Invariances in variance estimates

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Abstract
We provide variants and improvements of the Brascamp–Lieb variance inequality which takes into account the invariance properties of the underlying measure. This is applied to spectral gap estimates for log-concave measures with many symmetries and to non-interacting conservative spin systems.

1. Introduction

Poincaré-type inequalities, which provide upper estimates of variances of functions by energy terms involving quadratic forms in their gradients, are versatile tools of mathematical analysis. They allow for example to quantify the concentration of measure or the ergodic behaviour of evolution processes. In the recent years, it has become clear that they provide crucial information on the distribution of mass and on the central limit theorem for convex bodies (see, for example, [1, 7, 20, 24]). Recall that for a Borel probability measure $\nu$ on a Euclidean space $(E, | \cdot |)$, its Poincaré constant $c_p(\nu) \in (0, +\infty]$ is the best constant for which we have

$$\text{Var}_\nu(g) \leq c_p(\nu) \int |\nabla g|^2 \, d\nu$$

for every $g \in L^2(\nu)$ locally Lipschitz, where the variance with respect to $\nu$ is defined by

$$\text{Var}_\nu(g) := \int \left( g - \int g \, d\nu \right)^2 \, d\nu.$$ 

For a random vector, $Y \in E$, if $\nu$ is the law of $Y$ (a relation denoted by $Y \sim \nu$), we define $c_p(Y) := c_p(\nu)$. Let us also recall here that when $\nu$ is log-concave (see below), this Poincaré constant is finite, and we have, for instance, the following bound proved by Kannan–Lovász–Simonovits [24] and Bobkov [7]

$$c_p(\nu) \leq 4 \inf_{a \in E} \int_E |y - a|^2 \, d\nu(y).$$

(2)

Spectral estimates enter in the asymptotic geometry of convex bodies and log-concave measures mainly when the measure $\nu$ is isotropic. A probability measure $\nu$ (or a random vector $X \sim \nu$) is isotropic if $\int_E x \, d\nu(x) = \mathbb{E} X = 0$ and $\text{Cov}(\nu) := \int_E x \otimes x \, d\nu(x) = \mathbb{E} X \otimes X = \text{Id}_E$. The KLS conjecture claims that the Poincaré constant of isotropic log-concave distributions is universally bounded, that is, $\sup\{c_p(\mu); \ n \geq 1, \mu \text{ isotropic log-concave probability on } \mathbb{R}^n\} < +\infty$. A weaker conjecture known as the variance conjecture claims a similar result but when we use only the function $f(x) = |x|^2$; since $\mathbb{E} |\nabla f(X)|^2 = 4n$ when $X$ is isotropic, this conjecture amounts to the bound

$$\text{Var}(|X|^2) \leq Cn$$

(3)

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for some universal constant $C > 0$ and for every isotropic log-concave vector $X \in \mathbb{R}^n$. We shall detail a bit more on this later.

This paper has been very much inspired by the work of Klartag [26], who obtained an optimal variance estimate in the case of log-concave measures which are invariant under coordinate hyperplane reflections. His approach was based on a new twist in the $L^2$ method, introduced by Hörmander. Our goal is to extend these techniques to a more general setting (non-log-concave measures, more general symmetries) that is adapted to applications in other topics. One of our main results, Theorem 3 appears as an improvement of the classical Brascamp–Lieb variance inequality, where the log-concavity assumption may be relaxed in the presence of symmetries and spectral gaps for restrictions to certain subspaces.

The paper is organized as follows. In the next section, we recall the principle of the $L^2$ method (in the presence of invariances) and present a streamlined version of Klartag’s argument as an introduction to our further study. Then, in § 3 we establish an abstract Poincaré-type inequality for measures and functions having well-balanced invariances. Our results, which involve the spectral gaps of conditioned measures orthogonal to fixed-points subspaces of isometries leaving the measure invariant, go beyond the class of log-concave measures. In § 4, we apply these results to estimate the variance of the norm of log-concave random vectors with many invariances (as a consequence, we confirm the variance conjecture for log-concave measures having the invariances of the simplex). Section 5 shows how to extend the variance estimates of § 3 to general functions. It uses a symmetrization procedure that relies on spectral properties of the group of isometries of the underlying measure. Section 6 is devoted to spectral gap estimates for log-concave probability measures, with, as before, a special emphasis on the measure having several invariances by reflections and on the Schatten classes. Section § 7 gives an application to the study of spectral gap of conditioned spin systems. Section 8 is mainly independent of the rest, as far as methods are concerned. It discusses the isotropy constant of convex bodies having well-balanced invariances. In the appendix, we collect some useful observations regarding groups generated by reflections which provide examples satisfying our assumptions throughout the paper.

We conclude this introduction with precisions about the setting of our study and the notation. We shall be working with a Borel probability measure $\mu$ on $\mathbb{R}^n$ with density,

$$d\mu(x) = e^{-\Phi(x)} \, dx.$$  

When $\Phi$ is convex, we say that $\mu$ is log-concave. In our proofs, we shall impose for simplicity the condition (5) that $\Phi$ is of class $C^2$ on $\mathbb{R}^n$. However, the inequalities we obtain are of course valid for a larger class of measure, by standard approximations that we leave to the reader. For instance, conditions of the form $D^2\Phi \geq \rho \mathbb{I}$ can be interpreted in the sense of distributions. More importantly, we shall explain below why the results extend to the case $\mu$ has some convex support $K$ (not necessarily $\mathbb{R}^n$, thus) provided $\Phi$ is $C^2$ on $K$ (we take the value $+\infty$ outside $K$). For instance, all the inequalities proved in the paper for log-concave measures of the form (5) remain valid for general log-concave measures having a convex support. In particular, the results apply to $\mu_K$, the normalized Lebesgue measure restricted to a convex body of $K \subset \mathbb{R}^n$, that is,

$$\mu_K(A) = \frac{|A \cap K|}{|K|}, \quad \forall A \subset \mathbb{R}^n.$$ 

Given an isometry of the standard Euclidean space $(\mathbb{R}^n, \langle \cdot, \cdot \rangle)$, $R \in O_n$ and a function $g$ on $\mathbb{R}^n$, we say that $g$ is $R$-invariant if $g \circ R = g$. A measure $\mu$ is $R$-invariant if its push-forward by $R$ is $\mu$, or equivalently if its density is $R$-invariant. Accordingly, a random vector $X \in \mathbb{R}^n$ is $R$-invariant if $RX$ and $X$ have the same law. These notions extend in an obvious way to $G$-invariance where $G \subset O_n$ is a group of isometries. It is worth noting that if a function $g$ (or a measure $\mu$) is invariant under $k$ isometries $R_1, \ldots, R_k \in O_n$, then it
is invariant under \( \langle \{R_i\}_{i \leq k} \rangle \), the group of isometries generated by these isometries. For a measure \( \mu \) (resp. a random vector \( X \in \mathbb{R}^n \)), we denote by \( \mathcal{O}_n(\mu) \) (resp. \( \mathcal{O}_n(X) \)) the group of all isometries leaving \( \mu \) (resp. \( X \)) invariant. Similarly, for a convex body \( K \subset \mathbb{R}^n \), we denote \( \mathcal{O}_n(K) := \{ R \in \mathcal{O}_n ; RK = K \} \). Recall that each isometry \( R \in \mathcal{O}_n \) comes with a linear subspace of fixed points,

\[
\text{Fix}(R) := \{ x \in \mathbb{R}^n ; Rx = x \}.
\]

For a group \( G \) of isometries, \( \text{Fix}(G) \) denotes the intersection of \( \text{Fix}(R) \) when \( R \) runs over \( G \).

We shall give special attention to the case of (orthogonal) hyperplane symmetries, which we denote by \( \mathcal{H}(\mu) \). A reflection is characterized by the fact that its fixed points form a hyperplane \( H = u^+ \) with \( u \) a unit vector, and we shall later use the following notation:

\[
S_H(x) := S_{u^+}(x) := x - 2(x \cdot u)u \quad \forall x \in \mathbb{R}^n. \tag{4}
\]

For a measure \( \mu \), we denote by \( \mathcal{R}_n(\mu) \subset \mathcal{O}_n(\mu) \) the group generated by the reflections leaving \( \mu \) invariant.

2. Generalities on the \( L^2 \) method

Hörmander developed the \( L^2 \) method for solving the \( \bar{\partial} \) equation, emphasizing the central role played by the convexity, or rather plurisubharmonicity, of the domain or of the potential \( \phi \) (see [23]). We will use only the ‘easy’ part of the method, namely the \textit{a priori} spectral-type inequalities (which are often referred to, in the real case, as Poincaré or Brascamp–Lieb inequalities). Since Hörmander’s seminal work, the \( L^2 \) method has been recognized as a powerful way of obtaining spectral inequalities, in particular in the context of statistical mechanics, where the method is also referred to as ‘Bochner’s method’, since in many cases the argument boils down to Bochner’s integration by parts formula (10). More recently, links with convex geometry have been emphasized. For instance, the \( L^2 \) method was used to provide a local proof of functional (complex or real) Brunn–Minkowski-type inequalities in [12, 13]. But it is mainly the more recent paper by Klartag [26] in which he proves the variance conjecture in the case of unconditional distributions, that was the starting point of the present work. Before going, let us discuss a bit the \( L^2 \) method itself.

Throughout the paper, we shall work, unless otherwise stated, with a probability measure \( \mu \) on \( \mathbb{R}^n \) of the form

\[
d\mu(x) = e^{-\Phi(x)} \, dx \quad \text{with} \quad \Phi : \mathbb{R}^n \to \mathbb{R} \text{ of class } C^2. \tag{5}
\]

Introduce the natural Laplace operator on \( L^2(\mu) \) given by

\[
Lu = \Delta u - \nabla \Phi \cdot \nabla u. \tag{6}
\]

This operator is well defined on \( C^2 \)-smooth functions and can be extended into an unbounded closed self-adjoint operator on \( L^2(\mu) \) with dense domain \( \mathcal{D}(L) \) corresponding to Neumann condition at infinity ensuring (7); however, this domain is not important for our purposes and we stress that it is enough to know that it contains the space of \( C^2 \)-smooth functions that are compactly supported, which we denote by

\[
\mathcal{D} := \{ u : \mathbb{R}^n \to \mathbb{R} ; u \text{ of class } C^2 \text{ and compactly supported} \}.
\]

For \( u \in \mathcal{D} \) and \( f \in L^2(\mu) \) locally Lipschitz (this is just a sufficient requirement to perform the integration by parts, in virtue of Rademacher’s differentiation theorem), we have

\[
\int f Lu \, d\mu = - \int \nabla f \cdot \nabla u \, d\mu. \tag{7}
\]
Since we work with $\mu$ finite, the kernel of the self-adjoint operator $L$ is given by the constant functions and its orthogonal space will be denoted by

$$L_0^2(\mu) := \left\{ f \in L^2(\mu); \int f \, d\mu = 0 \right\}.$$  

The variance of $f$ is then the square of the $L^2$-norm of the projection of $f$ onto $L_0^2(\mu)$. Note that the Poincaré inequality (1) for $\mu$ amounts to the spectral gap estimate $-L \geq c_p(\mu)$ on $L_0^2(\mu) \cap \mathcal{D}$, say.

The starting point of the argument is to dualize the Poincaré inequality using $L$. To this aim, many authors impose that one can solve $f = Lu$ for given $f \in L_0^2(\mu)$, which amounts to saying that $L$ has a closed range (oddly enough, this was rather the conclusion Hörmander was aiming at). This has the disadvantage that one has to enter into tedious discussions and eventually impose further conditions on the measure $\mu$. Instead, we shall use a simple density argument. Let alone this point, the next lemma is standard, except maybe for the fact that we have included a discussion on the invariances, for later use. So the classical and well-known statement corresponds to the case where $G = \{\text{Id}\}$, that is, no invariance is imposed.

**Lemma 1.** Let $\mu$ be a probability measure on $\mathbb{R}^n$ written as in (5), $L$ be the operator given by (6) and let $G$ a group of isometries leaving $\mu$ invariant. If there exists a map $A : x \rightarrow Ax$ from $\mathbb{R}^n$ to the set of positive $n \times n$ matrices such that, for every $u \in \mathcal{D}$ that is $G$-invariant, we have

$$\int (Lu)^2 \, d\mu \geq \int A \nabla u \cdot \nabla u \, d\mu,$$

then for every $f \in L^2(\mu)$ locally Lipschitz that is $G$-invariant we have,

$$\text{Var}_\mu(f) \leq \int A^{-1} \nabla f \cdot \nabla f \, d\mu.$$  

**Proof.** Let us fix $f \in L_0^2(\mu)$ that is locally Lipschitz and $G$-invariant, and assume that we have the dual spectral inequality (8) for functions $u \in \mathcal{D}$ that are $G$-invariant.

In order to avoid discussion about solvability of $f = Lu$, we will use the following easy and classical fact, recalled in [13]: the space $L(\mathcal{D})$ is dense in $L_0^2(\mu)$. We also need to check that one can use $G$-invariant functions $u$ to approach $f$. For this, note first that, for continuous functions, invariance by $G$ or by the closure of $G$ (in the usual topology of $\mathcal{O}_n$) is equivalent, so we can assume that $G$ is compact, and equipped with a bi-invariant Haar measure $\sigma$ normalized to be a probability. If $Lu_k \rightarrow f$ in $L^2(\mu)$ for some sequence $u_k \in \mathcal{D}$, introduce $\tilde{u}_k := \int_G u_k \circ R \, d\sigma(R)$. Then $\tilde{u}_k \in \mathcal{D}$ and by construction $\tilde{u}_k$ is $G$-invariant. By convexity of the norm, using that $f$ and $\mu$ are $G$-invariant, we see that $L\tilde{u}_k \rightarrow f$ in $L^2(\mu)$, as wanted.

For an arbitrary function $u \in \mathcal{D}$ that is $G$ invariant, we have, using (7) and the assumption (8):

$$\text{Var}_\mu(f) - \int (f - Lu)^2 \, d\mu = -2 \int \nabla f \cdot \nabla u \, d\mu - \int (Lu)^2 \, d\mu \leq -2 \int \nabla f \cdot \nabla u \, d\mu - \int A \nabla u \cdot \nabla u \, d\mu \leq \int A^{-1} \nabla f \cdot \nabla f \, d\mu,$$

where we also used pointwise the inequality $-2 \cdot v \cdot w \leq Av \cdot v + A^{-1} w \cdot w$ for $v, w \in \mathbb{R}^n$. The conclusion then follows by the density argument recalled above. \qed
The power of the $L^2$ method relies on the fact that the dualization procedure of Lemma 1 allows for the use of the ‘curvature’ (or convexity) of the measure $\mu$ given by (5), which enters through the following classical integration by parts formula: for every $u \in \mathcal{D}$, we have

$$\int (Lu)^2 \, d\mu = \int D^2 \Phi(x) \nabla u(x) \cdot \nabla u(x) \, d\mu(x) + \int \|D^2 u(x)\|^2 \, d\mu(x),$$

where $\|D^2 u(x)\|^2 := \sum_{i,j \leq n} (\partial^2 u(x))_{ij}^2$ is the square of the Hilbert–Schmidt norm of the Hessian of $u$ at $x \in \mathbb{R}^n$. In particular, we see that $\int (Lu)^2 \, d\mu \geq \int D^2 \Phi \nabla u \cdot \nabla d\mu$, which translates, when $\mu$ is strictly log-concave (meaning $D^2 \Phi > 0$), into the celebrated Brascamp–Lieb [9] inequality: for every $f \in L^2(\mu)$ that is locally Lipschitz

$$\var_{\mu}(f) \leq \int (D^2 \Phi)^{-1} \nabla f \cdot \nabla f \, d\mu.$$

In particular, if there exists $\rho \in (0, +\infty)$, such that $D^2 \Phi \geq \rho \text{Id}$ pointwise, then $c_p(\mu) \leq \rho^{-1}$.

We can mention here that when $\mu$ has some convex support $K$, that is, $\mu$ has a density $e^{-\Phi}$ with $\Phi$ of class $C^2$ on $K$, and equal to $+\infty$ outside $K$, then the integration by parts above incorporates a boundary term, which, by the convexity of $K$ is always nonnegative. Therefore, formula (10) becomes an inequality $\geq$, which goes in the right direction for running all the arguments we use in the paper. This explains why our results can directly be extended to this more general class of measures. However, it seems like a challenging question to be able to use, in this case, the extra information coming from the boundary term.

Klartag used, among other things, a similar $L^2$ argument to provide an optimal bound for the variance of the function $f(x) = |x|^2$ when $\mu$ is a log-concave unconditional measure (actually, he worked with an unconditional convex body $K$). Unconditionality means invariance with respect to the coordinate hyperplanes, that is, under the reflections $S_{e_1^\perp}, \ldots, S_{e_n^\perp}$. Klartag manages to use (10) in the form $\int (Lu)^2 \, d\mu \geq \int \|D^2 u\|^2 \, d\mu$ when $\mu$ is log-concave. He then proves a ‘$H^{-1}(\mu)$’ estimate for the derivatives $\partial f$, which in turn is controlled using the Wasserstein (optimal transport) distance; a transportation argument closes the argument.

We want to emphasize the role of symmetry in the argument. The idea is that if $u$ has some invariance, then $\nabla u$ will have the ‘anti-invariance’ (for instance, we pass from being even to being odd with respect to some direction, say). Let us see this principle in action in the celebrated Brascamp–Lieb [9] inequality: for every $f \in L^2(\mu)$ that is locally Lipschitz

$$\var_{\mu}(f) \leq \int (D^2 \Phi)^{-1} \nabla f \cdot \nabla f \, d\mu.$$
we have from the argument explained above for \( i = 1 \) and from Fubini’s theorem that
\[
\int \frac{1}{g_i(P_{ix})} \left( \frac{\partial_i u(x)}{\partial_j u(x)} \right)^2 d\mu(x) \leq \int \left( \frac{\partial_i^2 u(x)}{\partial_j^2 u(x)} \right)^2 d\mu.
\]
Using that \( \sum_{i=1}^n (\partial_i^2 u) \leq \|D^2 u\|^2 \) in (10), we get a bound (8) which implies, by Lemma 1 the following estimate: for every function \( f \in L^2(\mu) \) that is unconditional and locally Lipschitz,
\[
\text{Var}_\mu(f) \leq \int \sum_{i=1}^n g_i(P_{ix}) (\partial_i f(x))^2 d\mu(x).
\]
When we apply this estimate to the particular case \( f(x) = |x|^2 \), the following happens. We can use again Fubini’s theorem and Hölder’s inequality, to get that
\[
\text{Var}_\mu(|x|^2) \leq 4 \int x_i^4 d\mu(x).
\]
It is a well-known and useful consequence of the Prékopa–Leindler inequality due to Borell that \( L_p \) norms of convex homogeneous functions with respect to a log-concave measure are equivalent [8]. In particular, there exists a numerical constant \( c > 0 \) such that for every \( n \geq 1 \), every log-concave probability measure \( \mu \) on \( \mathbb{R}^n \) and every even semi-norm \( H \), typically \( H(x) = x \cdot \theta \) or \( H(x) = |x| \), the following reverse Hölder inequality holds:
\[
\int H(x)^4 d\mu(x) \leq c \left( \int H(x)^2 d\mu(x) \right)^2.
\] (12)
We have therefore proved that for an unconditional log-concave measure \( \mu \) on \( \mathbb{R}^n \) it holds that \( \text{Var}_\mu(|x|^2) \leq C \sum_{i=1}^n \left( \int x_i^2 d\mu(x) \right)^2 \). When \( \mu \) is furthermore isotropic, that is, with covariance matrix equal to the identity, the previous bound reads as
\[
\text{Var}_\mu(|x|^2) \leq \tilde{c} n,
\]
which answers positively the variance conjecture in the case of unconditional distributions.

3. Functions and measures with invariances

As apparent from the above treatment of the unconditional case, we shall need to work with restrictions of measures onto subspaces. This idea has already been used successfully in statistical mechanics, and our goal is to bring the invariances into the game.

Let us start with some notation. For a subspace \( F \subset \mathbb{R}^n \), we denote by \( P_F \) the orthogonal projection onto \( F \). Given a probability measure \( \mu \) with density \( e^{-\Phi} \) on \( \mathbb{R}^n \), a subspace \( E \subset \mathbb{R}^n \) and a point \( x \in \mathbb{R}^n \), we denote by \( \mu_{x,E} \) the probability measure on \( E \) obtained by conditioning \( \mu \) to fixed \( P_{E^\perp} x \), that is,
\[
d\mu_{x,E}(y) := e^{-\Phi(x+P_{E^\perp} y)} \frac{dy}{\int_{E} e^{-\Phi(z+P_{E^\perp} z)} dz}, \quad y \in E.
\]
In other words, if \( X \sim \mu \), then
\[
E(X | P_{E^\perp} X = P_{E^\perp} x) \sim \mu_{x,E}.
\]
The measure \( \mu_{x,E} \) can be seen likewise as a measure on \( E \) or on \( x + E = P_{E^\perp} x + E \). Note that \( \mu_{x,E} \) depends only on \( P_{E^\perp} x \); \( \mu_{x,E} = \mu_{P_{E^\perp} x,E} \). For suitable \( g : \mathbb{R}^n \rightarrow \mathbb{R} \), we shall extensively use Fubini’s theorem in the form
\[
\int g \, d\mu = \int_{x \in E^\perp} \left( \int_{y \in E} g(x + y) e^{-\Phi(x+y)} \, dy \right) dx,
\]
that under the assumption that

$$E$$

for every $R$, therefore the underlying measure. We will need the following property of such functions, which is obvious unlike in the Brascamp–Lieb inequality, log-concavity is not required here. This is particularly effective for perturbations of product measures.

In what follows, we shall be interested in the case when we have fixed-point subspaces

$$K=\{x,\nu\}$$

where the $n \times n$ matrix $K(x)$ is defined as follows: $K(x)_{i,i}=c_p(\mu_{x,\mathbb{R}^n})^{-1}$ and for $i \neq j$, $K(x)_{i,j}=\partial_{ij}^2 \Phi(x)$. Therefore, by Lemma 1 (with no invariance yet, that is, $G=\{\text{Id}\}$), we see that under the assumption that $K(x)>0$ for every $x \in \mathbb{R}^n$, we have the following inequality: for every $f \in L^2(\mu)$ that is locally Lipschitz,

$$\text{Var}_\mu(f) \leq \int K^{-1} \nabla f \cdot \nabla f \, d\mu.$$

Unlike in the Brascamp–Lieb inequality, log-concavity is not required here. This is particularly effective for perturbations of product measures.

We want to push forward this approach by working with functions sharing invariances with the underlying measure. We will need the following property of such functions, which is obvious for a reflection (it then follows from the even/odd character of the functions).

**Fact 2.** Let $\mu$ be a probability measure on $\mathbb{R}^n$, $R \in O_n(\mu)$ and set $E = \text{Fix}(R)^\perp$. For every $R$-invariant function $g$ and for every $x \in \mathbb{R}^n$ we have,

$$\int_{E} P_E \nabla g(y) \, d\mu_{x,E}(y) = 0.$$

In particular, the measure $\mu_{x,E}$ is centred.

**Proof.** Denote by $\rho$ the density of $\mu$ and set $a := \int_{E} P_E \nabla g(y) \rho(y) \, d\mu$. By definition $a \in E$. But since $E = \text{Fix}(R)^\perp$ and $R$ is normal, we have $RE = E$ and $P_E R = RP_E$, and so

$$a = \int_{E} P_E \nabla g(Ry) \rho(Ry) \, dy = \int_{E} P_E R \nabla g(y) \rho(y) \, dy = Ra$$

where we have used that $\rho$ and $g$ are $R$-invariant. This shows that $a \in \text{Fix}(R) = E^\perp$ and therefore $a = 0$. \qed

In what follows, we shall be interested in the case when we have fixed-point subspaces $E_i = \text{Fix}(R_i)^\perp$, $i = 1, \ldots, m$, that induce a decomposition of the identity of the form

$$\sum_{i=1}^m c_i P_{E_i} = \text{Id},$$

or in the form

$$\int f \, d\mu = \int \left( \int f \, d\mu_{x,E} \right) \, d\mu(x).$$

Let us recall a restriction argument put forward by Helffer [21]. Here we work with a measure $\mu$ satisfying (5) and the canonical basis $\{e_i\}$. Using the Poincaré inequality for the measures $\nu = \mu_{x,\mathbb{R}^n}$ in the form $c_p(\nu) \int (L^2d\nu) \geq \int (w')^2d\nu$ we have

$$\left(\int (Lu)^2 \right) \, d\mu = \left(\int (||D^2u||^2 + D^2\Phi \nabla u \cdot \nabla u) \right) \, d\mu$$

$$\geq \sum_{i \neq j} \partial_{ij}^2 \Phi \partial_{ij} u \, d\mu + \sum_i \left( (\partial_{ii}^2 \Phi)^2 + \partial_{ii}^2 \Phi \partial_{ii} u \right) \, d\mu_{x,E_i} \, d\mu(x)$$

$$\geq \sum_{i \neq j} \partial_{ij}^2 \Phi \partial_{ij} u \, d\mu + \sum_i \left( c_p(\mu_{x,\mathbb{R}^n})^{-1} \int (\partial_i u)^2 \, d\mu_{x,E_i} \right) \, d\mu(x)$$

$$= \int K \nabla u \cdot \nabla u \, d\mu.$$
where the coefficients $c_i$ are positive reals. It will also be used in the form
\[
\forall v \in \mathbb{R}^n, \quad \sum_{i=1}^{m} c_i|P_{E_i}v|^2 = |v|^2.
\]

This situation naturally arises when we consider measures having enough invariances by reflections. The simplest example is when $m = n$, $E_i = \mathbb{R}e_i$ and $c_i = 1$, where $\{e_i\}$ is the canonical basis of $\mathbb{R}^n$ (this corresponds to unconditional measures). More examples appear in the appendix. Note that taking traces yields $\sum c_i \dim (E_i) = n$.

**Theorem 3.** Let $\mu$ be a probability measure on $\mathbb{R}^n$ given by (5). Assume that there exists $R_1, \ldots, R_m \in \mathcal{O}_n(\mu)$ and $c_1, \ldots, c_m > 0$ such that, setting $E_i := \text{Fix}(R_i)^\perp$, we have that $\{E_i, c_i\}$ decompose the identity in the sense of (14). Assume that, for all $x \in \mathbb{R}^n$,
\[
H(x) := D^2\Phi(x) + \sum_{i=1}^{m} \frac{c_i}{c_p(\mu_{x,E_i})} P_{E_i} > 0.
\]

Then for every locally Lipschitz and $\{R_i\}_{i \leq m}$-invariant function $f : \mathbb{R}^n \to \mathbb{R}$ we have
\[
\text{Var}_\mu(f) \leq \int H^{-1} \nabla f \cdot \nabla f \, d\mu.
\]

In particular, if there exists $\rho \in \mathbb{R}$ such that $D^2\Phi \geq \rho \text{Id}$ and for all $x, i$, $c_p(\mu_{x,E_i})^{-1} + \rho \geq 0$, then for every locally Lipschitz and $\{R_i\}_{i \leq m}$-invariant function $f : \mathbb{R}^n \to \mathbb{R}$,
\[
\text{Var}_\mu(f) \leq \left( \sum_{i=1}^{m} c_i(c_p(\mu_{x,E_i})^{-1} + \rho)^{-1} |P_{E_i}\nabla f(x)|^2 \right) d\mu(x)
\]
\[
\leq \sup_{i,x} (c_p(\mu_{x,E_i})^{-1} + \rho)^{-1} \int \nabla f(x) \, d\mu.
\]

**Proof.** By Lemma 1, it is sufficient to prove that, for every $\{R_i\}$-invariant $u \in \mathcal{D}$, we have \(\int (Lu)^2 \, d\mu \geq \int H \nabla u \cdot \nabla u \, d\mu\), which we rewrite, in view of (10) as
\[
\int \|D^2 u\|^2 \, d\mu \geq \left( \sum_{i=1}^{m} c_i \frac{c_i}{c_p(\mu_{x,E_i})} |P_{E_i}\nabla u|^2 \right) d\mu(x).
\] (16)

To establish the latter, first note that for every symmetric matrix $H$,
\[
\|H\|^2 = \text{Tr}(H^2) = \sum_{i=1}^{m} c_i \text{Tr}(P_{E_i}H^2P_{E_i}) \geq \sum_{i=1}^{m} c_i \text{Tr}((P_{E_i}HP_{E_i})^2) = \sum_{i=1}^{m} c_i \|P_{E_i}HP_{E_i}\|^2.
\] (17)

where we have used $P_{E_i} \leq \text{Id} \Rightarrow HP_{E_i}H \leq H^2 \Rightarrow (P_{E_i}HP_{E_i}) \leq P_{E_i}H^2P_{E_i}$. It follows that
\[
\int \|D^2 u\|^2 \, d\mu \geq \sum_{i=1}^{m} c_i \|P_{E_i}D^2 uP_{E_i}\|^2 \, d\mu.
\]

Next, by Fact 2, we know that for all $x, i$, $\int P_{E_i}\nabla u \, d\mu_{x,E_i} = 0$. Hence for all unit vector $a \in E_i$, we deduce that the function $h = \nabla u \cdot a$ verifies $\int h \, d\mu_{x,E_i} = 0$ and so $\int h^2 \, d\mu_{x,E_i} \leq c_p(\mu_{x,E_i}) \int |P_{E_i}\nabla h|^2 \, d\mu_{x,E_i}$. By taking vectors $a$ forming an orthonormal basis of $E_i$ we deduce that
\[
\left( \int |P_{E_i}\nabla u|^2 \, d\mu_{x,E_i} \leq c_p(\mu_{x,E_i}) \int \|P_{E_i}D^2 uP_{E_i}\|^2 \, d\mu_{x,E_i}. \right.
\]

Using Fubini’s theorem in the form of (13), we get that, for all $i = 1, \ldots, m$,
\[
\int \|P_{E_i}D^2 uP_{E_i}\|^2 \, d\mu \geq \left( \frac{1}{c_p(\mu_{x,E_i})} \right) \left( \int |P_{E_i}\nabla u|^2 \, d\mu \right).
\]

Summing upon the index $i$ with coefficient $c_i$ gives (16), which concludes the proof of the general case.
For the special case when $D^2\Phi \geq \rho \text{Id}$, we have $H(x) \geq \sum c_i(\rho + c_p(\mu_{x,E_i}))P_{E_i}$ and the result follows by bounding $H^{-1}$ from above. Indeed, if a positive matrix verifies $H \geq \sum c_i\alpha_i P_{E_i}$ with the $\alpha_i > 0$, then, for every vector $v \in \mathbb{R}^n$, setting $w = H^{-1}v$, we have

$$H^{-1}v \cdot v = 2v \cdot w - Hw \cdot w \leq \sum_{i=1}^m c_i(2P_{E_i}v \cdot P_{E_i}w - \alpha_i|P_{E_i}w|^2) \leq \sum_{i=1}^m \frac{c_i}{\alpha_i}|P_{E_i}v|^2. \quad \Box$$

Next, we present a variant of the previous result, which does not require invariances.

**Theorem 4.** Let $\mu$ be a probability measure on $\mathbb{R}^n$ given by (5) such that $D^2\Phi \geq \rho \text{Id}$ on $\mathbb{R}^n$ for some $\rho \geq 0$. Let $E_1, \ldots, E_m$ be subspaces of $\mathbb{R}^n$ and $c_1, \ldots, c_m > 0$ such that $\{E_i, c_i\}$ decompose the identity in the sense of (14). Then, for every locally Lipschitz function $f : \mathbb{R}^n \to \mathbb{R}$ such that, for every $x \in \mathbb{R}^n$ and $i \leq m$,

$$\left|P_{E_i}\nabla f d\mu_{x,E_i}\right| = 0,$$  \hspace{1cm} (18)

we have

$$\text{Var}_\mu(f) \leq \left(\sum_{i=1}^m c_i(c_p(\mu_{x,E_i})^{-1} + \rho)^{-1}|P_{E_i}\nabla f(x)|^2\right) d\mu(x). \quad (19)$$

**Proof.** Here, we will not use Lemma 1 directly since our hypothesis does not translate into a property of $u$. The small modification we have to do is a centring argument. Let us fix $f \in L^2_0(\mu)$, and let $u$ be a $C^2$ smooth compactly supported function, that is, $u \in D$. Write as before

$$\text{Var}_\mu(f) - \int (f - Lu)^2 d\mu = - \int (Lu)^2 d\mu - 2\int \nabla f \cdot \nabla u d\mu.$$

It now suffices to bound this quantity by the right-hand side of (19): the conclusion follows, as in Lemma 1, by the density of $L(D)$ in $L^2_0(\mu)$. For the first term, we have

$$\int (Lu)^2 d\mu \geq \left(\|D^2u\|^2 + \rho|\nabla u|^2\right) d\mu \geq \sum_i c_i \left(\|P_{E_i}D^2uP_{E_i}\|^2 + \rho|P_{E_i}\nabla u|^2\right) d\mu$$

$$\geq \sum_i c_i \left(\left\|P_{E_i}\nabla u - \int P_{E_i}\nabla u d\mu_{x,E_i}\right\|^2 d\mu_{x,E_i}\right) d\mu(x)$$

$$+ \rho \left(\left\|P_{E_i}\nabla u - \int P_{E_i}\nabla u d\mu_{x,E_i}\right\|^2 d\mu_{x,E_i}\right) d\mu(x)$$

$$= \sum_i c_i(c_p(\mu_{x,E_i})^{-1} + \rho) \left|P_{E_i}\nabla u - \int P_{E_i}\nabla u d\mu_{x,E_i}\right| d\mu(x),$$

where we have used the Poincaré inequality for $\mu_{x,E_i}$ and $\int g^2 d\mu_{x,E_i} \geq \text{Var}_{\mu_{x,E_i}}(g)$. On the other hand, using now the hypothesis $\int P_{E_i}\nabla f d\mu_{x,E_i} = 0$ we have

$$\int \nabla f \cdot \nabla u d\mu = \sum_{i=1}^m c_i P_{E_i}\nabla f \cdot P_{E_i}\nabla u d\mu$$

$$= \sum_{i=1}^m c_i P_{E_i}\nabla f \cdot \left(P_{E_i}\nabla u - \int P_{E_i}\nabla u d\mu_{x,E_i}\right) d\mu(x).$$

We conclude by using, pointwise, for fixed $x$ and $i$, the inequality $-2a \cdot b \leq \lambda^{-1}|a|^2 + \lambda|b|^2$ with $a = P_{E_i}\nabla f$, $b = P_{E_i}\nabla u - \int P_{E_i}\nabla u d\mu_{x,E_i}$ and $\lambda = (c_p(\mu_{x,E_i})^{-1} + \rho).$ \hspace{1cm} \Box
Remark 1. The following fact was crucial in the proof of the $B$-conjecture [13]: if $D^2\Phi \succeq \Id$, then any function with $\int \nabla f \, d\mu = 0$ verifies $\Var_\mu(f) \leq \frac{1}{2} \int \nabla f^2 \, d\mu$. The novelty there was of course the improved $\frac{1}{2}$ factor, which can be seen as a ‘second eigenvalue’ estimate. Applying the previous theorem with $m = 1$, $E = \R^n$, $\rho = 1$ recovers it. Indeed the hypothesis on the Hessian of $\Phi$ (which implies $c_p(\mu) \leq 1$) gives by restriction a similar inequality for the Hessian of the potential of $\mu_{x,E_i}$, which guarantees $c_p(\mu_{x,E_i}) \leq 1$. Let us mention that the $L^2$ proof given in [13] already used a centring argument.

4. Variance of the norm for log-concave measures

We present here a first application of the previous result to the study of the variance conjecture (3) for measure with invariances. Indeed, the function $f(x) = |x|^2$ is invariant by all isometries, so we can apply the bound of the previous section when $\mu$ (resp. $X \sim \mu$) is a log-concave measure (resp. a log-concave random vector) of $\R^n$ have well-distributed invariances. Introduce the quantity

$$v(n) := \sup \{\Var(|X|^2); \ X \text{ isotropic log-concave random vector in } \R^n\}.$$ 

Recall that the variance conjecture predicts that $v(n) \leq cn$ for some universal constant $c$. The Cauchy–Schwarz inequality immediately yields $v(n) \leq n^2$. Improving this trivial estimate is a difficult problem, recently solved by several authors, which led to the solution of the so-called central limit theorem for convex bodies. Up to date, the best-known estimate is due to Guédon and Milman [20]: $v(n) \leq C n^{5/3}$.

**Theorem 5.** Let $X$ be a log-concave random vector in $\R^n$. Assume that there exist isometries $R_1, \ldots, R_m \in \mathcal{O}_n(X)$ and numbers $c_1, \ldots, c_m \geq 0$ such that, setting $E_i = \text{Fix}(R_i)^\perp$, we have that $\{E_i, c_i\}$ decompose the identity in the sense of (14). Then,

$$\Var(|X|^2) \leq 16 \sum_{i=1}^m c_i |P_{E_i}X|^4,$$

and when $X$ is also isotropic,

$$\Var(|X|^2) \leq C \sum_{i=1}^m c_i d_i^2 \leq C n \max_{i \leq m} d_i,$$

where $d_i := \text{dim}(E_i)$. Here $C > 0$ is some numerical constant.

**Proof.** Let us denote $F_i = E_i^\perp$. Theorem 3 applied to $f(x) = |x|^2$ and $X \sim \mu$ gives

$$\Var_\mu(f) \leq 4 \sum_i c_i c_p(\mu_{x,E_i}) |P_{E_i}x|^2 \, d\mu(x).$$

Next, by the bound (2) applied to the log-concave measure $\mu_{x,E_i}$ (for fixed $i$, $x$), we have

$$c_p(\mu_{x,E_i}) \leq 4 \int_{E_i} |y|^2 \, d\mu_{x,E_i}(y) = 4E[|P_{E_i}X|^2 | P_{F_i}X = P_{F_i}x].$$

Conditioning on $P_{E_i}X$ and applying Cauchy–Schwarz inequality yields

$$\Var(|X|^2) \leq 16 \sum_{i=1}^m c_i \E[|P_{E_i}X|^2 | P_{F_i}X] |P_{E_i}X|^2]$$

$$\leq 16 \sum_{i=1}^m c_i \E[|P_{E_i}X|^4 | P_{F_i}X] = c \sum_{i=1}^m c_i \E[|P_{E_i}X|^4].$$
The second inequality follows from Borell’s lemma (12) and $E|P_E X|^2 = \dim(E)$ when $X$ is isotropic. The last one is derived from the relation $n = \sum_i c_i d_i$. □

Actually, one can relax the hypothesis on the structure of the isometries, by allowing invariant
directions.

**Theorem 6.** Let $X$ be an isotropic log-concave random vector in $\mathbb{R}^n$. Assume that there
exist isometries $U_1, \ldots, U_m \in \mathcal{O}_n(X)$ and numbers $c_1, \ldots, c_m \geq 0$ such that
\[
\sum_{i=1}^m c_i P_{\text{Fix}(U_i)} = P_E,
\]
where $E = (\bigcap_i \text{Fix}(U_i))^\perp$. Set $d = \dim(\bigcap_i \text{Fix}(U_i))$ and $d_i = \text{codim}(\text{Fix}(U_i))$. Then
\[
\text{Var}(|X|^2) \leq 2v(d) + cn \max_i d_i.
\]
In particular, if $d \leq \alpha \sqrt{n}$ and for all $i$, $d_i \leq \alpha$, then $\text{Var}(|X|^2) \leq C(\alpha)n$.

**Proof.** Write $X = (Y, Z) \in E \times E^\perp$. Then $Y$ and $Z$ are log-concave isotropic random
vectors in $E$ and $E^\perp$. Since $E^\perp = \bigcap_i \text{Fix}(U_i)$, $X \sim U_i X = (U_i Y, Z)$ so $U_i Y \sim Y$. Since
$E \cap \bigcap_i \text{Fix}(U_i) = \{0\}$, we may apply the previous statement to $Y \in E$ and obtain $\text{Var}(|Y|^2) \leq \alpha(n-d) \max_i d_i$. For $Z \in E^\perp$, we apply the trivial estimate $\text{Var}(|Z|^2) \leq v(d) \leq d^2$. Eventually,
$\text{Var}(|X|^2) = \text{Var}(|Y|^2 + |Z|^2) \leq 2\text{Var}(|Y|^2) + 2\text{Var}(|Z|^2)$. □

The preceding results are particularly useful in the case we have nice invariances by
reflections, since $d_i = 1$ then. Indeed, if $\text{Fix}(\mathcal{R}(X)) = \{0\}$, then we can find a decomposition of
the identity by directions orthogonal to the hyperplane symmetries, and therefore we obtain the desired bound $\text{Var}(|X|^2) \leq cn$. Actually, a little more is true, in the spirit of the previous result.

**Theorem 7.** Let $X$ be an isotropic log-concave random vector in $\mathbb{R}^n$. Assume that there
exist reflections $S_{H_1}, \ldots, S_{H_m} \in \mathcal{O}_n(X)$ with $\dim(\bigcap_i H_i) \leq \alpha \sqrt{n}$. Then $\text{Var}(|X|^2) \leq C(\alpha)n$.

In particular, if $\bigcap_i H_i = \{0\}$, the vector $X$ verifies the variance conjecture.

**Proof.** This relies on the basic fact about reflection groups recalled in the appendix. More
precisely, the result follows from Lemma A.2 and from the previous theorem. □

The previous statement gives that every isotropic log-concave distribution which has the
invariance of the simplex satisfies the variance conjecture. In the case of the simplex itself, this
was also recovered by Klartag in a very recent preprint [27]; there Klartag proposes a nice way
of taking advantage of some particular symmetries in the study of Poincaré inequalities, by
lifting the inequalities to larger, more symmetric spaces.

Let us present another application, which does not involve reflections. Consider $S^d_p$ the
Schatten class, that is, the space of $d \times d$ real matrices equipped with the norm $\|A\|_p = \sum_{i=1}^d \lambda_i(A)^p$ for $p \in [1, +\infty)$, where the $\lambda_i(A)$ denote the singular values of $A$, that is, the
eigenvalues of $(A^*A)^{1/2}$. Consider the linear maps $R_i$ which flip the signs of all the entries
in the $i$th row of a matrix. Clearly $\|R_i A\|_p = \|A\|_p$. Moreover, $\text{Fix}(R_i)$ is of codimension $\dim d$ and
$\sum_{i=1}^d P_{\text{Fix}(R_i)} = \text{Id}$ (see the appendix for more details). Let $n = d^2$ be the dimension
and let $B^d_p \subset \mathbb{R}^n$ be the unit ball for the Schatten norm $\|\cdot\|_p$. Consider a suitable dilation
$\lambda B^d_p$ ensuring that the random vector $X_{p,n} \sim \mu_{\lambda B^d_p}$ uniformly distributed on $\lambda B^d_p$ is isotropic.
Theorem 5 then gives that
\[
\text{Var}(|X_{n,p}|^2) \leq cnp = cn^{3/2}
\]
which is slightly better than the general bound of Guédon and Milman.

5. Invariant measures and general functions

The goal of this section is to get rid of the invariance hypotheses for the functions in Theorem 3. We will prove that when some group of isometries \( G \) leaving the measure invariant has nice spectral properties, then indeed Theorem 3 is valid for all functions. For this, we will average (or symmetrize) through the group \( G \). This method is inspired in part by an argument of Fleury [16] who treated the case of unconditional measures. Let us fix the setting.

**Setting 8.** Let \( G = \{R_1, \ldots, R_m\} \) be a set of \( m \) isometries and let \( G \) be the (compact) group they generate, equipped with its (normalized) Haar measure \( \gamma \). We assume the following.

(i) The set of generators \( G \) is stable under conjugacy in \( G \) (that is, \( gGg^{-1} = G, \forall g \in G \)).

(ii) We consider the Cayley graph associated to these generators and we suppose that some Poincaré inequality holds on \( G \) for some (generalized) discrete gradient. More precisely, we assume that there exist positive numbers \( d_i \) such that
\[
\forall f : G \to \mathbb{R}, \quad \text{Var}_\gamma(f) \leq \mathcal{E}(f, f) := \left( \sum_{i=1}^m d_i [f(R_i) - f(g)]^2 \right)^{\frac{1}{2}} \gamma(g).
\]  
(20)

We impose the following structural condition on the weights \( d_i \):
\[
\forall i, j \leq m, \forall g \in G : \quad R_i = gR_jg^{-1} \implies d_i = d_j.
\]  
(21)

This condition is obviously satisfied if we take all the \( d_i \) to be equal to the same constant \( c > 0 \), and then the best constant \( c \) for which (20) holds is known to be the Poincaré constant associated to \( (G, \gamma) \) which we denote by \( c_p(G) \).

A crucial observation that follows from the fact that \( G \) is stable under conjugacy is that \( G \) acts as a permutation not only on \( \mathcal{F} \), but also on the set of fixed subspaces \( E_i := \text{Fix}(R_i)^\perp \), in the sense that, for every \( g \in G \), there exists a permutation \( \tau \) of \( \{1, \ldots, m\} \) such that
\[
g(E_1, E_2, \ldots, E_m) = (E_{\tau(1)}, E_{\tau(2)}, \ldots, E_{\tau(m)}).
\]
To check this, just note that \( \text{Fix}(gR_i g^{-1})^\perp = g(\text{Fix}(R_i)^\perp) = gE_i \).

Let us first state a very simple but crucial observation:

**Fact 9.** Let \( u : \mathbb{R}^n \to \mathbb{R} \) be an arbitrary function and \( R \) be an isometry leaving a measure \( \mu \) invariant. Then, setting \( E = \text{Fix}(R)^\perp \), we have that, for every \( x \in \mathbb{R}^n \),
\[
\int_E [u \circ R - u] d\mu_{x,E} = 0.
\]

**Proof.** Set \( F = \text{Fix}(R) \) and let \( \rho \) be the density of \( \mu \). As for Fact 2, we use that \( RE = E \). For every fixed \( x \in \mathbb{R}^n \) we have, since \( \rho \circ R = \rho \),
\[
\int_E [u \circ R \cdot \rho](P_F x + y) dy = \int_E [(u \circ R) \cdot (\rho \circ R)](P_F x + y) dy = \int_E [u \cdot \rho](RP_F x + z) dz,
\]
where we used that \( R \) is an isometry of \( E \) and performed the change of variable \( z = Ry \). To conclude, use that \( RP_F = P_F \).

We are ready to start the extension of variance estimates from invariant to non-invariant functions. The first step is to estimate from above the variance of a general function by the variance of the $G$-invariant function obtained by averaging.

**Proposition 10.** Under the Setting 8 with $E_i := \text{Fix}(R_i)^+1$ we have, for every locally Lipschitz function $f$ on $\mathbb{R}^n$ and $F := \int f \circ g \, d\gamma(g)$,

$$\text{Var}_\mu(f) \leq \text{Var}_\mu(F) + 4 \int \sum_i d_c(\mu_{x,E_i}) |P_{E_i} \nabla f(x)|^2 \, d\mu(x).$$

**Proof.** Let $X$ be a random vector with distribution $\mu$ and $\Gamma$ be a random isometry of distribution $\gamma$, chosen independently of $X$. Then by the invariance properties of $\mu$, the random vector $\Gamma X$ has distribution $\mu$. Hence, using the classical decomposition of the variance

$$\text{Var}_\mu(f) = \text{Var}_\mu(f \circ \Gamma) = \text{Var}_\mu((\mathcal{E}_f \circ \Gamma)(X)) + \mathbb{E}_X(\text{Var}_\Gamma(f)(X))$$

$$= \text{Var}_\mu(F) + \int \text{Var}_\gamma(g \to f(gx)) \, d\mu(x).$$

We estimate the second term by the discrete Poincaré inequality (20) on $G$:

$$\int \text{Var}_\gamma(g \to f(gx)) \, d\mu(x) \leq \sum_i \int \sum_i d_c(f(gR_i x) - f(gx))^2 \, d\gamma(g) \, d\mu(x)$$

$$= \sum_i \int \sum_i d_c ((f \circ g(R_i x) - f \circ g(x))^2 \, d\mu(x) \, d\gamma(g).$$

The crucial point is that, setting $h = f \circ g$, we have in view of Fact 9 that, for all $x$, $\int_{E_i} (h \circ R_i - h) \, d\mu_x \, E_i = 0$, which allows us to apply the Poincaré inequality for the restrictions of $\mu$ to subspaces parallel to $E_i$, without a remainder term, that is, in the form

$$\int_{E_i} (h \circ R_i - h)^2 \, d\mu_x \, E_i \leq c_p(\mu_{x,E_i}) \int_{E_i} |P_{E_i} \nabla (h \circ R_i - h)|^2 \, d\mu_x \, E_i.$$

Consequently, using Fubini’s theorem,

$$\int (f \circ g(R_i x) - f \circ g(x))^2 \, d\mu(x)$$

$$\leq \sum_i c_p(\mu_{x,E_i}) \int_{E_i} |P_{E_i} \nabla (h \circ R_i - h)|^2 \, d\mu_x \, E_i \, d\mu(x)$$

$$\leq 2 \sum_i c_p(\mu_{x,E_i}) (|P_{E_i} \nabla f(x)|^2 + |P_{E_i} \nabla (f \circ g_R)(x)|^2) \, d\mu(x) \, d\gamma(g).$$

Next, observe that $|P_{E_i} \nabla (f \circ g)| = |P_{E_i} g^{-1}(\nabla f) \circ g| = |gP_{E_i} g^{-1}(\nabla f) \circ g| = |P_{E_i}(\nabla f) \circ g|$. Hence, using the invariance of $\mu$ by $G$ twice (first in the form $c_p(\mu_{x,E_i}) = c_p(\mu_{g \circ x,E_i})$) and using the fact that $G$ acts as a permutation on $(E_1, \ldots, E_m)$

$$\sum_i \int_G c_p(\mu_{x,E_i}) |P_{E_i} \nabla(f \circ g)(x)|^2 \, d\mu(x) \, d\gamma(g)$$

$$= \sum_i \int_G c_p(\mu_{g \circ x,E_i}) |P_{E_i} \nabla f(gx)|^2 \, d\mu(x) \, d\gamma(g)$$

$$= \int_G \sum_i c_p(\mu_{g \circ x,E_i}) |P_{E_i} \nabla f(gy)|^2 \, d\mu(y) \, d\gamma(g).$$
shall say that a map from the gradient of the initial function to the above function one of the sense of quadratic forms valued functions. Then for all \( \gamma \in \mathcal{G} \) be a group of isometries valued in positive quadratic forms. Then for all \( x, u \in \mathbb{R}^n \) and all \( g \in G \),

\[ Q_{gy}(gu) = Q_x(u). \]

**Lemma 11.** Let \( G \) be a group of isometries equipped with its Haar probability measure \( \gamma \). Let \( \mu \) be a \( G \)-invariant probability measure on \( \mathbb{R}^n \), and \( Q \) be a \( G \)-invariant function on \( \mathbb{R}^n \) with values in positive quadratic forms. Then for all \( f : \mathbb{R}^n \to \mathbb{R}^n \) with gradient in \( L^2(\mu) \), setting \( F = \int_G f \circ g \, d\gamma(g) \), it holds

\[
\left( \int Q_x(\nabla F(x)) \, d\mu(x) \right) \leq \left( \int Q_x(\nabla f(x)) \, d\mu(x) \right).
\]

**Proof.** Since for all \( x, u \to Q_x(u) \) is convex,

\[
\int Q(\nabla F) \, d\mu = \int Q_x \left( \int g^{-1}(\nabla f)(gx) \, d\gamma(g) \right) \, d\mu(x)
\]

\[
\leq \int Q_x(g^{-1}(\nabla f)(gx)) \, d\mu(x) \, d\gamma(g)
\]

\[
= \int Q_{g^{-1}y}(g^{-1}(\nabla f)(y)) \, d\mu(y) \, d\gamma(g)
\]

\[
= \int Q_y(\nabla f(y)) \, d\mu(y) \, d\gamma(g)
\]

where we used \( \nabla(f \circ g) = g^*(\nabla f) \circ g = g^{-1}(\nabla f) \circ f \), the invariance of \( \mu \) and then the one of \( Q \).

**Lemma 12.** Let \( G \) be a group of isometries of \( \mathbb{R}^n \).

1. If \( \Phi : \mathbb{R}^n \to \mathbb{R}^n \) is twice differentiable and \( G \)-invariant, then \( D^2\Phi \) is also \( G \)-invariant (in the sense of quadratic forms valued functions).
(2) Let \((E_1, \ldots, E_m)\) be a \(m\)-tuple of subspaces of \(\mathbb{R}^n\), onto which \(G\) acts by permutation. Let \(c(x, E_i)\) be coefficients such that for all \(x, y, i\), \(c(gx, gE_i) = c(x, E_i)\). Then (identifying quadratic forms and symmetric linear maps), \(x \mapsto \sum_i c(x, E_i)P_{E_i}\) is also \(G\)-invariant.

(3) If \(x \to Q_x\) is \(G\)-invariant with values in definite positive quadratic forms, then so is the dual form map \(x \to Q^*_x\).

Proof. The first item is obvious by differentiating \(\Phi(gx) = \Phi(x)\). For the second item, denoting the quadratic form by \(Q_x\), and using the properties of \(c\) gives

\[
Q_{gx}(gu) = \sum_i c(gx, E_i)|P_{E_i}gu|^2 = \sum_i c(gx, E_i)|g^{-1}P_{E_i}gu|^2 = \sum_i c(x, g^{-1}E_i)|P_{g^{-1}E_i}u|^2 = Q_x(u),
\]

where in the last equality, we have used that \(g^{-1}\) induces a permutation of \((E_1, \ldots, E_m)\). The last item is straightforward from the definition of the dual of a definite positive quadratic form \(Q^*(x) = \sup\{(x \cdot y)/Q(y); \ y \neq 0\}\). Also, recall that if \(Q(x) = Ax \cdot x\) for all \(x\), then \(Q^*(x) = A^{-1}x \cdot x\).

We can now state the extensions of the estimates of Section 3 to general functions.

**Theorem 13** (Extension of Theorem 3 to general functions). Let \(d\mu(x) = e^{-\Phi(x)}dx\) be a probability measure which is invariant by isometries \(R_1, \ldots, R_m\) and set \(E_i = \text{Fix}(R_i)^\perp\). Assume the conditions of Setting 8 are satisfied. Let \(c_1, \ldots, c_m > 0\) be coefficients satisfying the same condition (21) as the coefficients \(d_i\) and such that \(\{E_i, c_i\}\) decompose the identity in the sense of (14).

If pointwise, \(H_x := D^2\Phi(x) + \sum_i (c_i/c_p(\mu_x, E_i))P_{E_i} > 0\), then, for all \(f : \mathbb{R}^n \to \mathbb{R}\) locally Lipschitz, we have

\[
\text{Var}_\mu(f) \leq \left( H_{x}^{-1} + 4 \sum_i d_i c_p(\mu_x, E_i)P_{E_i} \right) \nabla f(x) \cdot \nabla f(x) d\mu(x).
\]

In particular, if there exists \(\alpha > 0\) such that for all \(x\), \(D^2\Phi(x) \geq -\alpha \text{Id}\) and for all \(i\), \(c_p(\mu_x, E_i) < 1/\alpha\), then for all \(f : \mathbb{R}^n \to \mathbb{R}\) locally Lipschitz,

\[
\text{Var}_\mu(f) \leq \sum_i \left( c_i + 4d_i(c_p(\mu_x, E_i))^{-1} - \alpha \right)^{-1} |P_{E_i} \nabla f(x)|^2 d\mu(x).
\]

These two inequalities hold in particular if we take \(d_i \equiv c_p(\mathcal{G})\), the Poincaré constant of the group.

Proof. Given \(f\), the \(G\)-invariant function \(F = \int f \circ g d\gamma\) satisfies \(\text{Var}_\mu(F) \leq \|H^{-1}\nabla F \cdot \nabla F d\mu\) thanks to Theorem 3. Next, Lemma 12 ensures that \(x \to H_{x}^{-1}\) is \(G\)-invariant. Thus, by Lemma 11, \(\|H^{-1}\nabla F \cdot \nabla F d\mu\) is at most \(\|H^{-1}\nabla f \cdot \nabla f d\mu\). The first claim thus follows from Proposition 10.

For the second inequality, we apply (15) to the function \(F\) and so the same arguments give

\[
\text{Var}_\mu(f) \leq \left( \sum_i c_i(c_p(\mu_x, E_i))^{-1} - \alpha \right)^{-1} |P_{E_i} \nabla f(x)|^2 d\mu(x) + 4 \sum_i d_i c_p(\mu_x, E_i) |P_{E_i} \nabla f(x)|^2 d\mu(x).
\]

To conclude, note that, since \(\alpha > 0\), we have \(c_p(\mu_x, E_i) \leq (c_p(\mu_x, E_i))^{-1} - \alpha\).
Remark 2. Let us note that in all examples, the coefficients $c_i$ from the decomposition of the identity will indeed verify condition (21). If not, this property can however be enforced using the invariance by conjugacy of $G$, by a standard averaging procedure. Indeed, if $\sum c(R_i)P_{E_i} = \text{Id}$, then conjugating by $g \in G$,

$$\text{Id} = g \cdot \left( \sum_i c(R_i)P_{E_i} \right) g^{-1} = \sum_i c(R_i)P_{gE_i} = \sum_j c(gR_jg^{-1})P_{E_j},$$

using that any $g \in G$ permutes the $m$-tuple $(E_1, \ldots, E_m)$. Averaging over $G$ yields

$$\text{Id} = \sum_j \left( \int_G c(gR_jg^{-1}) d\gamma(g) \right) P_{E_j},$$

and the new coefficients $c'_j := \int_G c(gR_jg^{-1}) d\gamma(g)$ then verify (21).

A simple and useful instance of the previous theorem is when $c_p(G) \leq \kappa \min_i c_i$ (or more generally, when (20) holds with $d_i \leq \kappa c_i$). Indeed, we can then conclude that the variance estimate (15) for invariant functions, passes to general function $f : \mathbb{R}^n \to \mathbb{R}$, in the case when $-\alpha = \rho \leq 0$, with only an additional multiplicative factor:

$$\text{Var}_\mu(f) \leq (1 + 4\kappa) \int c_i(c_p(\mu_{x,E_i})^{-1} - \alpha)^{-1}|P_{E_i}\nabla f(x)|^2 d\mu(x).$$

$$\leq (1 + 4\kappa) \sup_{i,x} c_i(c_p(\mu_{x,E_i})^{-1} - \alpha)^{-1} \int |\nabla f|^2 d\mu$$

Let us present a few examples where we are in such a situation.

(i) Unconditional symmetries: in this case $m = n$, and $R_i$ is the reflection of hyperplane $\{x; x_i = 0\}$. Obviously $E_i = \mathbb{R}e_i$ and $c_i = 1$ provide the decomposition $\sum E_i = \text{Id}$. The group $G$ generated by these $n$ reflections is commutative and isomorphic to $\{-1,1\}^n$ (with coordinate-wise multiplication). With our notation $c_p(G) = \frac{1}{n}$. Indeed, by the usual tensorisation property it is enough to deal with the case $n = 1$, which is quite simple as for $f : \{-1,1\} \to \mathbb{R}$, for the uniform probability on the two-points space $\text{Var}(f) = (f(0) - f(1))^2/4$, while the Dirichlet form is $\int (f(x) - f(-x))^2 d\gamma(x) = (f(0) - f(1))^2$. In particular, for any $n$, $c_p(G) = \frac{1}{n} \min_i c_i$, which ensures (22) for general functions, at the expense of an additional factor $(1 + 4\kappa) = 2$.

(ii) The group of symmetries of the regular simplex of $\mathbb{R}^n$, say with barycentre at 0, can be represented as the group of permutations on its $n + 1$ vertices $u_1, \ldots, u_{n+1}$. It is generated by $n(n + 1)/2$ reflections, which correspond to transpositions of two vertices. Let us denote them $R_{i,j}$ for $1 \leq i < j \leq n + 1$. Then $E_{i,j} = \mathbb{R}(u_i - u_j)$. The corresponding decomposition of the identity is

$$\frac{2}{n+1} \sum_{1 \leq i < j \leq n+1} P_{E_{i,j}} = \text{Id},$$

(the appendix explains why all the coefficients can be taken equal. Taking traces gives their common value). Hence in this case $c_{i,j} = 2/(n + 1)$. When the generating set is taken to be the set $\{R_{i,j}\}$ of all transpositions (which is indeed stable by conjugacy), the spectral gap of the Cayley graph of the symmetric group was computed by Diaconis and Shahshahani [14]. Their result can be stated in our notation as $c_p(G) = 1/2(n + 1)$ which is again equal to $\min c_{i,j}/4$. Thus (22) holds with $(1 + 4\kappa) = 2$.

(iii) The group of symmetries of the regular $k$-gon in the plane, has $2k$ elements: $k$ rotations and $k$ reflections. The set $G = \{R_1, \ldots, R_k\}$ of reflections generate the group and is stable by conjugacy. The corresponding decomposition of the identity is $\text{Id}_{2^2} = (2/k) \sum_{i=1}^k P_{E_i}$, hence $c_i = 2/k$ for all $i$. Next, the Cayley graph $\Gamma$ of $G$ for the generating set $G$ is a complete bipartite
graph on $2k$ elements (direct and undirect isometries being the two sets of vertices). With our notation $2c_p(\mathcal{G})$ is the inverse of the smallest positive eigenvalue of $kI - A$, where $A$ is the adjacency matrix of $\Gamma$ and $I$ the identity of the same size. The spectrum of this adjacency matrix is easily computed. One obtains $c_p(\mathcal{G}) = 1/(2k) = \min c_{ij}/4$, as before.

(iv) The latter two examples are finite irreducible reflection groups. These groups have been classified by Coxeter. We may ask whether a similar inequality between the coefficients of the decomposition of the identity (given by Lemma A.1) and the spectral gap holds for all of them. Diaconis and Shahshahani have expressed the spectral gap for Cayley graphs of groups, with conjugacy stable generating sets, in terms of the characters of irreducible decompositions. Since the representation theory of reflection groups is well understood, it is in principle possible to settle this question.

(v) The group of direct isometries of the regular $k$-gon is generated by the set $\mathcal{G}$ of its non-trivial rotations. For each such rotation $R_i$, $1 \leq i \leq k - 1$, $E_i = \mathbb{R}^2$, hence one can take $c_i = 1/(k - 1)$ in the decomposition of the identity. The corresponding Cayley graph is the complete graph on $k$ vertices. This leads to $c_p(\mathcal{G}) = 1/(2k)$. This example is not interesting in itself, since each $E_i$ is equal to the whole space. It will be of interest though as a factor in a product group.

It will be useful to consider groups of isometries having a product structure. This is the case of reflection groups, which factor as direct products of irreducible reflection groups. So let us assume that $\mathcal{G} = \{R_1, \ldots, R_m\}$ can be written as a disjoint union $\mathcal{G}_1 \cup \ldots \cup \mathcal{G}_\ell$, such that the sets $\text{Fix}(\mathcal{G}_i)^\perp$, $i = 1, \ldots, \ell$ are orthogonal. This implies, in particular, that $\mathcal{G}$ is the direct product of the corresponding groups $G_1, \ldots, G_\ell$, which act on different blocks of an orthogonal decomposition of $\mathbb{R}^n$. For convenience, let us denote $\mathcal{G}_j = \{R_{j,1}, \ldots, R_{j,m_j}\}$ and $E_{j,i} = \text{Fix}(R_{j,i})^\perp$. Note that conjugacy will respect the product structure. Therefore, the Poincaré inequality (20) holds (with some abuse of notation) with $d_{ij} = c_p(\mathcal{G}_j)$ for all $i \leq m_j$, which satisfy (21). By doing so, we get in (22) a result sharper than by using the Poincaré constant over the whole product, which is $c_p(\mathcal{G}) = \max_j c_p(\mathcal{G}_j)$. In particular, if we have a decomposition of the identity $\{c_{ij}, E_{ij}\}$ with

$$d_{ij} = c_p(\mathcal{G}_j) \leq \kappa \min c_{ij},$$

then, for all function $f : \mathbb{R}^n \to \mathbb{R}$ that is locally Lipschitz,

$$\text{Var}_\mu(f) \leq (1 + 4\kappa) \int \sum_{ij} c_{ij}(c_p(\mu_{x,E_{ij}})^{-1} - \alpha)^{-1} |P_{E_{ij}} \nabla f(x)|^2 \, d\mu(x).$$

In particular, if the decomposition of the identity is obtained by concatenating decompositions of the identity for each $G_j$ on the subspace where it acts, having checked the condition on each factor implies it on the whole space. This allows us to get new examples from those listed above, leading to interesting spectral inequalities, as discussed in the next section. We will consider, in particular, direct products where the factors are isometry groups of simplices in different dimensions, or groups of (direct or general) isometries of regular polytopes in planes.

6. Spectral gap estimate for log-concave measures

6.1. Using weighted Poincaré inequalities

We next show how to pass from the weighted Poincaré-type inequalities that we have established so far to spectral gap estimates, by using inequalities like (22), which is stronger than (23). Let $\mu$ be a log-concave probability measure, invariant by isometries $R_1, \ldots, R_m$ satisfying Setting 8. We also assume that $\sum c_i P_{E_i} = \text{Id}$, where $c_i > 0$ satisfy that $c_i = c_j$ when $R_i$ and $R_j$ are conjugates in the group $G$ that these isometries generate (recall that $E_i$ is the orthogonal of
constant $F$. Applying Jensen inequality twice, we obtain a universal constant such that
\[
\text{the equivalence between the bound } (2)\text{. We obtain, with the probabilistic notation where $X$ is a random vector with distribution $\mu$,}
\]
\[
\text{Setting } \kappa = \max_i d_i/c_i \text{ and using the decomposition of the identity gives}
\]
\[
\Var_{\mu}(f) \leq 4 \sum_{i=1}^m (c_i + 4d_i)c_p(\mu_{x_i,E_i})|P_{E_i}\nabla f(x)|^2 \, d\mu(x).
\]
The weight in front of the gradient may be unbounded. However, a deep result of Milman [30] ensures that for log-concave probabilities, any weight appearing in front of the gradient in such inequality can be ‘averaged out’ of the integral up to a numerical constant (because of the equivalence between $L^2$ and $L^\infty$ Poincaré inequalities), and so we obtain that there is a universal constant $c_0$ such that
\[
c_p(\mu) \leq c_0 (1 + 4\kappa) \max_{1 \leq i \leq m} \mathbb{E}[|P_{E_i}X|^2|P_{F_i}X] \cdot \tag{25}
\]
To estimate the latter expectation, we use the so-called $\psi_1$-property of log-concave distribution (which is related to the result of Borell [8] recalled at the end of §2): there exists a universal constant $c$ such that, for any $k \geq 1$, any log-concave random vector $Y$ in $\mathbb{R}^k$ and any even $1$-homogeneous convex function $H : \mathbb{R}^k \to \mathbb{R}^+$,
\[
\mathbb{E}\exp \left( \frac{H(Y)}{c \mathbb{E}(H(Y))^2} \right) \leq 2.
\]
Setting $D = c^2 \max_i \mathbb{E}(|P_{E_i}X|^2)$, using the convexity of $\psi_1/2(t) = \exp(\sqrt{t + t})$, $t \geq 0$ and applying Jensen inequality twice, we obtain
\[
\psi_{1/2} \left( \mathbb{E} \left[ \max_{1 \leq i \leq m} \mathbb{E}[D^{-1}|P_{E_i}X|^2|P_{F_i}X] \right] \right) \leq \mathbb{E} \max_{1 \leq i \leq m} \mathbb{E}[\psi_{1/2}(D^{-1}|P_{E_i}X|^2)|P_{F_i}X] \leq \mathbb{E} \sum_{1 \leq i \leq m} \mathbb{E}[\psi_{1/2}(D^{-1}|P_{E_i}X|^2)|P_{F_i}X] \]
\[
= \sum_{1 \leq i \leq m} \mathbb{E}[\psi_{1/2}(D^{-1}|P_{E_i}X|^2)] \leq c \sum_{1 \leq i \leq m} \mathbb{E}[^{\exp(D^{-1/2}|P_{E_i}X|)}] \leq 2cm.
\]
This estimates leads to
\[
c_p(\mu) \leq c'(1 + 4\kappa)(1 + \log m)^2 \max_i \mathbb{E}(|P_{E_i}X|^2).
\]
If $\mu$ is also isotropic, then $c_p(\mu) \leq c'(1 + 4\kappa)(1 + \log m)^2 \max_i \dim(E_i)$. These estimates depend on the number of isometries involved, so it is better to choose them parsimoniously. In particular, note that in the previous estimation of $\mathbb{E}[^{\max_{1 \leq i \leq m} \mathbb{E}(|P_{E_i}X|^2|P_{F_i}X)]$, what really
m' := \text{Card}(\{ E_i; \ i = 1, \ldots, m\}), \quad \text{(26)}

for if \( E_i = E_j \), then \( \mathbb{E}[|P_{E_i}X|^2|P_{E_j}X] = \mathbb{E}[|P_{E_j}X|^2|P_{E_j}X] \) which contributes only once in the supremum. So under the same assumptions, the bound for a log-concave isotropic theoretical proof that.

\[
c_p(\mu) \leq c'(1 + 4\kappa)(1 + \log m')^2 \max_i \dim(E_i). \quad \text{(27)}
\]

Let us illustrate the interest of such bound in the following application, which extends Klartag’s result to more general sets of reflections.

**Corollary 14.** Let \( H_1, \ldots, H_m \) be hyperplanes of \( \mathbb{R}^n \) such that \( \bigcap_{i=1}^{m} H_i = \{0\} \). Let \( \mu \) be an isotropic log-concave measure on \( \mathbb{R}^n \), which is invariant by the hyperplane symmetries \( S_{H_1}, \ldots, S_{H_m} \). Then \( c_p(\mu) \leq c \log(1 + n)^2 \), where \( c > 0 \) is a numerical constant.

**Proof.** The group generated by the reflections \( G \) that leave \( \mu \) invariant might be quite large and we want to apply (27) to a well chosen set of generators as discussed at the end of the previous section. Indeed, the structure of reflection groups is fully described by Coxeter’s classification theorem. As explained in the appendix, there is an orthogonal decomposition \( \mathbb{R}^n = E_1 \oplus \cdots \oplus E_t \), such that \( \mathcal{G} \) contains a subgroup \( \mathcal{G}' = \mathcal{O}(P_1) \times \cdots \times \mathcal{O}(P_t) \) where \( P_i \) is either a regular simplex of full dimension in \( E_i \) or a regular polygon if \( E_i \) is a plane. Set \( \mathcal{G}_i = \mathcal{O}(P_i) \) if \( P_i \) is a regular simplex in dimension at least 3 and \( \mathcal{G}_i = SO(P_i) \) if \( P_i \) is a regular polygon, and set \( \mathcal{G}'' := \mathcal{G}_1 \times \cdots \times \mathcal{G}_t \). This subgroup of \( \mathcal{G} \) only fixes the origin. Let us describe precisely the generators of \( \mathcal{G}'' \) that we consider.

(i) If \( n_i := \dim(E_i) \geq 3 \), then \( \mathcal{O}(P_i) \) is generated by the \( n_i(n_i + 1)/2 \) hyperplane symmetries of a regular simplex in \( E_i \). We denote by \( R_{i,j} \), \( 1 \leq j \leq n_i(n_i + 1)/2 \) the hyperplane reflections on \( \mathbb{R}^n \) which extend them to \( \mathbb{R}^n \) (by acting as the identity on \( E_i \)).

(ii) If \( n_i := \dim(E_i) = 2 \), then \( P_i \) is a regular \( k_i \)-gon. We consider all its non-trivial rotations \( R_{i,j} \), \( j = 1, \ldots, k_i - 1 \) as acting on the whole \( \mathbb{R}^n \). Obviously, \( E_{i,j} = \text{Fix}(R_{i,j}) = E_i \) is of dimension 2 and \( F_{i,j} = \text{Fix}(R_{i,j}) = E_i^\perp \). These spaces do not depend on \( j \), and so they contribute only once in (26).

We define \( \mathcal{G}'' \) as the set of all isometries \( R_{i,j} \). It generates \( \mathcal{G}'' \) and is stable by conjugacy. Moreover, by the remarks at the end of the previous section, \( \mathcal{G}'' \) satisfies all the required hypotheses to carry on the previous analysis of \( c_p(\mu) \) (a decomposition of the identity is obtained by putting together those on individual subspaces \( E_i \). Note that it is obvious when \( n_i = 2 \). Also \( \kappa = \frac{1}{2} \)). In order to conclude, we just need to estimate the number \( m' \) (which is smaller than the number of generators in \( \mathcal{G}'' \)):

\[ m' = \sum_{i,n_i \neq 2} \frac{n_i(n_i + 1)}{2} + \text{card}(\{ i; \ n_i = 2\}) \leq \sum_{i,n_i \neq 2} n_i^2 + \sum_{i,n_i = 2} n_i^2 \leq \left( \sum_i n_i \right)^2 = n^2. \]

Consequently, from (27), we get that \( c_p(\mu) \leq c \log(1 + n)^2. \)

\[ \square \]

The method also applies to the case of the Schatten classes. The notation here are those from the end of §4. So \( X_{p,n} \sim \mu_{\lambda B_p^n} \) is an isotropic log-concave random vector uniformly distributed on a multiple \( \lambda B_p^n \) of the unit ball of the Shatten space \( S_p^n \). The dimension is \( n = d^2 \). Consider again the linear maps \( R_i \) which flip the signs of all the entries in the \( i \)-th row of a matrix, \( i = 1, \ldots, d \). The orthogonal of the fixed point subspaces decompose the identity (with constant coefficients), and the group generated by the maps \( R_i \) is \( \{-1, 1\}^d \) (because the maps \( R_i \) commute and \( R_i^2 = \text{Id} \)), which also has a constant spectral gap. So the estimate (27)
applies and we obtain that
\[ c_p(X_{n,p}) \leq c\sqrt{n}\log(1 + n)^2, \]
for some universal constant \( c > 0 \).

### 6.2. Anti-invariance of eigenfunctions

The previous subsection recovers Klartag’s bound on the spectral gap for isotropic unconditional bodies [26], but by a different method. Below we briefly present a streamlined version of his argument, which applies to rather general symmetries (even in comparison to the previous subsection).

We consider a (strictly) log-concave probability measure \( \mu \) with density \( e^{-\Phi} \) with \( \Phi \) smooth and \( D^2\Phi > 0 \). We also assume that the spectral gap is achieved, that is, when there is a (smooth) non-zero \( \varphi \in L^2(\mu) \) belonging to the domain of \( L \) such that
\[ L\varphi = -\lambda_1(\mu)\varphi \quad \text{where} \quad \lambda_1(\mu) := \frac{1}{c_p(\mu)}. \]

This is the case if, for instance, \( D^2\Phi(x) \geq \varepsilon_0 \text{Id} \) for all \( x \in \mathbb{R}^n \), for some \( \varepsilon_0 > 0 \). Indeed, the paper [33] puts forward functional inequalities involving \( \mu \) which ensure that the operator \( L \) has an empty essential spectrum. Since the condition \( D^2\Phi \geq \varepsilon_0 \text{Id} \) guaranties that \( \mu \) satisfies a log-Sobolev inequality, it then follows that the spectral gap is achieved. Inequalities weaker than log-Sobolev, called super-Poincaré inequalities, are actually enough to get to such a conclusion; however, even for log-concave measures, a Poincaré inequality is not sufficient, as shown by the case of the exponential measure. Note that the condition \( D^2\Phi \geq \varepsilon_0 \text{Id} \) may be ensured by adding \( \varepsilon_0|x|^2/2 \) to the potential \( \Phi(x) \) for an arbitrarily small \( \varepsilon_0 > 0 \).

**Proposition 15.** Let \( \mu \) be a strictly log-concave probability measure. Let \( R_1, \ldots, R_m \in O_n(\mu) \) such that \( \bigcap_{i \leq m} \text{Fix}(R_i) = \{0\} \). Then, if \( u \) is a non-zero eigenfunction for \( \lambda_1(\mu) \), there exists \( j \leq m \) such that the function
\[ \varphi(x) := u(R_jx) - u(x) \quad \forall x \in \mathbb{R}^n \] (28)
is again a non-zero eigenfunction for \( \lambda_1(\mu) \).

It is worth noting that when the maps \( R_i \) are such that \( R_i^2 = \text{Id} \) (for instance, when the \( R_i \) are reflections or \(-\text{Id}\) ), then the function \( \varphi \) of the theorem verifies \( \varphi(R_jx) = -\varphi(x) \) for all \( x \in \mathbb{R}^n \). In the case of even measures and of unconditional measures, the existence of an eigenfunction verifying this anti-symmetry was proved by Klartag [26].

**Proof.** Let \( u \) be an eigenfunction. Note that the functions \( u \circ R_i \) are also eigenfunction, so if the first conclusion of the theorem is false (that is, if for any choice of \( j \) the corresponding \( \varphi \) is zero), then it means that, for all \( i \leq m \), we have that \( u \circ R_i = u \). Taking gradients, integrating with respect to \( \mu \) and using its invariance by \( R_i \) then gives \( R_i^{-1} \int \nabla u \, d\mu = \int \nabla u \, d\mu \). Hence \( \int \nabla u \, d\mu \in \cap_i \text{Fix}(R_i) \). Our assumptions on the maps \( R_i \) then implies that
\[ \int \nabla u \, d\mu = 0. \]
Consequently, \( \int \partial_i u \, d\mu = 0 \) for \( i = 1, \ldots, n \), and therefore by the Poincaré inequality and by (10), we have
\[
\lambda_1(\mu) \int u^2 \, d\mu = \int |\nabla u|^2 \, d\mu \leq \frac{1}{\lambda_1(\mu)} \sum_{i=1}^n \int |\partial_i u|^2 \, d\mu = \frac{1}{\lambda_1(\mu)} \int \|D^2 u\|^2 \, d\mu \leq \frac{1}{\lambda_1(\mu)} \int (Lu)^2 \, d\mu = \lambda_1(\mu) \int u^2 \, d\mu.
\]
Equality means, from the use of (10), that \( D^2 \Phi \nabla u \cdot \nabla u = 0 \) on \( \mathbb{R}^n \) and so \( \nabla u = 0 \). Therefore \( u \) is constant, and this constant must be zero (\( \lambda_1 > 0 \)). This shows that when we start from a non-zero eigenfunction \( u \), we can indeed find a \( j \leq m \) such that the corresponding \( \varphi = u \circ R_j - u \) is a non-zero eigenfunction.

The interest of having a non-zero eigenfunction of the form (28) comes from the mean zero property given by Fact 9. Using the same argument as Klartag [26], we can deduce from the existence of an ‘anti-invariant’ eigenfunction an estimation on the spectral gap, similar to the bound (23) holding under different hypotheses.

**Corollary 16.** Let \( \mu \) be a log-concave function on \( \mathbb{R}^n \) and \( R_1, \ldots, R_m \in O_n(\mu) \) such that \( \bigcap_{i \leq m} \text{Fix}(R_i) = \{0\} \). Assume that the spectral gap is achieved. Then we have, setting \( E_i = \text{Fix}(R_i)^\perp \),
\[
c_p(\mu) \leq \max_{i \leq m} \sup_{x \in \text{Fix}(R_i)} c_p(\mu_{x,E_i}).
\]

**Proof.** By the previous proposition and Fact 9, we know that there exists \( j \leq m \) and a non-zero eigenfunction such that \( \int_{E_j} \varphi \, d\mu_{x,E_j} = 0 \) for all \( x \in \mathbb{R}^n \). This implies that
\[
\int_{E_j} \varphi^2 \, d\mu_{x,E_j} \leq c_p(\mu_{x,E_j}) \int_{E_j} |P_{E_j} \nabla \varphi|^2 \, d\mu_{x,E_j} \leq C(\mu) \int_{E_j} |\nabla \varphi|^2 \, d\mu_{x,E_j},
\]
setting \( C(\mu) := \max_{i \leq m} \sup_{x \in \text{Fix}(R_i)} c_p(\mu_{x,E_i}). \) The conclusion follows from Fubini’s theorem, since by definition \( \int \nabla \varphi^2 \, d\mu = c_p(\mu)^{-1} \int \varphi^2 \, d\mu. \)

To follow Klartag’s proof in order to reach bounds depending only on \( n \) for isotropic measures, one upper bounds \( c_p(\mu_{x,E_i}) \) as before, considers the probability \( \mu_{|A} \) measure obtained by restricting \( \mu \) to a set \( A = \{ x \in \mathbb{R}^n; \forall i \leq m, |P_{E_i} x| \leq C \} \), where \( C \) should be tuned to ensure \( \mu(A) \geq 1/2 \) and thus \( d_{TV}(\mu, \mu_{|A}) \leq 1 \) (while the maximum distance is 2). Another result by Milman [30] ensures \( c_p(\mu_{|A}) \approx c_p(\mu_{|A}). \) If \( \mu_{|A} \) has the same invariances (which requires stability by conjugacy of the set of isometries), then applying the previous theorem to \( \mu_{|A} \) gives \( c_p(\mu_{|A}) \leq C^2. \) Eventually, one chooses \( C \) to be an upper estimate of \( 2 \mathbb{E} \max_i |P_{E_i} X| \) which is derived from the \( \psi_1 \) property of log-concave distributions. We skip the details.

7. An application to conservative spin systems

We now apply the previous tools to a conservative non-interacting unbounded spin system. Below, \( \mu \) will be a probability measure on \( \mathbb{R} \) of the form \( d\mu(t) = e^{-V(t)} \, dt \). For \( n \geq 2 \) and \( m \in \mathbb{R} \), we consider the probability measure obtained by restriction of the product measure \( \mu^n = \mu \otimes \ldots \otimes \mu \) on \( \mathbb{R}^n \) to the affine hyperplane \( H_m^n = \{ x \in \mathbb{R}^n; \sum_i x_i = nm \} \):
\[
\mu^{n|m} := \mu^n \left( \sum_{i=1}^n x_i = nm \right).
\]
Equivalently, the density of $\mu_{n|m}$ with respect to Lebesgue’s measure of $H_m^n$ is proportional to

$$\exp\left(-\sum_{i=1}^{n} V(x_i)\right).$$

As always, $H_m^n \simeq H_0^n \simeq \mathbb{R}^{n-1}$ is viewed as an Euclidean space for the structure inherited from $\mathbb{R}^n$.

Ergodic inequalities have been studied for these measures. Varadhan posed the following question [32]: for which kind of single-site potentials $V$ is it true that the measures $\mu_{n|m}$ have a uniform spectral gap, that is, $\sup_{n,m} c_p(\mu_{n|m}) < +\infty$? The same question may also be asked for the stronger logarithmic Sobolev inequalities. After contributions by Landim–Panizo–Yau [28], Caputo [10], Chafai [11], Grunewald–Otto–Villani–Westdickenberg [19], a very satisfactory answer was recently given by Menz and Otto [29]. They show that if $V = \varphi + \psi$, with $\inf_x \varphi''(x) > 0$ and $\|\psi\|_{\infty}, \|\psi'\|_{\infty} < +\infty$, then the measures $\mu_{n|m}$ satisfy a log-Sobolev inequality with constants which do not depend on $n$ and $m$. In particular, if $V$ is a bounded and Lipschitz perturbation of a strictly uniformly convex function, then $\sup_{n,m} c_p(\mu_{n|m}) < +\infty$.

The arguments of these articles are quite involved. They rely heavily on the fact that the spectral gap is uniform, which allows induction on coordinates or coarse-graining approaches. Our goal is to show how the symmetries can be exploited to provide a soft proof of various results for these measures. Some of them apply to the sub-quadratic case where it is known that the spectral gap cannot be uniform in $m$. Not much is known in this case (note that the first named author and Wolff [6] have obtained precise estimates of the spectral gap and log-Sobolev constants when $\mu$ is a Gamma distribution with parameter at least 1).

The measure $\mu^n$ is obviously invariant by permutations of coordinates. Since $H_m^n = \{x \in \mathbb{R}^n; \sum_i x_i = nm\}$ is invariant as well, it follows that $\mu_{n|m}$ is invariant by the restrictions to $H_m^n$ of permutations of coordinates of $\mathbb{R}^n$. They obviously act as a permutation of the points $\text{nme}_1, \ldots, \text{nme}_m$ which form a regular simplex in $H_m^n$ with barycentre at $(m, \ldots, m)$. It is convenient to consider this point as the new origin for this hyperplane. Summarizing, $\mu_{n|m}$ is invariant by the group of isometries of a regular simplex. Our previous results apply, and require the estimation of the Poincaré constants of restrictions to lines which are orthogonal to the hyperplanes of symmetries. These restrictions have a very simple structure, as we put forward next.

For $1 \leq i < j \leq n$, let $S_{i,j}$ be the hyperplane symmetry defined on $\mathbb{R}^n$ by $S_{i,j}(e_k) = e_{\tau_{i,j}(k)}$ where $\tau_{i,j}$ is the transposition of $i$ and $j$, that is, $S_{i,j} = S_{(e_i-e_j)+}$. We shall view $S_{i,j}$ as a hyperplane symmetry of $H_m^n$. Setting $E_{i,j} := \text{Fix}(S_{i,j})^\perp = \mathbb{R}(e_i - e_j)$, we can note that for $x \in H_m^n$, we have $x + E_{i,j} \subset H_m^n$.

**Lemma 17.** Let $n \geq 2$. For any $x \in H_m^n$ and all $i < j$,

$$c_p(\mu_{n|m}^{x,E_{i,j}}) = c_p(\mu^{2|(x_i+x_j)/2}).$$

**Proof.** Since permutations of coordinates leave $\mu_{n|m}$ invariant, we can assume that $i = 1$ and $j = 2$. Then

$$x + E_{1,2} = \left\{ \left( x_1 + \frac{s}{\sqrt{2}}, x_2 - \frac{s}{\sqrt{2}}, x_3, \ldots, x_n \right); \ s \in \mathbb{R} \right\} = \left\{ \left( \frac{x_1 + x_2}{2} + \frac{t}{\sqrt{2}} x_3, \ldots, x_n \right); \ t \in \mathbb{R} \right\},$$
where we have chosen parameterizations of unit speed. Hence the density of $\mu^{n|m}$ at point of $x + E_{1,2}$ is proportional to
\[
\exp\left(-V\left(\frac{x_1 + x_2}{2} + \frac{t}{\sqrt{2}}\right) - V\left(\frac{x_1 + x_2}{2} - \frac{t}{\sqrt{2}}\right) - V(x_1) - \ldots - V(x_n)\right).
\]
Note that the last $n - 2$ terms are constant on $x + E_{1,2}$. Hence they disappear when conditioning $\mu^{n|m}$ to this line:
\[
\mu^{n|m}_{x, E_{i,j}}(dt) = \frac{1}{Z} \exp\left(-V\left(\frac{x_1 + x_2}{2} + \frac{t}{\sqrt{2}}\right) - V\left(\frac{x_1 + x_2}{2} - \frac{t}{\sqrt{2}}\right)\right) dt,
\]
where $Z$ is the normalization constant. This measure corresponds to the normalized restriction of $\mu^2$ to the line $\{y \in \mathbb{R}^2; y_1 + y_2 = x_1 + x_2\}$, that is, to $\mu_0^{2[(x_1 + x_2)/2]}$.

The next statement is then an obvious consequence of the results of Section 5.

**Proposition 18.** Assume that there exists $\alpha \in \mathbb{R}^+$ such that, for all $t \in \mathbb{R}$, $V''(t) \geq -\alpha$ and $\sup_{n,m} c_p(\mu^{2|m}) < 1/\alpha$. Then,
\[
\sup_{n,m} c_p(\mu^{n|m}) \leq 2 \sup_m (c_p(\mu^{2|m})^{-1} - \alpha)^{-1}.
\]

**Proof.** Recall that for a measure $d\nu(x) = e^{-W(x)} dx/Z$, it is convenient to call $W$ a potential of $\nu$. Since $\mu$ has a potential with second derivative bounded from below by $-\alpha$, so does the product measure $\mu^n$: the Hessian of its potential is bounded from below by $-\alpha \text{Id}$. By restriction, this property passes to $\mu^{n|m}$. Since the latter measure has the symmetries of the regular simplex, we are in a position to apply Theorem 13 by the remarks after (23) in the case of invariances by the symmetric group. Lemma 17 allows us to deal with the restrictions to lines which are orthogonal to hyperplanes of symmetries.

In what follows, let us adopt the notation $a \approx b$ for the existence of numerical constants $c, C > 0$ such that $ca \leq b \leq CB$; by numerical constants we mean universal computable constants (and so independent of $n, m, V$, etc.)

In the case convex single-site potentials, we can get a precise quantitative estimate of the uniform Poincaré constant (finite or infinite):

**Proposition 19.** If the potential $V$ is convex, then
\[
\sup_{n,m} c_p(\mu^{n|m}) \approx \sup_m c_p(\mu^{2|m}) \approx \sup_m \left(\int_0^{+\infty} e^{-[V(m+t)+V(m-t)-2V(m)]} dt\right)^2.
\]

**Proof.** Applying the previous proposition with $\alpha = 0$ (recall the convention for non-negative numbers $1/0 = +\infty$) gives
\[
\sup_m c_p(\mu^{2|m}) \leq \sup_{n,m} c_p(\mu^{n|m}) \leq 2 \sup_m c_p(\mu^{2|m}),
\]
which gives the first approximate equality. Note that applying Corollary 16 would remove the factor 2 and give an equality (this may require an approximation argument in order to ensure the existence of an eigenfunction corresponding to the spectral gap).
Note that $\mu^{2|m}$ can be viewed as the probability measure on $\mathbb{R}$ with density $f(t)\,dt/\int f$, where
\[
f(t) = \exp \left( -V \left( m + \frac{t}{\sqrt{2}} \right) + V \left( m - \frac{t}{\sqrt{2}} \right) \right)
\]
is an even log-concave function on $\mathbb{R}$. A result of Bobkov [7] (see also [24]) states that for log-concave measures on the line, the bound (2) is sharp, and so
\[
c_p(\mu^{2|m}) \approx \text{Var}_{\mu^{2|m}}(t) = \frac{\int_\mathbb{R} t^2 f(t) \, dt}{\int_\mathbb{R} f(t) \, dt}.
\]
Next, we apply a very classical fact about even log-concave measures on the real line (see, for example, [2, 31]):
\[
\frac{1}{3} \leq \frac{f(0)^2 \int_0^{+\infty} t^2 f(t) \, dt}{(\int_0^{+\infty} f(t) \, dt)^2} \leq 2.
\]
It follows that
\[
c_p(\mu^{2|m}) \approx \left( \frac{\int_0^{+\infty} f(t) \, dt}{f(0)} \right)^2 = \left( \int_0^{+\infty} \exp(-V(m+t/\sqrt{2}) - V(m-t/\sqrt{2}) + 2V(m)) \, dt \right)^2.
\]
The claim follows after an obvious change of variables.

The previous characterization allows us to distinguish two different types of behaviours:

(i) If $V(t) = |t|$, one gets that $\int_0^{+\infty} e^{-\omega(V(m+t)+V(m-t)-2V(m))} \, dt = |m| + 1/2$ and there is no uniform spectral gap. The same happens if $V(t) = |t|^{\beta}$ for $\beta \in (1, 2)$ as a study of the corresponding integrals for $m \to \infty$ shows.

(ii) If any strict uniform convexity property of $V$ holds, of the form
\[
\forall m, t \in \mathbb{R}, \quad V(m+t) + V(m-t) - 2V(m) \geq \omega(t) \quad \text{with} \quad \int_\mathbb{R} e^{-\omega} < \infty,
\]
then we can guarantee a uniform spectral gap. This condition is more general than the usual strict uniform convexity $V'' > 0$ and is verified, for example, by potential $V(t) = t^\beta$, $\beta > 2$ (see below).

We conclude this section with an example of application. It is definitely less encompassing than the recent Menz–Otto theorem, but covers some cases of non-convex potentials which were not treated by Caputo for technical reasons.

**Corollary 20.** Let $C : \mathbb{R}^+ \to \mathbb{R}$ be a non-constant convex non-decreasing function.

Let $\psi : \mathbb{R}^+ \to \mathbb{R}$ be twice continuously differentiable with $\|\psi\|_\infty, \|\psi''\|_\infty < +\infty$. Let $V_\epsilon(t) = C(t^2) + \epsilon \psi(t)$ and $d\mu_\epsilon(t) = e^{-V_\epsilon(t)} \, dt/Z_\epsilon$ the corresponding probability measure. Then there exists $\epsilon_0 > 0$ such that for all $\epsilon \in [-\epsilon_0, \epsilon_0]$,
\[
\sup_{n,m} c_p(\mu^{n|m}_\epsilon) < +\infty.
\]

**Proof.** Let us start with the case $\epsilon = 0$. The single site potential is convex and we may apply the previous proposition. Thanks to the convexity of $C$, used twice
\[
V_0(m+t) + V_0(m-t) - 2V_0(m) = C(m^2 + t^2 + 2mt) + C(m^2 + t^2 - 2mt) - 2C(m^2) \\
\geq 2(C(m^2 + t^2) - C(m^2)) \geq 2(C(t^2) - C(0)) \\
= 2(V_0(t) - V_0(0)) \geq V_0(t) - V_0(0).
\]
Hence
\[ \int_{\mathbb{R}^+} \exp(-|V_0(m + t) + V_0(m + t) - 2V_0(m)|) \, dt \leq \int \exp(-V_0(t) + V_0(0)) \, dt = Z_0 e^{V_0(0)} < +\infty. \]

The case of \( \varepsilon \neq 0 \) is obtained by perturbation. First note that \( V''(t) \geq -|\varepsilon||\psi''|_\infty \). Setting \( \alpha := |\varepsilon||\psi''|_\infty \), we deduce that the potential \( \Phi \) of \( \mu_\varepsilon^{2|m} \) satisfies \( D^2 \Phi \geq -\alpha \text{Id} \) pointwise.

Thanks to Proposition 18, proving that, for all \( m \), \( c_p(\mu_\varepsilon^{2|m}) \leq 1/(2\alpha) \) would be enough to establish the uniform spectral gap inequalities for the measures \( \mu_\varepsilon^{n|m} \), \( n \geq 2 \), \( m \in \mathbb{R} \). But this follows from the classical Holley–Stroock bounded perturbation principle (on \( \mathbb{R} \)): if \( dv = e^g \, d\mu \), then \( c_p(v) \leq e^{\sup g - \inf g_\Phi(\mu)} \). Indeed the potential of \( \mu_\varepsilon^{2|m} \) differs from the one of \( \mu_0^{2|m} \) only by the term \( \varepsilon \psi(m + t/\sqrt{2}) + \varepsilon \psi(m - t/\sqrt{2}) \) (and a constant term coming from normalization, which does not contribute to the oscillation of the perturbation). Hence
\[ c_p(\mu_\varepsilon^{2|m}) \leq e^{4|\varepsilon||\psi|_\infty} c_p(\mu_0^{2|m}) \leq c(Z_0 e^{V_0(0)/2} e^{4|\varepsilon||\psi|_\infty}), \]
where we have used the estimate established in the \( \varepsilon = 0 \) case. Consequently, if \( |\varepsilon| \) verifies that
\[ c(Z_0 e^{V_0(0)/2} e^{4|\varepsilon||\psi|_\infty}) \leq \frac{1}{2|\varepsilon||\psi''|_\infty}, \]
then we have uniform Poincaré constant for the measures \( \mu_\varepsilon^{n|m} \), \( n \geq 2 \), \( m \in \mathbb{R} \). This is obviously true when \( \varepsilon \) is close enough to zero.

Finally, let us state a result for log-concave single-site potentials, which just uses the symmetries of \( \mu_\varepsilon^{n|m} \). It follows from what we already proved for log-concave measures with the symmetries of the simplex:

**Theorem 21.** Let \( \mu \) be a log-concave measure on \( \mathbb{R} \). Let \( \ell : \mathbb{R}^n \to \mathbb{R} \) defined by \( \ell(x) = x_i \sqrt{n/(n - 1)} \), for any \( i \leq n \). Then, for all \( n \geq 2 \), \( m \in \mathbb{R} \),
\[ \text{Var}_{\mu_\varepsilon^{n|m}}(\ell) \leq c_p(\mu_\varepsilon^{n|m}) \leq c(\log n)^2 \text{Var}_{\mu_\varepsilon^{n|m}}(\ell), \]
where \( c \) is a universal constant.

**Proof.** Since the measure \( \mu_\varepsilon^{n|m} \) is invariant by an irreducible groups of isometries, it is automatically a dilate (by \( \sqrt{\text{Var}_{\mu_\varepsilon^{n|m}}(\ell)} \)) of an isotropic distribution. Note that \( \ell \) is a linear function with unit length gradient (in \( H_n^m \) Euclidean structure). So the left-hand side inequality just follows by applying the Poincaré inequality to \( \ell \). The right-hand side inequality is a particular case of what we have proved for isotropic log-concave measures having the symmetries of the simplex.

The previous result applies even when there are no uniform bounds. The structure of the measure may be used to estimate precisely the variance of linear functions (say of \( \ell \)).

8. **Isotropy constant of bodies with invariances**

This section investigates bounds on the isotropic constant of convex bodies (having, as before, many invariances). This problem is central in the asymptotic theory of convex bodies, and is closely related to the questions discussed in previous sections, although the methods we use here are rather different. We work with convex bodies rather than with measures, mainly for convenience and for historical reasons.
Recall that the isotropy constant of a convex body $K \subset \mathbb{R}^n$ is the positive number defined by

$$L_K^2 = \inf_{T \in A(\mathbb{R}^n)} \frac{1}{|TK|^{1+2/n}} \int_{TK} \frac{|x|^2}{n} \, dx,$$

where $A(K)$ denotes the affine group. The infimum is achieved for a map $T_0$ if and only if the barycentre of $T_0K$ is at the origin, and there exists a constant $M$ such that, for all $\theta \in \mathbb{R}^n$,

$$\frac{1}{|T_0K|^{1+2/n}} \int_{T_0K} \langle x, \theta \rangle^2 \, dx = M|\theta|^2.$$

One then says that $T_0K$ is in isotropic position. Note that necessarily, $M = L_K^2$ and that $K \to \int_K |x|^2 \, dx/|K|^{1+2/n}$ being invariant by dilations, one may find a minimizer also satisfying $|T_0K| = 1$. In what follows, we shall also assume that our convex bodies have their barycenter at the origin.

A major open problem is whether the numbers $L_K$ are uniformly bounded, independently of the dimension (a classical reference is [31]). This question is in fact related to the variance conjecture, as established in [15]. It will be convenient to define $L(d)$ as the supremum of the isotropy constant of convex bodies in $\mathbb{R}^d$. The best-known upper bound is due to Klartag [25]:

$$L(d) \leq c d^{1/4}.$$

Given a subspace $E \subset \mathbb{R}^n$, the measures $|F \cap E|$ and $|P_F E| \subset \mathbb{R}^d$ for clarity. By convention, we have $|A|_d = 1$ if $d = 0$ (that is, $E = \{0\}$) and $0 \in A$.

The isotropy constant is related to the size of sections of bodies in isotropic position. This principle goes back to Hensley [22]. The next statement appears in the lecture notes by Giannopoulos [18, pp. 60–61]; it is a non-symmetric version of a result of Ball [2] (see also [17] for sharp constants in the hyperplane case).

**Theorem 22.** Let $n > m$ and let $C \subset \mathbb{R}^n$ be a convex body in isotropic position. Let $E$ be a subspace of $\mathbb{R}^n$ with codimension $m$. Then

$$|C \cap E|^{1/m} L_C \leq \kappa L(m) |C|^{1/m-1/n},$$

where $\kappa$ is a universal constant.

Let us emphasize a useful property of subspaces obtained as fixed-point spaces of an isometry of $K$.

**Lemma 23.** Let $K \subset \mathbb{R}^n$ be a convex body and $U \in O_n(K)$. Then, for $F := \text{Fix}(U)$, we have

$$P_F K = K \cap F.$$ 

**Proof.** For $k \geq 1$, let $U_k := (\text{Id} + U + \ldots + U^k)/(k + 1).$ We use that $\lim_{k \to \infty} U_k = P_F$ (to see this, simply diagonalize $U$ over $\mathbb{C}$). The convexity of $K$ ensures that $U_kx \in K$ for every $x \in K$, and taking limits gives $P_F x \in K$. Hence $P_F K \subset K \cap F$. \qed

As noted by several authors in the 1980s, unconditional convex bodies have a bounded isotropy constant. The next statement gives a similar result for more general symmetries. Surprisingly, the symmetries may leave unchanged a large subspace.
THEOREM 24. Let $K$ be an origin-symmetric convex body in $\mathbb{R}^n$. Assume that there exist isometries $U_1, \ldots, U_m \in O_n(K)$ and coefficients $c_1, \ldots, c_m > 0$ such that, setting $E_i = \text{Fix}(U_i)^\perp$,

$$\sum_{i=1}^m c_i P_{E_i} = P_E,$$

for some subspace $E \in \mathbb{R}^n$. If the codimension $d$ of $E$ verifies $d \leq \alpha n/\log n$, then

$$L_K \leq C(\alpha) \max_i L(\text{dim}(E_i)).$$

REMARK 3. Recall that $\bigcap_i \text{Fix}(U_i) = E^\perp$. Hence, the condition on $d$ means that $\dim(\bigcap_i \text{Fix}(U_i)) \leq \alpha n/\log n$. In other words, the group of isometries of $K$ may not act on a subspace of dimension $n/\log(n)$.

Proof. First let us note that we may assume that $K$ is isotropic. Indeed let $A$ be the positive matrix such that, for all $\theta \in \mathbb{R}^n$, $\int_K (x \cdot \theta)^2 \, dx = A\theta \cdot \theta$. Then it is plain that $A^{-1/2}K$ is isotropic. For any isometry $U$ preserving $K$,

$$A\theta \cdot \theta = \int_K (x \cdot \theta)^2 \, dx = \int_{UK} (x \cdot \theta)^2 \, dx = AU^{-1}\theta \cdot U^{-1}\theta.$$

Hence $UAU^* = A$, that is $AU = UA$. Consequently, $UA^{-1/2}K = A^{-1/2}UK = A^{-1/2}K$. So $A^{-1/2}K$ is isotropic and has the same isometric invariances.

It is convenient to set $F_0 = E$ and for $i \geq 1$, $F_i = \text{Fix}(U_i)$. Since $P_{E_i} = \text{Id} - P_{F_i}$ for $i = 1, \ldots, m$, the decomposition of the Theorem gives

$$\sum_{i=0}^m c_i' P_{F_i} = \text{Id},$$

(29)

where $c_i' = (\sum_{j=1}^m c_j)^{-1}$ and for $i \geq 1$, $c_i' = c_i/(\sum_{j=1}^m c_j)$. This decomposition of the identity allows us to apply the geometric version of the Brascamp–Lieb inequality (see, for example, [4]): since $K \subset \bigcap_{i=0}^m \{x \in \mathbb{R}^n; P_{F_i}x \in P_{F_i}K\}$,

$$|K| \leq \prod_{i=0}^m \int_{\mathbb{R}^n} 1_{P_{F_i}K}(P_{F_i}x) c_i' \, dx \leq \prod_{i=0}^m \left( \int_{F_i} 1_{P_{F_i}K}(x) \, dx_i \right)^{c_i'}$$

$$= |P_{E_i}K|^{c_i'} \prod_{i=1}^m |P_{F_i}K|^{c_i'}.$$

Note that a special case of this inequality was derived by geometric methods in [3, Theorem 3]. Set $d_i = \dim(E_i) = n - \dim(F_i)$. For $i \geq 1$, since $F_i = \text{Fix}(U_i)$ and $U_i$ leaves $K$ invariant, we know by Lemma 23 and Theorem 22 that

$$|P_{F_i}K| = |K \cap F_i|_{n-d_i} \leq |K|^{(n-d_i)/n} \left( \frac{nL(d_i)}{L_K} \right)^{d_i}.$$

For the projection onto $E$, we first use the Rogers–Schecht inequality

$$|P_{E_i}K|_{n-d} \leq \left( \frac{n}{d} \right)^{n} \frac{|K|}{|K \cap E^\perp|}.$$

Next, by a result of Kannan–Lovász–Simonovits [24], $|K|^{1/n} L_K B_2^n \subset K$ (actually for symmetric convex sets this can be found in a stronger form in the article by Milman and Pajor [31]).
Taking sections yields $|K \cap E^\perp_d| \geq |K|^{d/n} L_K^d |B_d^d|_d$, hence
\[
|P_{E^\perp_d}K|_{n-d} \leq \binom{n}{d} L_K^{(n-d)/n} |K|^{(n-d)/n} |B_d^d|_d.
\]
Combining these bounds yields
\[
|K| \leq \left( \frac{n}{d} \right) |K|^{(n-d)/n} L_K^{d/n} \prod_{i=1}^m \left( |K|^{(n-d_i)/n} \left( \frac{\kappa L(d_i)}{L_K} \right)^{d_i} \right) \epsilon_i.
\]
Taking traces in $\binom{n}{d}$ gives $n = \epsilon_0(n-d) + \sum_{i \geq 1} \epsilon_i(n-d_i)$ so that the terms in $|K|$ cancel out. The latter equality can be also stated as $n - d = \sum_{i \geq 1} c_i d_i$. Using also that $c' = (\epsilon_0', \epsilon_1', \ldots, \epsilon_m')$ is proportional to $c = (1, c_1, \ldots, c_m)$ and rearranging the terms gives
\[
L_K \leq \left( \frac{n}{d} \right)^{1/d} \prod_{i=1}^m (\kappa L(d_i))^{c_i d_i/\sum_{j \geq 1} c_j d_j} \leq \left( \frac{n}{d} \right)^{1/d} \left( \frac{\kappa \max_i L(d_i)}{n} \right)^{1-d/n} \leq \beta' e^{\kappa d/2 \log n} \max_i L(d_i),
\]
where $\beta, \beta' > 0$ are universal constants. We have also used that $\inf_k L(k) > 0$. 

**Corollary 25.** Let $K \subset \mathbb{R}$ be a convex body with barycentre at the origin. Assume that there exists (non necessarily orthogonal) symmetries $S_1, \ldots, S_m$ with respect to hyperplanes $H_1, \ldots, H_m$ such that, for all $i \leq m$, $S_i K = K$ and $\dim(\bigcap_{i \leq m} H_i) \leq \alpha(n/\log n)$. Then $L_K \leq C(\alpha)$. 

**Proof.** Since any compact subgroup of the linear group is affinely conjugated to a subgroup of the orthogonal group, and since the isotropy constant is an affine invariant, we may assume that the $S_i$ are orthogonal hyperplane symmetries. The reflection group $G$ that they generate satisfies $\text{Fix}(G) \subset \bigcap_{i \leq m} H_i$. Hence, by Lemma A.2, there exists unit vectors $v_1, \ldots, v_\ell$ and coefficients $c_1, \ldots, c_\ell$ such that $S_{v_i} K = K$ and
\[
\sum_{i \leq \ell} c_i P_{v_i} = P_{\text{Fix}(G) \perp}.
\]
Hence we may apply Theorem 24. 

**Appendix. Some observations concerning reflections**

A reflection group $G$ is a subgroup of some $O_n$ generated by reflections (that is, by hyperplane symmetries). It is irreducible if there is no non-trivial subspace stable by all elements of $G$.

**Lemma A.1.** Let $G$ be a finite irreducible reflection group acting on $\mathbb{R}^n$. Let $V = \{v \in S^{n-1}; v_\perp \in G\}$. Then, using the tensor notation $(v \otimes v)(x) = \langle x, v \rangle v$ for projections on lines, we have
\[
\sum_{v \in V} v \otimes v = \frac{\text{card}(V)}{n} \text{Id}.
\]
Proof. Note that, for \( v \in V \) and \( R \in G \), it holds \( RS_n R^{-1} = S_{(Rv)^{-}} \in G \). Hence \( R \) restricted to \( V \) is a permutation of \( V \). Set \( L = \sum_{v \in V} v \otimes v \). The previous observation implies that
\[
R L R^{-1} = R L R^* = \sum_{v \in V} R v \otimes R v = L.
\]
Hence \( L \) is in the centre of \( G \). Let \( \lambda \) be an eigenvalue of the self-adjoint map \( L \) and the corresponding eigenspace. By the above commutation, \( L \) is globally invariant by all elements of \( G \) and it is not empty. By irreducibility \( E = \mathbb{R}^n \) and \( L = \lambda \text{Id} \).

**Lemma A.2.** Let \( \mathcal{R} \subset O_n \) be a closed reflection group. Then there exist \( m \in \mathbb{N} \), unit vectors \( v_1, \ldots, v_m \) such that \( S_{v_i} \in \mathcal{R} \) for all \( i \leq m \) and coefficients \( c_1, \ldots, c_m > 0 \) such that
\[
\sum_{i=1}^{m} c_i v_i \otimes v_i = P_E,
\]
where \( E = \text{Fix}(\mathcal{R}) \).

**Proof.** Classically \( \mathbb{R}^n \) can be written as an orthogonal sum of \( \text{Fix}(\mathcal{R}) \) and of spaces \( E_1, \ldots, E_\ell \) irreducible for the action of \( \mathcal{R} \). Also, \( \mathcal{R} \) can be written as a direct product of reflection groups \( \mathcal{R}_i \) acting, in an irreducible manner, on the subspaces \( E_i \). If \( \mathcal{R}_i \) is finite, the previous lemma gives a decomposition of \( \text{Id}_{E_i} \). When \( \mathcal{R}_i \) is infinite (and closed), it acts on \( E_i \) as the whole orthogonal group, and it is not hard to find a decomposition of the identity on \( E_i \) since all unit vectors are allowed. Finally, summing up the decomposition on each \( E_i \) yields the claimed decompositions of the identity on \( \text{Fix}(\mathcal{R}) \).

In view of the previous lemma, a natural and convenient invariance hypothesis to work with is the following: there exist isometries \( (U_i)_{i=1}^{m} \) such that \( U_i k = k \) and positive coefficients \( (c_i)_{i=1}^{m} \) such that
\[
\sum_{i=1}^{m} c_i P_{\text{Fix}(U_i)^\perp} = P_E. \tag{A.1}
\]
This implies that, for all \( x \in \mathbb{R}^n \), \( |P_E x|^2 = \sum c_i |P_{\text{Fix}(U_i)^\perp} x|^2 \). Hence \( \bigcap_i \text{Fix}(U_i) = E^\perp. \) Usually \( E \) will be a large space, meaning that the isometries actually operate on a large part of the space. Let us provide concrete examples of invariance hypotheses.

Unconditional convex bodies have attracted a lot of attention. They are invariant by changes of signs of coordinates, or equivalently by reflection with respect to the coordinate hyperplanes of an orthonormal base \( (e_1, \ldots, e_n) \). In this particular case, (A.1) boils down to \( \sum c_i e_i = \text{Id} \).

A natural extension is to consider sets \( K \) in \( \mathbb{R}^{kd} \) which are unconditional by blocks (of size \( d \)): \( (x_1, \ldots, x_k) \in K \Rightarrow (\pm x_1, \ldots, \pm x_k) \in K \). The isometries defined by \( R_{i} : (x_1, \ldots, x_k) \mapsto (x_1, \ldots, x_{i-1}, -x_i, x_{i+1}, \ldots, x_k) \) satisfy that \( \text{Fix}(R_i) = \{ x = (x_1, \ldots, x_k) \in \mathbb{R}^{kd}; \ x_i = 0 \} \) and it is plain that \( \sum_i P_{\text{Fix}(R_i)^\perp} = \text{Id} \).

This pattern naturally occurs when considering matricial norms which only depend on the absolute values of matrices. Let us consider a norm on \( M_n(\mathbb{R}) \) of the form \( ||A|| = f(A^*A) \) (Schatten norms \( ||A||_p = (\text{Tr}((A^*A)^{p/2}))^{1/p} \), \( p \geq 1 \) are the simplest examples). Then if
\[
E_i := \text{Diag} \left( 1, \ldots, 1, -1, 1, \ldots, 1 \right),
\]
then the maps \( R_i : A \mapsto E_i A \) are isometries of \( (M_n(\mathbb{R}), ||.||_2) \) since \((E_i A)^* E_i A = A^* A \). Note that \( R_i A \) is obtained from \( A \) by changing the signs of all the entries of the \( i \)th row of \( A \).
Consequently, the unit ball of any Schatten norm is unconditional by blocks of size \( n \). Note that \( \text{Fix}(R_i) = \{ A \in M_n(\mathbb{R}) ; a_{i,j} = 0, \forall j \leq n \} \) has a codimension \( n \) while the ambient space is of dimension \( n^2 \). Plainly \( \sum_j P_{\text{Fix}(R_i)^+} = \text{Id} \).

Thanks to Coxeter’s classification of irreducible finite reflection groups, one may obtain many concrete examples of invariances. Among them, let us emphasize the group of isometries of dimension \( n \) and \( \text{Fix}(R_i) \) such a rotation and consider the plane \( \Pi \). By reflections, the direct isometries in \( \text{SO}(n) \) act by permutations of these vertices. The group \( \text{O}(\Delta_n) \) contains exactly \( n(n+1)/2 \) reflections; namely the \( S_{(u_i-u_j)^+} \), for \( 1 \leq i < j \leq n+1 \). They correspond to transpositions.

Another natural invariance hypothesis is related to the regular simplex: namely the exchangeability condition. A set or a measure is exchangeable if it is invariant by permutations of coordinates. Here one considers the isometries of \( \mathbb{R}^n \) given by

\[ R_\sigma : (x_1, \ldots, x_n) \mapsto (x_{\sigma(1)}, \ldots, x_{\sigma(n)}) , \]

where \( \sigma \in \mathcal{S}_n \). The group \( G = \{ R_\sigma ; \sigma \in \mathcal{S}_n \} \) has a line of fixed points: \( \text{Fix}(G) = \mathbb{R}v_n \), where \( v_n = (1, \ldots, 1) \). It is a reflection group generated by the images of transpositions \( R_{e_{ij}} \). On \( v_n^+ \), \( G \) acts as \( \text{O}(\Delta_{n-1}) \). Indeed, it permutes the points \( (e_i - v_n/n)_{i=1}^n \) which form a regular simplex of \( v_n^+ \).

Lemma A.2 thus provides a decomposition of the form (A.1)

\[ \frac{2}{n} \sum_{i<j} e_i - e_j \otimes e_i - e_j = P_{v_n^+} . \]

One could in the same way introduce a block-exchangeability condition and derive a corresponding decomposition.

We can also consider invariances involving only direct isometries. For instance, the next statement encompasses the set \( \text{SO}(\Delta_n) \) of direct isometries of the simplex.

**Lemma A.3.** Let \( G \) be a finite reflection group acting on \( \mathbb{R}^n, n \geq 2 \). Set \( E = \text{Fix}(G)^+ \). Then there exists \( m, \) rotations \( U_1, \ldots, U_m \in G \cap \text{SO}(n) \) with \( \dim(\text{Fix}(U_i)^+) = 2 \), and coefficients \( c_1, \ldots, c_m \geq 0 \) such that

\[ \sum_{i=1}^m c_i P_{\text{Fix}(U_i)^+} = P_E , \]

where \( F \) is \( E \) or a hyperplane of \( E \) (the latter occurs when \( G \) has an odd number of one-dimensional irreducible factors).

**Proof.** First assume that \( G \) is irreducible and acts on \( \mathbb{R}^n \) with \( n \geq 2 \). Since it is generated by reflections, the direct isometries in \( G \) are generated by products of two reflections, that is, rotations (since \( n \geq 2 \) there are at least two distinct reflections). Let \( R \in G \cap \text{SO}(n) \) be such a rotation and consider the plane \( \Pi = \text{Fix}(R)^+ \). For all \( U \in G, \) \( URU^{-1} \in G \cap \text{SO}(n) \) and \( \text{Fix}(URU^{-1}) = U\text{Fix}(R)^+ = \Pi U \). Also note that for every subspace \( \Sigma, \) \( U P_\Sigma U^{-1} = P_{\Sigma} \).

Consider

\[ L = \sum_{U \in G} P_{\text{Fix}(RU^{-1})^+} = \sum_{U \in G} P_{\Pi U} . \]

From the above remarks and the group property, for all \( V \in G, \) \( VLV^{-1} = L \). So \( L \) commutes with all the elements of \( G \). Since \( L \) is a symmetric positive map, it has at least a non-zero eigenvalue \( \lambda \). By the commutation, the eigenspace \( E_\lambda \) is stable by \( G \) and thus by irreducibility it is the whole space. Hence \( L = \lambda \text{Id} \). This proves the claim for an irreducible group \( G \).

For a general group, we consider the induced irreducible decomposition. On components of dimension at least 2 we apply the above argument. We group the one-dimensional components
by two. On each such plane the rotation of angle $\pi$ is in the group, as the product of minus identity on each irreducible line. The decomposition of the identity of this plane is obvious (the origin is the only fixed point of the rotation). Summing up all these decompositions, we obtain the claim. Note that when there is an odd number of one-dimensional irreducible components, one of them is left aside.

Finally, we recall a useful lemma, which uses more of the explicit description of finite reflection groups, see [5].

**Lemma A.4.** Let $G$ be a reflection group on $\mathbb{R}^n$. Assume that the set of its reflections is closed. If $\text{Fix}(G) = \{0\}$, then there exists an orthogonal decomposition $\mathbb{R}^n = F_1 \oplus \ldots \oplus F_t$ and polytopes $P_i \subset F_i$ for all $i \leq t$ such that $P_i$ is a (full dimension) regular simplex in $F_i$, or a regular polygon if $F_i$ is of dimension 2, such that

$$O(P_1) \times \ldots \times O(P_t) \subset G.$$

If $E_i$ is a line, then by convention $P_i$ is a symmetric interval. Note that $\text{Fix}(O(P_1) \times \ldots \times O(P_t)) = \{0\}$. The interest of this result is to provide a simple reflection subgroup of $G$ with no nontrivial fixed points.

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