

This leads to

Shape-constrained maximum likelihood estimation

- ▶ monotonically decreasing densities: Grenander 1956, Rao 1969
- ▶ convex densities: Anevski 1994, Groeneboom, Jongbloed, and Wellner 2001
- ▶ log-concave densities: Cule, Samworth, and Stewart 2008
- ▶ generalized additive models with shape constraints: Chen and Samworth 2016

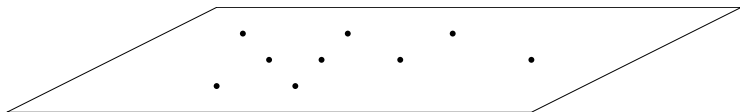


Gaussian densities are **log-concave**:

$-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu)$ is a concave function

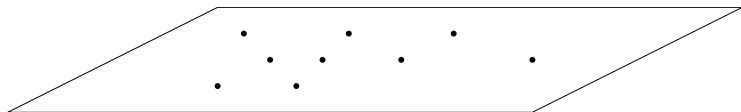
Our Optimization Problem

Maximize the log-likelihood of the given sample (X, w)
over all integrable functions $p : \mathbb{R}^d \rightarrow \mathbb{R}_{\geq 0}$ such that
 $\log(p)$ is concave and $\int_{\mathbb{R}^d} p(x) dx = 1$.



Our Optimization Problem

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 $\log(p)$ is concave and $\int_{\mathbb{R}^d} p(x) dx = 1$.



This problem was solved for uniform weights $w = \frac{1}{n}(1, 1, \dots, 1)$ by

M. Cule, R. Samworth and M. Stewart:

Maximum likelihood estimation of a multi-dimensional log-concave density,
J. R. Stat. Soc. Ser. B Stat. Methodol. **72** (2010) 545–607.

M. Cule, R.B. Gramacy and R. Samworth: *LogConcDEAD: an R package for maximum likelihood estimation of a multivariate log-concave density*,

J. Statist. Software **29** (2009) Issue 2.

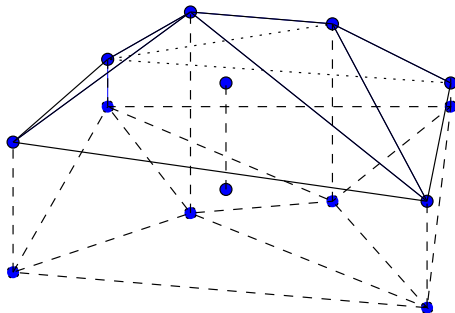
We extend to arbitrary w and develop the link to [geometric combinatorics](#):

J. De Loera, J. Rambau and F. Santos: *Triangulations. Structures for Algorithms and Applications*, Algorithms and Computation in Mathematics **25**, Springer Berlin, 2010.

Maximum Likelihood Estimation

Theorem

A log-concave maximum likelihood estimate \hat{p} exists for all (X, w) . It is unique with probability 1. The concave function $\log(\hat{p})$ is a tent function supported on the convex polytope $P = \text{conv}(X)$.

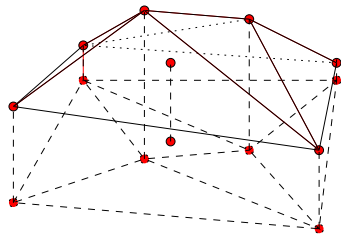
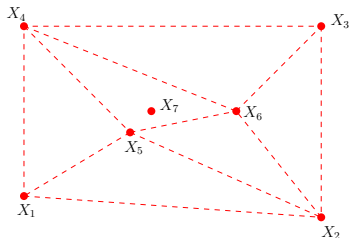


Tent function means: *piecewise linear and concave, supported on a regular polyhedral subdivision of the configuration X of n points in \mathbb{R}^d .*

Tent Functions

Given points $X = \{x_1, \dots, x_n\}$ and heights y_1, \dots, y_n at these points, the *tent function* $h_{X,y} : \mathbb{R}^d \rightarrow \mathbb{R}$ is the smallest concave function such that $h_{X,y}(x_i) \geq y_i$ for all i . Thus,

$$\hat{p} = \exp(h_{X,y}) \quad \text{for some height vector } y \in \mathbb{R}^n.$$



Two equivalent Optimization Problems:

$$\begin{aligned} & \text{maximize}_p \quad \sum_{i=1}^n w_i \log(p(x_i)) \\ & \text{s.t.} \quad p \text{ is a density} \\ & \text{and} \quad p \text{ is log-concave.} \end{aligned}$$

INFINITE DIMENSIONAL

$$\begin{aligned} & \text{maximize}_{y \in \mathbb{R}^n} \quad \sum_{i=1}^n w_i y_i \\ & \text{s.t.} \quad \int \exp(h_{X,y}(t)) dt = 1 \end{aligned}$$

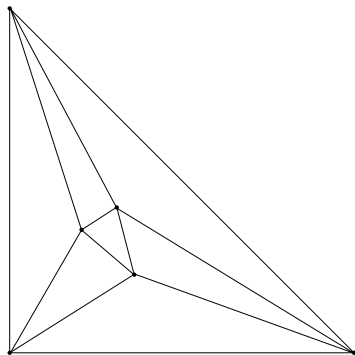
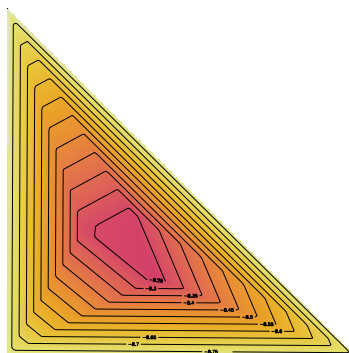
FINITE DIMENSIONAL

LogConcDEAD

Example

Let $d = 2$, $n = 6$, $w = \frac{1}{6}(1, 1, 1, 1, 1, 1)$, and fix the point configuration

$$X = ((0, 0), (100, 0), (0, 100), (22, 37), (43, 22), (36, 41)).$$



The optimal log-concave density \hat{p} for the six data points in X with [unit weights](#).

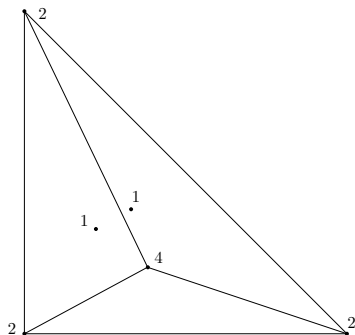
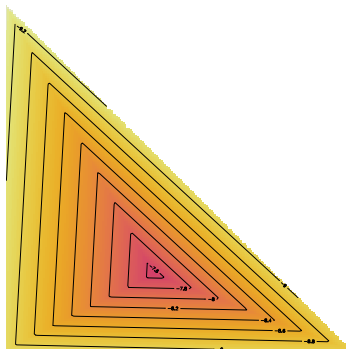
Computed with the **R** package of Cule, Gramacy and Samworth.

LogConcDEAD

Example

Let $d = 2$, $n = 6$, $w = \frac{1}{12}(2, 2, 2, 1, 4, 1)$, and fix the point configuration

$$X = ((0, 0), (100, 0), (0, 100), (22, 37), (43, 22), (36, 41)).$$

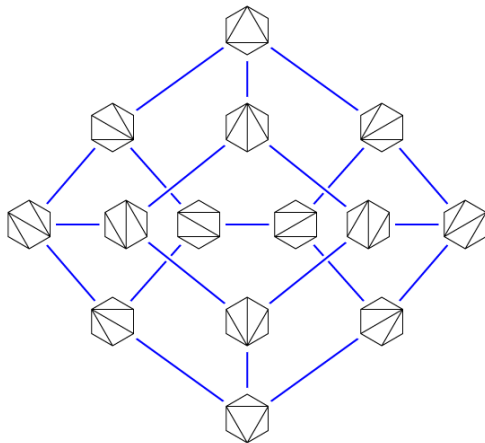


The optimal log-concave density \hat{p} for the six data points in X with **non-unit weights**.

Computed with the **R** package of Cule, Gramacy and Samworth.

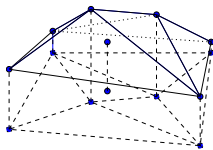
Secondary Polytope

The *secondary polytope* $\Sigma(X)$ has dimension $n-d-1$ but lives in \mathbb{R}^n . Its faces are in bijection with the *regular subdivisions* of X . The vertices of $\Sigma(X)$ correspond to *regular triangulations* of X .



I.M. Gel'fand, M.M. Kapranov and A.V. Zelevinsky: *Discriminants, Resultants and Multidimensional Determinants*, Birkhäuser, Boston, 1994.

Samworth Body



The **support function** of the **secondary polytope** $\Sigma(X)$ is the p.l. function that measures the **volume under the tent**:

$$\mathbb{R}^n \rightarrow \mathbb{R}, \quad y \mapsto \int_P h_{X,y}(t) dt.$$

The convex polyhedron dual to the secondary is unbounded:

$$\Sigma(X)^* = \left\{ y \in \mathbb{R}^n : \int_P h_{X,y}(t) dt \leq 1 \right\}.$$

The **Samworth body** is the following continuous analogue:

$$\mathcal{S}(X) = \left\{ y \in \mathbb{R}^n : \int_P \exp(h_{X,y}(t)) dt \leq 1 \right\}.$$

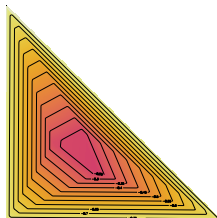
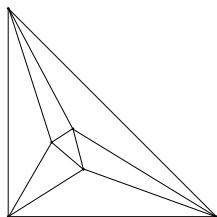
Proposition

The Samworth body $\mathcal{S}(X)$ is a full-dimensional closed convex set in \mathbb{R}^n .

Log-Concave Density Estimation

.... is Linear Programming over the Samworth body:

Maximize $w \cdot y$ subject to $y \in \mathcal{S}(X)$.



Proposition

This is equivalent to the unconstrained optimization problem

$$\text{Maximize } w \cdot y - \int_{\mathcal{P}} \exp(h_{X,y}(t)) dt \text{ over all } y \in \mathbb{R}^n$$

Interpretation: the optimal value function of our convex optimization problem is the *Legendre-Fenchel transform* of the convex function $y \mapsto \int_{\mathcal{P}} \exp(h_{X,y}(t)) dt$.

Barvinok meets Samworth

Lemma (Barvinok 1993)

Fix linear function $\ell : \mathbb{R}^d \rightarrow \mathbb{R}$ and a d -simplex σ . Then

$$\int_{\sigma} \exp(\ell(t)) dt = \text{vol}(\sigma) \sum_{i=0}^d \exp(y_i) \prod_{j \neq i} (y_i - y_j)^{-1},$$

where y_0, y_1, \dots, y_d are the values of ℓ at the vertices of σ .

Theorem (Cule, Samworth, Stewart 2008)

Let $y \in \mathbb{R}^n$ such that $h_{X,y}$ induces a triangulation Δ of X . Then

$$\int_C \exp(h_{X,y}(t)) dt = \sum_{\sigma \in \Delta} \sum_{i \in \sigma} \frac{\text{vol}(\sigma) \exp(y_i)}{\prod_{j \in \sigma \setminus i} (y_i - y_j)}.$$

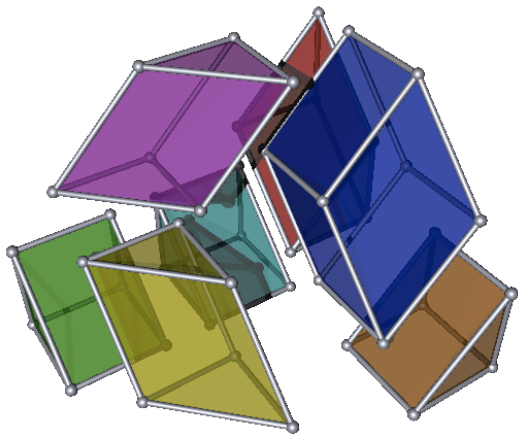
Corollary

On the secondary cone of a fixed triangulation Δ , the Samworth body $S(X)$ consists of all y such that the right hand side is ≤ 1 .

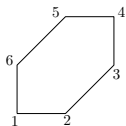
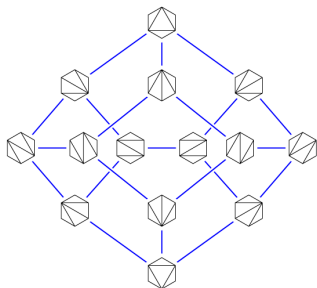
Every Regular Subdivision Arises

Theorem

For *every* regular subdivision Δ of X , there exists an open subset $\mathcal{U}_\Delta \subset \mathbb{R}^n$ such that, for every $w \in \mathcal{U}_\Delta$, the optimal solution \hat{p} to the optimization problem for (X, w) gives rise to the subdivision Δ .



Six Points in the Plane



Fix the configuration

$$X = \{(0, 0), (1, 0), (2, 1), (2, 2), (1, 2), (0, 1)\}$$

We sampled 100,000 vectors uniformly from the simplex $\{w \in \mathbb{R}_{\geq 0}^6 : \sum_{i=1}^6 w_i = 1\}$.
For each w , we computed the optimal y and the subdivision it induces:

\emptyset	35	46	24	15	13	26	25	14	36			
30.5	5.95	5.85	5.84	5.83	5.75	5.70	3.91	3.90	3.87			
13 15	26 46	15 35	13 35	24 26	24 46	13 14	35 36	14 24	26 36	14 46	25 35	15 25
1.23	1.21	1.21	1.20	1.16	1.14	0.96	0.92	0.92	0.92	0.92	0.90	0.90
25 26	14 15	36 46	24 25	13 36	13 46	26 35	15 24	13 14 15	13 15 35	14 24 46	24 26 46	
0.89	0.89	0.87	0.87	0.84	0.82	0.77	0.70	0.25	0.24	0.23	0.22	
15 25 35	26 36 46	13 35 36	24 25 26	13 36 46	25 26 35	15 24 25	14 15 24	13 14 46	26 35 36			
0.22	0.21	0.20	0.18	0.18	0.16	0.15	0.15	0.15	0.14			

Every Tent Function Arises

Lemma

Let Δ be a regular triangulation, given by h_{X,y^*} for some $y^* \in \partial\mathcal{S}(X)$. There exist weights $w \in \mathbb{R}_{\geq 0}^n$ that induce y^* .

Proof: The vector y^* is the global maximizer of the function

$$\sum_{i=1}^n w_i y_i - \int \exp(h_{X,y}(t)) dt.$$

By taking the partial derivative with respect to y_i , we find

$$\begin{aligned} w_i &= \frac{\partial}{\partial y_i} \int \exp(h_{X,y^*}(t)) dt \\ &= \sum_{\substack{\sigma \in \Delta: \\ i \in \sigma}} \text{vol}(\sigma) \exp(y_i^*) H(y_j^* - y_i^*, j \in \sigma \setminus i), \end{aligned}$$

where $H(u_1, \dots, u_d)$ is a certain explicit function of d arguments.

A Symmetric Function

Proposition

The following expressions define the same function $H : \mathbb{R}^d \rightarrow \mathbb{R}$:

- $$H = (-1)^d \frac{1 + u_1^{-1} + \dots + u_d^{-1}}{u_1 u_2 \dots u_d} + \sum_{j=1}^d \frac{e^{u_j}}{u_j^2 \prod_{k \neq j} (u_j - u_k)}$$
- $$H = \sum_{r=0}^{\infty} \frac{h_r(u_1, \dots, u_d)}{(r + d + 1)!}$$
- $$H = \int_{\Sigma_d} \left(1 - \sum_{i=1}^d t_i \right) \exp \left(\sum_{i=1}^d u_i t_i \right) dt_1 \dots dt_d.$$

This function is positive, increasing in each argument, and convex.

Here h_r is the homogeneous symmetric function, and Σ_d is the standard simplex.

Every Tent Function Arises

We characterize the **normal cones of the Samworth body**:

Theorem

Fix a vector $y \in \partial\mathcal{S}(X)$, let Δ be the regular subdivision of X that is induced by $h_{X,y}$ and $\Delta_1, \dots, \Delta_m$ all regular triangulations of X which refine Δ . Write $w^{\Delta_1}, \dots, w^{\Delta_m}$ for their weight vectors in \mathbb{R}^n with i -th coordinates seen two slides ago.

A vector of weights $w \in \mathbb{R}_{>0}^n$ induces the heights y if and only if

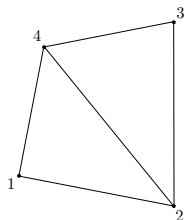
$$w \in \text{Cone}(w^{\Delta_1}, \dots, w^{\Delta_m}).$$

Corollary

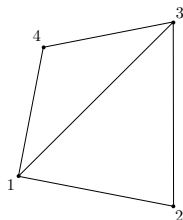
Fix $y^* = (c, c, \dots, c)$, where $c = -\log(\text{vol}(P))$, so that $\exp(h_{X,y})$ is a probability density. Then w^{Δ_i} is precisely the vertex of the secondary polytope $\Sigma(X)$ given by the regular triangulation Δ_i .

Four Points in the Plane

Let $x_1, x_2, x_3, x_4 \in \mathbb{R}^2$ be in convex position. Then X has two triangulations:



$$\Delta_1 = \{124, 234\}$$



$$\Delta_2 = \{123, 134\}$$

Pick $y \in \mathbb{R}^4$. If $h_{X,y}$ induces Δ_1 , then the weight vector w^{Δ_1} has coordinates

$$w_1^{\Delta_1} = v_{124} e^{y_1} H(y_2 - y_1, y_4 - y_1)$$

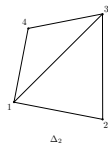
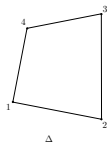
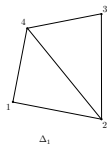
$$w_2^{\Delta_1} = v_{124} e^{y_2} H(y_1 - y_2, y_4 - y_2) + v_{234} e^{y_2} H(y_3 - y_2, y_4 - y_2)$$

$$w_3^{\Delta_1} = v_{234} e^{y_3} H(y_2 - y_3, y_4 - y_3)$$

$$w_4^{\Delta_1} = v_{124} e^{y_4} H(y_1 - y_4, y_2 - y_4) + v_{234} e^{y_4} H(y_2 - y_4, y_3 - y_4).$$

There is an analogous vector w^{Δ_2} for the other triangulation. If $h_{X,y}$ induces the flat subdivision Δ then w can be any positive linear combination of w^{Δ_1} and w^{Δ_2} .

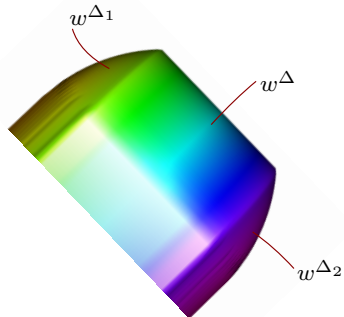
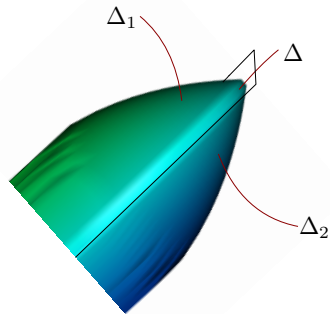
Convex Bodies



Samworth body

and

its dual



The secondary fan of X

and

the secondary polytope of X .

Unit weights

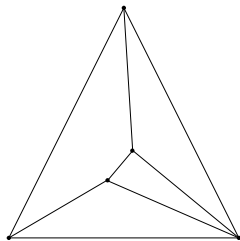
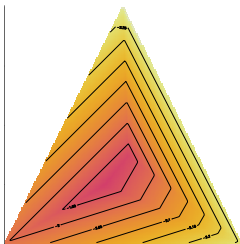
Theorem

Let X be a configuration of $n = d + 2$ points that span \mathbb{R}^d . If $w = \frac{1}{n}(1, \dots, 1)$, then the optimal density $\hat{\rho}$ is log-linear, and the optimal subdivision is trivial.

Example

Unit weights on the following configuration of five points

$$X = \{(0, 0), (40, 0), (20, 40), (17, 10), (21, 15)\}$$



Theorem

For any integer $d \geq 2$, there exists a configuration of $n = d + 3$ points in \mathbb{R}^d for which the optimal subdivision with respect to unit weights is non-trivial.

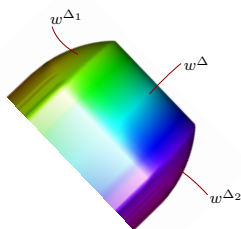
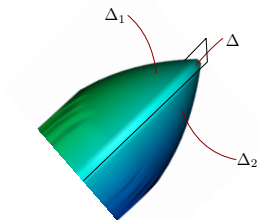
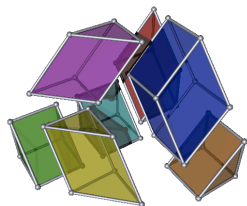
Experiments

We sampled six i.i.d. points in \mathbb{R}^2 from four different distributions:

- ▶ Gaussian $\mathcal{N}(0, 1)$
- ▶ Uniform
- ▶ Circular: $(U_1^a \cos(2\pi U_2), U_1^a \sin(2\pi U_2))$, where U_1, U_2 are i.i.d uniform on $[0, 1]$, and $a = 0.3$
- ▶ Circular: $(U_1^a \cos(2\pi U_2), U_1^a \sin(2\pi U_2))$, where U_1, U_2 are i.i.d uniform on $[0, 1]$, and $a = 0.1$

Subdivision: number of				Convex hull	Gaussian	Uniform	Circular	Circular
3-gons	4-gons	5-gons	6-gons		$\mathcal{N}(0, 1)$	$a = 0.5$	$a = 0.3$	$a = 0.1$
1	0	0	0	3	948	533	257	34
0	1	0	0	4	8781	6719	4596	1507
0	0	1	0	5	8209	9743	10554	8504
0	0	0	1	6	1475	2805	4495	9887
2	0	0	0	4	8	3	6	7
1	1	0	0	5	1	2	1	2
3	0	0	0	3	6	2	2	1
2	1	0	0	4	39	16	4	7
2	0	1	0	5	1	1	0	1
1	2	0	0	5	1	0	1	6
4	0	0	0	4	1	0	0	0
3	1	0	0	3	114	38	10	1
3	0	1	0	4	39	20	9	2
2	2	0	0	4	59	19	16	9
5	0	0	0	3	3	0	0	0
4	1	0	0	4	1	0	0	0
4	0	1	0	3	90	27	8	1
3	2	0	0	3	120	32	11	0
5	1	0	0	3	50	11	3	0
7	0	0	0	3	2	1	0	0

Open Problems



- ▶ Design a **test statistic** for log-concavity based on optimal Δ .
- ▶ What is the smallest size n of a configuration X in \mathbb{R}^d whose optimal subdivision with unit weights has at least c cells?
(e.g. we showed $n = d + 3$ for $c = 2, d \geq 2$.)
- ▶ Which subdivisions are realizable by points with unit weights?
- ▶ For a fixed w and a fixed combinatorial type of subdivision Δ , study the semianalytic set of all configurations X such that Δ is the optimal subdivision for the data (X, w) .