# DESCRIPTIVE PROPERTIES OF THE TYPE OF AN IRRATIONAL NUMBER 

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#### Abstract

The type $\tau(\alpha)$ of an irrational number $\alpha$ measures the extent to which rational numbers can closely approximate $\alpha$. More precisely, $\tau(\alpha)$ is the infimum over those $t \in \mathbb{R}$ for which $|\alpha-h / k|<k^{-t-1}$ has at most finitely many solutions $h, k \in \mathbb{Z}, k>0$. In this paper, we regard the type as a function $\tau: \mathbb{R} \backslash \mathbb{Q} \rightarrow[1, \infty]$ and explore its descriptive properties. We show that $\tau$ is invariant under the natural action of $G L_{2}(\mathbb{Q})$ on $\mathbb{R} \backslash \mathbb{Q}$. We show that $\tau$ is densely onto, and we compute the descriptive complexity of the pre-image of the singletons and of certain intervals. Finally, we show that the function $\tau$ is $[1, \infty]$-upper semi-Baire class 1 complete.


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## 1. Introduction

Descriptive set theory is a branch of mathematical logic that revolves around the study of "definable sets" in Polish (i.e., separable, completely metrizable) spaces. In this theory, well-behaved sets are classified in hierarchies arranged according to the complexity of their definitions, and the structure of the sets at each level in the hierarchy is methodically analyzed. Descriptive set theory is a primary area of research in set theory and has applications in other areas of mathematics, including ergodic theory, functional analysis, and the study of operator algebras and group actions.

Number theory (or higher arithmetic) is a branch of pure mathematics that is devoted to the study of prime numbers, integers, integer-valued functions, and mathematical objects constructed from the integers (for example, the set $\mathbb{Q}$ of rational numbers). One also studies real numbers in relation to rational numbers, for example, as approximated by the latter; this is Diophantine approximation. Although many problems in number theory can be approached using analytic or algebraic techniques, such methods do not lend themselves well to the study of irrational numbers. Transcendental number theory bears little resemblance to other branches of number theory, although it is an indispensable part of the field.

The present paper is a rare example in the literature of results that bridge the two branches of mathematics described above (another example is the excellent paper of Jackson et al [5], which contains an application of descriptive set theory to number theory). Our work originates in the observation that the set of irrational real numbers $\mathbb{R} \backslash \mathbb{Q}$ is a Polish space (in the usual topology), and hence various distinguished subsets of $\mathbb{R} \backslash \mathbb{Q}$ are of simultaneous interest in both disciplines. The initial aim of this paper was to combine techniques from both descriptive set theory and number theory to determine precisely the descriptive complexity of subsets of $\mathbb{R} \backslash \mathbb{Q}$ consisting of all irrational numbers of a specified irrationality type (see the definition in §1.1). Later on, as our tools developed, our goals became more ambitious. In the end, we have shown (among other things and in a sense to be made precise below) that the function afforded by irrationality type has the highest descriptive complexity in its class; it is likely the first concrete example of a Baire complete function for the natural class of functions in which it resides.

Our methods are fairly general and can be applied to other Polish spaces. To formulate our results, we first recall some standard terminology. ${ }^{1}$
1.1. The type of an irrational number. For a real number $x$, we write $\llbracket x \rrbracket$ to denote the distance from $x$ to the nearest integer:

$$
\llbracket x \rrbracket:=\min _{n \in \mathbb{Z}}|x-n| .
$$

For any irrational number $\alpha$, the type of $\alpha$ is the quantity defined by ${ }^{2}$

$$
\begin{equation*}
\tau(\alpha):=\sup \left\{\theta \in \mathbb{R}: \varliminf_{q \in \mathbb{N}} q^{\theta} \llbracket q \alpha \rrbracket=0\right\} \tag{1.1}
\end{equation*}
$$

[^1]The Dirichlet approximation theorem ${ }^{3}$ implies that $\tau(\alpha) \in[1, \infty]$. One says that $\alpha$ is of finite type if $\tau(\alpha)<\infty$. The celebrated theorems of Khinchin [7] and of Roth $[\mathbf{1 0}, \mathbf{1 1}]$ assert that $\tau(\alpha)=1$ for almost all real numbers (in the sense of the Lebesgue measure) and all irrational algebraic numbers, respectively.

A Liouville number is an irrational number $\alpha$ with the property that for each positive integer $n$ there exist integers $p$ and $q>1$ such that

$$
\begin{equation*}
\left|\alpha-\frac{p}{q}\right|<\frac{1}{q^{n}} . \tag{1.2}
\end{equation*}
$$

Using (1.2) it is easy to show that $\alpha$ is a Liouville number if and only if $\tau(\alpha)=\infty$.
We remark that the quantity $\mu(\alpha):=\tau(\alpha)+1$ is called the irrationality measure (or the Liouville-Roth constant) associated with $\alpha$, and very often it occurs in the literature instead of $\tau(\alpha)$; this is largely a matter of taste.
1.2. Borel hierarchy and completeness of sets. Let $\mathcal{X}$ be a Polish space, i.e., a separable and completely metrizable topological space. The Borel hierarchy on $\mathcal{X}$ consists of sets $\boldsymbol{\Sigma}_{\xi}^{0}(\mathcal{X}), \boldsymbol{\Pi}_{\xi}^{0}(\mathcal{X})$, and $\boldsymbol{\Delta}_{\xi}^{0}(\mathcal{X})$, which are defined for every countable ordinal $\xi>0$. The elements of these sets are all subsets of $\mathcal{X}$. The space $\mathcal{X}$ is not mentioned when there is no ambiguity or when $\mathcal{X}$ is considered as a variable (in the latter case, for instance, a set $A$ is in the class $\boldsymbol{\Sigma}_{\xi}^{0}$ if there is a Polish space $\mathcal{X}$ such that $A$ belongs to the $\left.\operatorname{set} \boldsymbol{\Sigma}_{\xi}^{0}(\mathcal{X})\right)$. When $\mathcal{X}$ is fixed, these sets are defined inductively according to the following rules:

- $A \in \Sigma_{1}^{0}$ if and only if $A$ is open in $\mathcal{X}$;
- $A \in \boldsymbol{\Pi}_{\xi}^{0}$ if and only if $\mathcal{X} \backslash A \in \boldsymbol{\Sigma}_{\xi}^{0}$;
- For $\xi>1, A \in \Sigma_{\xi}^{0}$ if and only if $A$ is the union of some countable collection $\left\{A_{j}: j \in \mathbb{N}\right\}$ such that each $A_{j}$ lies in $\boldsymbol{\Pi}_{\xi_{j}}^{0}$ for some $\xi_{j}<\xi$;
- $A \in \boldsymbol{\Delta}_{\xi}^{0}$ if and only if $A \in \boldsymbol{\Sigma}_{\xi}^{0}$ and $A \in \boldsymbol{\Pi}_{\xi}^{0}$.

The class of Borel sets ramifies in the following hierarchy:

and every class is contained in any class to the right of it. If $\mathcal{X}$ is an uncountable Polish space, then one has $\boldsymbol{\Sigma}_{\xi}^{0} \neq \boldsymbol{\Pi}_{\xi}^{0}$ for every countable ordinal $\xi>0$; for a proof, see Kechris [6, Thm. 22.4].

Note that $\mathbb{R} \backslash \mathbb{Q}$ is Polish since it is a $G_{\delta}$ subspace of the Polish space $\mathbb{R}$ (see [6, Thm. 3.11]). A subset of a topological space $\mathcal{X}$ is clopen if it is closed and open, and $\mathcal{X}$ is zero-dimensional if it has a basis consisting of clopen sets. The space $\mathbb{R} \backslash \mathbb{Q}$ is zero-dimensional since it is the complement of $\mathbb{Q}$, which is dense in $\mathbb{R}$. Moreover, $\mathbb{R} \backslash \mathbb{Q}$ is uncountable, hence by $[\mathbf{6}$, Thm. 22.4] we have

$$
\Sigma_{\xi}^{0}(\mathbb{R} \backslash \mathbb{Q}) \neq \Pi_{\xi}^{0}(\mathbb{R} \backslash \mathbb{Q})
$$

[^2]for every countable ordinal $\xi>0$.
If $\mathcal{X}$ and $\mathcal{Y}$ are topological spaces, $A \subset \mathcal{X}$, and $B \subset \mathcal{Y}$, then $A$ is said to be Wadge reducible to $B$ if there is a continuous map $f: \mathcal{X} \rightarrow \mathcal{Y}$ with $f^{-1}(B)=A$ (that is, $x \in A \Longleftrightarrow f(x) \in B$ ); in this situation, we write $A \leqslant_{W} B$. Wadge reducibility provides a notion of the relative complexity of sets in topological spaces, where the notation $A \leqslant_{W} B$ indicates that $A$ is "simpler" than $B$ in a suitable sense. The relation $\leqslant_{W}$ is reflexive and transitive; it imposes an (essentially well-ordered in zero-dimensional spaces) hierarchy on the Borel sets, called the Wadge hierarchy. The classes $\boldsymbol{\Sigma}_{\xi}^{0}$ and $\boldsymbol{\Pi}_{\xi}^{0}$ are closed under continuous pre-images, and these classes are initial segments in the Wadge hierarchy.

Let $\boldsymbol{\Gamma}$ be a class of sets defined on Polish spaces. If $\mathcal{Y}$ is a Polish space, a subset $B \subset \mathcal{Y}$ is called $\Gamma$-complete if $B \in \Gamma(\mathcal{Y})$ and $A \leqslant_{W} B$ for any $A \in \Gamma(\mathcal{X})$, where $\mathcal{X}$ is any arbitrary zero-dimensional Polish space; see [6, Def. 22.9]. In particular, if $\mathcal{Y}$ is a zero-dimensional Polish space, then by a theorem of Wadge, one knows that $B \subset \mathcal{Y}$ is $\boldsymbol{\Sigma}_{\xi}^{0}$-complete [resp. $\boldsymbol{\Pi}_{\xi}^{0}$-complete] if and only if $B$ belongs to $\boldsymbol{\Sigma}_{\xi}^{0} \backslash \boldsymbol{\Pi}_{\xi}^{0}\left[\right.$ resp. $\left.\boldsymbol{\Pi}_{\xi}^{0} \backslash \boldsymbol{\Sigma}_{\xi}^{0}\right]$; see, for example, [6, Thm. 22.10]. In other words, relative to the Wadge ordering $\leqslant_{W}$, the sets in $\boldsymbol{\Sigma}_{\xi}^{0} \backslash \boldsymbol{\Pi}_{\xi}^{0}$ are maximal among all $\boldsymbol{\Sigma}_{\xi}^{0}$ sets (and similarly switching $\boldsymbol{\Sigma}_{\xi}^{0}$ and $\boldsymbol{\Pi}_{\xi}^{0}$ ). We remark that the hypothesis that $\mathcal{X}$ is zero-dimensional guarantees the existence of "sufficiently many" continuous functions (by contrast, the only continuous functions from $\mathbb{R}$ into the Cantor space $\{0,1\}^{\omega}$ are the constant functions). On the other hand, it is unnecessary to assume that $\mathcal{Y}$ is zero-dimensional in Wadge's theorem, for it holds in any uncountable Polish space; see [6, 24.20].
1.3. Baire hierarchy and completeness of functions. There is also a hierarchy of functions between Polish spaces called the Baire hierarchy. Recall that a function is continuous if the pre-image of any open set is open, i.e., in $\boldsymbol{\Sigma}_{1}^{0}$. A function is called Baire class 1 if the pre-image of any open set is in $\boldsymbol{\Sigma}_{2}^{0}$. More generally, in the light of [6, 24.1 and 24.3], a function is called Baire class $\xi$ if the pre-image of any open set is in $\Sigma_{\xi+1}^{0}$, for any countable ordinal $\xi$. Thus, the Baire class 0 functions are the continuous ones.

Recall that a function $f$ from a Polish space $\mathcal{X}$ into $\overline{\mathbb{R}}:=\mathbb{R} \cup\{-\infty, \infty\}$ is said to be upper semi- continuous (resp., lower semi-continuous) if $f^{-1}([-\infty, r))$ (resp., $f^{-1}((r, \infty])$ ) is an open subset of $\mathcal{X}$ for each real number $r$. Considering the usual order topology on $\overline{\mathbb{R}}$, which is homeomorphic to $[-1,1]$ and thus Polish, we see that the semi-continuous functions are (relatively simple) Baire class 1 functions. We naturally extend these notions to countable ordinals by saying that a function $f$ from a Polish space $\mathcal{X}$ into a subset $K \subset \overline{\mathbb{R}}$ is upper semi-Baire class $\xi$ [resp. lower semi-Baire class $\xi]$ if $f^{-1}([-\infty, r))\left[\right.$ resp. $\left.f^{-1}((r, \infty])\right]$ is a $\boldsymbol{\Sigma}_{\xi+1}^{0}$ subset of $\mathcal{X}$ for every real number $r$. As we show in Lemma 3.2, there is an equivalent definition of the type of an irrational number in terms of limit superior. According to Elekes et al [4, Theorem 2.1], functions defined in terms of limit superior are deeply connected with the upper-semi Baire class 1 functions.

The notion of a complete $K$-upper semi-continuous function was introduced and characterized in Solecki [13, Section 5]; this notion naturally extends here. Let $f: \mathcal{X} \rightarrow K$ be an upper semi-Baire class $\xi$ function. We say that $f$ is $K$ upper semi-Baire class $\xi$ complete if for every upper semi-Baire class $\xi$ function
$g: 2^{\omega} \rightarrow K$, there exists a continuous function $\phi: 2^{\omega} \rightarrow \mathcal{X}$ such that $g=f \circ \phi$. This notion generalizes the notion of completeness of sets defined above. ${ }^{4}$ Indeed, let $\mathbf{1}_{A}: \mathcal{X} \rightarrow\{0,1\}$ be the characteristic function a given subset $A \subset \mathcal{X}$. Then $\mathbf{1}_{A}$ is upper semi-Baire class $\xi$ if and only if $A \in \boldsymbol{\Pi}_{\xi+1}^{0}(\mathcal{X})$, and $\mathbf{1}_{A}$ is $\{0,1\}$-upper semi-Baire class $\xi$ complete if and only if $A$ is a $\boldsymbol{\Pi}_{\xi+1}^{0}$-complete subset of $\mathcal{X}$.
1.4. Statement of results. The group $\mathrm{GL}_{2}(\mathbb{Q})$ acts naturally on the space $\mathbb{R} \backslash \mathbb{Q}$ via Möbius transformations:

$$
g \alpha:=\frac{a \alpha+b}{c \alpha+d} \quad \text { for any } g=\left(\begin{array}{ll}
a & b  \tag{1.3}\\
c & d
\end{array}\right) \in \mathrm{GL}_{2}(\mathbb{Q}) \text { and } \alpha \in \mathbb{R} \backslash \mathbb{Q} .
$$

Our first theorem (proved in §3.3) asserts that the type of an irrational number is well-defined on the orbits of this action.

THEOREM 1.1. For all $\alpha \in \mathbb{R} \backslash \mathbb{Q}$ and $g \in \mathrm{GL}_{2}(\mathbb{Q})$ we have $\tau(g \alpha)=\tau(\alpha)$.
A consequence is that the type of an irrational number does not depend on the finite beginning of its continued fraction development (see Corollary 3.7). Next, we show that $\tau: \mathbb{R} \backslash \mathbb{Q} \rightarrow[1, \infty]$ is a densely onto map, meaning that the pre-image of any singleton is dense in the domain. Hence, the map afforded by type is discontinuous in quite a spectacular way.

Theorem 1.2. The function $\tau: \mathbb{R} \backslash \mathbb{Q} \rightarrow[1, \infty]$ is surjective. Moreover, for any given $\mathrm{t} \in[1, \infty]$, the set $\{\alpha \in \mathbb{R} \backslash \mathbb{Q}: \tau(\alpha)=\mathrm{t}\}$ is dense in the space $\mathbb{R} \backslash \mathbb{Q}$.

We give three proofs of Theorem 1.2, one in $\S 3.3$, another in $\S 3.5$, and another in $\S 5$. The next result is proved in $\S 6$.

Theorem 1.3. For every $\mathrm{t} \in[1, \infty)$, the set $\{\alpha \in \mathbb{R} \backslash \mathbb{Q}: \tau(\alpha)=\mathrm{t}\}$ is $\Pi_{3}^{0}-$ complete. In other words, it is a $\Pi_{3}^{0}$ set that does not belong to $\boldsymbol{\Sigma}_{3}^{0}$. The set $\{\alpha \in \mathbb{R} \backslash \mathbb{Q}: \tau(\alpha)=\infty\}$ is $\boldsymbol{\Pi}_{2}^{0}$-complete.

Our main result is the following; it is proved in $\S 5$.
Theorem 1.4. The type function is $[1, \infty]$-upper semi-Baire class 1 complete.
Very often in descriptive set theory, we can construct complete or universal objects using ad-hoc internal methods. There are few classes of sets or functions for which natural complete elements, coming from the rest of mathematics, are known. The type function provides an example of such an object.

[^3]
## 2. An ORIENTED GRAPH

2.1. Edges and trails. We denote by $\mathbb{N}$ the set of natural numbers (including zero) and by $\mathbb{N}_{1}$ the set of strictly positive natural numbers. In the sequel, we extensively use an oriented graph $\mathcal{G}$, defined as follows. For the vertex set, we take

$$
V:=\left\{(x, y) \in \mathbb{N}_{1}^{2}: x<y\right\} .
$$

Two vertices $v=(x, y)$ and $\tilde{v}=(\tilde{x}, \tilde{y})$ are connected by a directed edge from $v$ to $\tilde{v}$ if and only if there is a positive integer $a$ such that

$$
\begin{equation*}
\tilde{x}=y \quad \text { and } \quad \tilde{y}=a y+x . \tag{2.1}
\end{equation*}
$$

We write $v \stackrel{a}{\rightsquigarrow} \tilde{v}$ in this situation, and we say that $\tilde{v}$ is a vertex succeeding $v$, and that $v$ is the vertex preceding $\tilde{v}$. Note that every vertex $(\tilde{x}, \tilde{y})$ has at most one predecessor ( $x, y$ ), since the relations (2.1) imply that

$$
a=\lfloor\tilde{y} / \tilde{x}\rfloor, \quad x=\tilde{y}-a \tilde{x}, \quad y=\tilde{x}
$$

and therefore $(x, y)$ is determined uniquely by $(\tilde{x}, \tilde{y}) .{ }^{5}$
For a given vertex $v_{0} \in V$ and a sequence $a=\left(a_{n}\right)_{n \geqslant 1}$ of positive integers, we denote by $\operatorname{Tr}\left(v_{0}, a\right)$ the associated trail:

$$
\begin{equation*}
\operatorname{Tr}\left(v_{0}, a\right): \quad v_{0} \stackrel{a_{1}}{\rightsquigarrow} v_{1} \stackrel{a_{2}}{\rightsquigarrow} v_{2} \xrightarrow{a_{3}} v_{3} \stackrel{a_{4}}{\rightsquigarrow} \cdots . \tag{2.2}
\end{equation*}
$$

In this paper, we are interested in studying irrational numbers of a fixed type. Motivated by a characterization of type given in $\S 3.2$ below (see (3.8)) we introduce a map $\ell: V \rightarrow[1, \infty)$ which is defined by

$$
\forall v=(x, y) \in V: \quad \ell(v):= \begin{cases}\frac{\log y}{\log x} & \text { if } x>1  \tag{2.3}\\ 1 & \text { if } x=1\end{cases}
$$

For an infinite trail $\mathrm{T}=\operatorname{Tr}\left(v_{0}, a\right)$ of the form (2.2), we define the $\ell$-limit of T as

$$
\ell(\mathrm{T}):=\lim _{n \rightarrow \infty} \ell\left(v_{n}\right),
$$

provided this limit exists. We also define the $\ell$-limsup of T to be the quantity

$$
\bar{\ell}(\mathrm{T}):=\varlimsup_{n \rightarrow \infty} \ell\left(v_{n}\right) .
$$

Note that $\bar{\ell}(T) \in[1, \infty]$.

### 2.2. Hitting the target.

Lemma 2.1. Let $\varepsilon \in(0,1)$, and suppose that

$$
\begin{equation*}
\mathrm{t} \geqslant 1 \quad \text { and } \quad y>(10 / \varepsilon)^{1 / \varepsilon} . \tag{2.4}
\end{equation*}
$$

Given $v=(x, y) \in V$, there exists a positive integer a and vertex $\tilde{v}=(\tilde{x}, \tilde{y}) \in V$ such that (2.1) holds (in other words, $v \stackrel{a}{\rightsquigarrow} \tilde{v}$ ) and $\ell(\tilde{v}) \in[\mathrm{t}, \mathrm{t}+\varepsilon$ ).
${ }^{5}$ For all $u \in \mathbb{R}$, we denote by $\lfloor u\rfloor$ the largest integer that does not exceed $u$.

Proof. For all $u \in \mathbb{R}$, let $\lceil u\rceil$ be the smallest integer that is greater than or equal to $u$; note that $u \leqslant\lceil u\rceil<u+1$ for all $u$. The integer

$$
a:=\left\lceil y^{\mathrm{t}-1}-x / y\right\rceil
$$

is at least one since $x<y$ and $y^{\mathrm{t}-1} \geqslant 1$, and we have

$$
y^{\mathrm{t}-1}-x / y \leqslant a<y^{\mathrm{t}-1}-x / y+1 .
$$

Put $\tilde{x}:=y$ and $\tilde{y}:=a y+x$, so that (2.1) holds. Since

$$
\tilde{y}=a y+x \geqslant\left(y^{\mathrm{t}-1}-x / y\right) y+x=y^{\mathrm{t}}
$$

it follows that

$$
\ell(\tilde{v})=\frac{\log \tilde{y}}{\log \tilde{x}} \geqslant \frac{\log y^{\mathrm{t}}}{\log y}=\mathrm{t} .
$$

Similarly,

$$
\tilde{y}=a y+x<\left(y^{\mathrm{t}-1}-x / y+1\right) y+x=y^{\mathrm{t}}+y
$$

and therefore

$$
\ell(\tilde{v})=\frac{\log \tilde{y}}{\log \tilde{x}}<\frac{\log \left(y^{\mathrm{t}}+y\right)}{\log y}=\frac{\mathrm{t} \log y+\log \left(1+y^{1-\mathrm{t}}\right)}{\log y}<\mathrm{t}+\frac{y^{1-\mathrm{t}}}{\log y}
$$

where in the last step, we used the fact that $\log (1+u) \leqslant u$ for all $u>0$. In view of (2.4) we have

$$
\frac{y^{1-\mathrm{t}}}{\log y} \leqslant \frac{1}{\log y}<\frac{\varepsilon}{\log (10 / \varepsilon)}<\varepsilon
$$

thus we obtain the upper bound $\ell(\tilde{v})<\mathrm{t}+\varepsilon$. Thus $\ell(\tilde{v}) \in[\mathrm{t}, \mathrm{t}+\varepsilon)$.
Proposition 2.2. For every $v=(x, y) \in V$ and $\mathrm{t} \in[1, \infty]$, there exists an infinite trail $\mathrm{T}=\operatorname{Tr}(v, a)$ whose $\ell$-limit is $\ell(\mathrm{T})=\mathrm{t}$.

Proof. In the argument that follows, we use induction on $n$ to construct a sequence $\left(a_{n}\right)_{n \in \mathbb{N}} \subset \mathbb{N}$ for which the resulting trail

$$
\mathrm{T}=\operatorname{Tr}(v, a): \quad v \stackrel{a_{0}}{\rightsquigarrow} v_{0} \stackrel{a_{1}}{\rightsquigarrow} v_{1} \stackrel{a_{2}}{\rightsquigarrow} v_{2} \stackrel{a_{3}}{\rightsquigarrow} v_{3} \stackrel{a_{4}}{\rightsquigarrow} \ldots
$$

has the desired property.
Let $v_{0}:=\left(x_{0}, y_{0}\right)$ be the vertex defined by $x_{0}=y$ and $y_{0}=400 y+x$. Put $a_{0}:=400$, and note that $v \stackrel{a_{0}}{\rightsquigarrow} v_{0}$.

Next, suppose the vertex $v_{n}=\left(x_{n}, y_{n}\right) \in V$ has been defined for some $n \in \mathbb{N}$. Let $m \geqslant 2$ be the unique integer such that

$$
(10 m)^{m}<y_{n} \leqslant(10 m+10)^{m+1}
$$

(because each $y_{n}>400$, such an integer $m$ must exist). Put

$$
\varepsilon_{m}:=m^{-1} \quad \text { and } \quad \mathrm{t}_{m}:=\mathrm{t}+2 \varepsilon_{m} \geqslant 1 .
$$

Since $y_{n}>\left(10 / \varepsilon_{m}\right)^{1 / \varepsilon_{m}}$, we can apply Lemma 2.1 to conclude that there exists a positive integer $a_{n+1}$ and a vertex $v_{n+1}=\left(x_{n+1}, y_{n+1}\right) \in V$ such that

$$
v_{n} \stackrel{a_{n+1}}{\sim} v_{n+1} \quad \text { and } \quad \ell\left(v_{n+1}\right) \in\left[\mathrm{t}_{m}, \mathrm{t}_{m}+\varepsilon_{m}\right)=\left[\mathrm{t}+2 \varepsilon_{m}, \mathrm{t}+3 \varepsilon_{m}\right) .
$$

As $n$ tends to infinity, we have

$$
y_{n} \rightarrow \infty \quad \Longrightarrow \quad m \rightarrow \infty \quad \Longrightarrow \quad \varepsilon_{m} \rightarrow 0^{+} \quad \Longrightarrow \quad \ell(\mathrm{T})=\lim _{n \rightarrow \infty} \ell\left(v_{n}\right)=\mathrm{t}
$$

as required.

## 3. Continued fractions

3.1. Background on continued fractions. A (simple) continued fraction is an expression of the form

$$
\begin{equation*}
a_{0}+\frac{1}{a_{1}+\frac{1}{a_{2}+\frac{1}{a_{3}+\cdots}}}, \tag{3.1}
\end{equation*}
$$

where the coefficients $a_{n}$ are chosen independently of one another. In this paper, we consider only continued fractions with $a_{0} \in \mathbb{Z}$ and $a_{n} \in \mathbb{N}_{1}:=\mathbb{N} \backslash\{0\}$ for each $n \geqslant 1$; note that (3.1) always converges under these conditions. When the number of terms is finite, one writes

$$
\begin{equation*}
\left[a_{0} ; a_{1}, a_{2}, \ldots, a_{n}\right]:=a_{0}+\frac{1}{a_{1}+\frac{1}{a_{2}+\cdots \frac{1}{\cdots+\frac{1}{a_{n}}}}} \tag{3.2}
\end{equation*}
$$

and then $\left[a_{0} ; a_{1}, a_{2}, \ldots, a_{n}\right] \in \mathbb{Q}$. On the other hand, given an infinite sequence $\left(a_{0}, a_{1}, a_{2}, \ldots\right) \in \mathbb{Z} \times \mathbb{N}_{1}^{\omega}$, we denote by $\alpha=\left[a_{0} ; a_{1}, a_{2}, \ldots\right]$ the value of the infinite continued fraction (3.1); in this case, $\alpha$ is necessarily irrational, i.e., $\alpha \in \mathbb{R} \backslash \mathbb{Q}$. It is known that the map

$$
\alpha=\left[a_{0} ; a_{1}, a_{2}, \ldots\right] \mapsto\left(a_{0}, a_{1}, a_{2}, \ldots\right)
$$

is homeomorphism of $\mathbb{R} \backslash \mathbb{Q}$ (with the usual topology inherited from $\mathbb{R}$ ) onto $\mathbb{Z} \times \mathbb{N}_{1}^{\omega}$ (with the product topology). We give a proof of this fact below; see Proposition 3.5.

For any $\alpha=\left[a_{0} ; a_{1}, a_{2}, \ldots\right]$, the associated sequence $\left(a_{0}, a_{1}, a_{2}, \ldots\right)$ is used to derive the sequence of convergents $\left(\frac{h_{0}}{k_{0}}, \frac{h_{1}}{k_{1}}, \frac{h_{2}}{k_{2}}, \ldots\right) \in \mathbb{Q}^{\omega}$, where the numerators and denominators are defined inductively by

$$
\begin{array}{llll}
h_{0}:=a_{0}, & h_{1}:=a_{1} a_{0}+1, & \forall n \in \mathbb{N}: & h_{n+2}:=a_{n+2} h_{n+1}+h_{n} \\
k_{0}:=1, & k_{1}:=a_{1}, & \forall n \in \mathbb{N}: & k_{n+2}:=a_{n+2} k_{n+1}+k_{n} . \tag{3.4}
\end{array}
$$

By induction, $k_{n+2}>k_{n+1}$ for all $n \in \mathbb{N}$; in particular, it is clear that $k_{n} \rightarrow \infty$ as $n \rightarrow \infty$. Using Khinchin [8, §2] we infer that

$$
\begin{equation*}
\forall n \in \mathbb{N}: \quad \frac{h_{n}}{k_{n}}=\left[a_{0} ; a_{1}, \ldots, a_{n}\right] ; \tag{3.5}
\end{equation*}
$$

in other words, each convergent is a finite continued fraction (3.2) obtained by truncating the infinite continued fraction (3.1). The following bounds are known (see [8, Thms. 9 and 13]):

$$
\begin{equation*}
\frac{1}{k_{n}\left(k_{n}+k_{n+1}\right)}<\left|\alpha-\frac{h_{n}}{k_{n}}\right|<\frac{1}{k_{n} k_{n+1}} ; \tag{3.6}
\end{equation*}
$$

in particular, from (3.6) we deduce that

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \frac{h_{n}}{k_{n}}=\alpha \tag{3.7}
\end{equation*}
$$

The next result is also well known; see [8, Thm. 19].

Lemma 3.1. If $\alpha \in \mathbb{R} \backslash \mathbb{Q}$, and the inequality

$$
\left|\alpha-\frac{p}{q}\right|<\frac{1}{2 q^{2}}
$$

holds with some integers $p$ and $q>0$, then $p / q$ is one of the convergents of $\alpha$. In particular, the inequality $q \llbracket q \alpha \rrbracket<\frac{1}{2}$ implies that $q=k_{n}$ for some $n \in \mathbb{N}$.
3.2. A characterization of type. The next lemma plays a crucial role in this paper, for it shows that the type $\tau(\alpha)$ of an irrational number $\alpha$ is determined by the sequence of denominators $\left(k_{n}\right)$ of the convergents of $\alpha$. The origin of this result is unclear, however, the statement and sketch of the proof appear in a 2004 preprint of Sondow; see Sondow [14, Thm. 1]. For the convenience of the reader, we include a full proof here.

Lemma 3.2. In the notation of §3.1, for every $\alpha \in \mathbb{R} \backslash \mathbb{Q}$ we have

$$
\begin{equation*}
\tau(\alpha)=\varlimsup_{n \rightarrow \infty} \frac{\log k_{n+1}}{\log k_{n}} \tag{3.8}
\end{equation*}
$$

Proof. By (1.1) and the Dirichlet approximation theorem, we have $\tau(\alpha)=\sup \mathcal{T}(\alpha)$, where $\mathcal{T}(\alpha)$ is the set of real numbers defined by

$$
\mathcal{T}(\alpha):=\left\{\theta \geqslant 1: \varliminf_{q \in \mathbb{N}} q^{\theta} \llbracket q \alpha \rrbracket=0\right\} .
$$

We define

$$
\begin{equation*}
\forall n \geqslant 2: \quad \theta_{n}:=\frac{\log k_{n+1}}{\log k_{n}}, \quad \text { and } \quad \Theta:=\varlimsup_{n \rightarrow \infty} \theta_{n} \tag{3.9}
\end{equation*}
$$

To prove the lemma, we show that $\Theta=\sup \mathcal{T}(\alpha)$.
For any $n \geqslant 2$, we have $k_{n+1}=k_{n}^{\theta_{n}}$, hence from (3.6) it follows that

$$
\frac{1}{2} k_{n}^{-\theta_{n}}<\left|k_{n} \alpha-h_{n}\right|<k_{n}^{-\theta_{n}} .
$$

Note that $\left|k_{n} \alpha-h_{n}\right|<\frac{1}{2}$ since $k_{n} \geqslant 2$ and $\theta_{n}>1$, hence $\left|k_{n} \alpha-h_{n}\right|=\llbracket k_{n} \alpha \rrbracket$; this shows that

$$
\begin{equation*}
\forall n \geqslant 2: \quad \frac{1}{2}<k_{n}^{\theta_{n}} \llbracket k_{n} \alpha \rrbracket<1 \tag{3.10}
\end{equation*}
$$

By (3.9), for any $\varepsilon>0$ there are infinitely many $n \in \mathbb{N}$ such that $\theta_{n}>\Theta-\varepsilon$. For any such $n$, using the upper bound in (3.10) we have

$$
k_{n}^{\Theta-2 \varepsilon} \llbracket k_{n} \alpha \rrbracket<k_{n}^{\theta_{n}-\varepsilon} \llbracket k_{n} \alpha \rrbracket<k_{n}^{-\varepsilon} .
$$

Consequently,

$$
\varliminf_{q \in \mathbb{N}} q^{\Theta-2 \varepsilon} \llbracket q \alpha \rrbracket=0,
$$

and so $\Theta-2 \varepsilon \in \mathcal{T}(\alpha)$. Since $\varepsilon>0$ is arbitrary, we get that $\Theta \leqslant \sup \mathcal{T}(\alpha)$.
To finish the proof, we need to show that sup $\mathcal{T}(\alpha) \leqslant \Theta$. Since $\Theta \geqslant 1$ (because $\theta_{n}>1$ for all $n$ ), there is nothing more to do in the case that $\sup \mathcal{T}(\alpha)=1$.

From now on, suppose that $\sup \mathcal{T}(\alpha)>1$. Let $\theta \in \mathcal{T}(\alpha)$ with $\theta>1$. Since

$$
\varliminf_{q \in \mathbb{N}} q^{\theta} \llbracket q \alpha \rrbracket=0
$$

we have $q^{\theta} \llbracket q \alpha \rrbracket<\frac{1}{2}$ for infinitely many $q \in \mathbb{N}$. By Lemma 3.1, any such $q$ has the form $q=k_{n}$ for some $n$, and thus

$$
k_{n}^{\theta} \llbracket k_{n} \alpha \rrbracket<\frac{1}{2}
$$

for infinitely many $n$. Now (3.10) implies that $\theta<\theta_{n}$ for infinitely many $n$. By (3.9), one has $\theta_{n}<\Theta+\varepsilon$ for all sufficiently large $n$; therefore, $\theta<\Theta+\varepsilon$. Since this is true for any $\theta \in \mathcal{T}(\alpha)$ with $\theta>1$, it follows that $\sup \mathcal{T}(\alpha) \leqslant \Theta+\varepsilon$. Finally, as $\varepsilon>0$ is arbitrary, we get that $\sup \mathcal{T}(\alpha) \leqslant \Theta$ as required.
3.3. Preservation of type under the action of $\mathrm{GL}_{2}(\mathbb{Q})$. Let

$$
\begin{equation*}
\mathcal{T}(\alpha):=\left\{\theta \geqslant 1: \varliminf_{q \in \mathbb{N}} q^{\theta} \llbracket q \alpha \rrbracket=0\right\} \tag{3.11}
\end{equation*}
$$

as in the proof of Lemma 3.2. Then $\tau(\alpha)=\sup \mathcal{T}(\alpha)$ for each $\alpha \in \mathbb{R} \backslash \mathbb{Q}$. The following lemma gives some invariance properties of the set $\mathcal{T}(\alpha)$.

Lemma 3.3. For any irrational number $\alpha$, we have
(i) $\mathcal{T}(-\alpha)=\mathcal{T}(\alpha)$;
(ii) $\mathcal{T}(r \alpha)=\mathcal{T}(\alpha)$ for all $r \in \mathbb{Q}_{+}^{\times}:=\mathbb{Q} \cap(0, \infty)$;
(iii) $\mathcal{T}(\alpha+1)=\mathcal{T}(\alpha)$;
(iv) $\mathcal{T}\left(\alpha^{-1}\right)=\mathcal{T}(\alpha)$.

Proof. Properties (i) and (iii) follow simply from (3.11) since $\llbracket q \alpha \rrbracket=\llbracket-q \alpha \rrbracket$ and $\llbracket q \alpha \rrbracket=\llbracket q(\alpha+1) \rrbracket$ for all $q \in \mathbb{Z}$.

To prove property (ii), it suffices to show that

$$
\begin{equation*}
\forall \alpha \in \mathbb{R} \backslash \mathbb{Q}, \forall r \in \mathbb{Q}_{+}^{\times}: \quad \mathcal{T}(\alpha) \subset \mathcal{T}(r \alpha), \tag{3.12}
\end{equation*}
$$

since (3.12) implies the opposite inclusion

$$
\forall \alpha \in \mathbb{R} \backslash \mathbb{Q}, \forall r \in \mathbb{Q}_{+}^{\times}: \quad \mathcal{T}(r \alpha) \subset \mathcal{T}\left(r^{-1} \cdot r \alpha\right)=\mathcal{T}(\alpha) .
$$

To prove (3.12), let $\theta \geqslant 1$ be an arbitrary element of $\mathcal{T}(\alpha)$, and write $r=u / v$ with some integers $u, v \in \mathbb{N}_{1}$. For any given $\varepsilon>0$, let $\delta \in\left(0, \frac{1}{2}\right)$ be such that $u v^{\theta} \delta<\varepsilon$. Since $\theta \in \mathcal{T}(\alpha)$, the inequality $q^{\theta} \llbracket q \alpha \rrbracket<\delta$ holds for infinitely many $q \in \mathbb{N}_{1}$. For any such $q$, there is an integer $p$ (the one closest to $q \alpha$ ) for which

$$
q^{\theta}|q \alpha-p|<\delta .
$$

Multiplying both sides of the inequality by $r v^{\theta+1}=u v^{\theta}$, we get

$$
(v q)^{\theta}|v q r \alpha-u p|<u v^{\theta} \delta \quad \Longrightarrow \quad(v q)^{\theta} \llbracket v q(r \alpha) \rrbracket<\varepsilon .
$$

Since this holds for infinitely many $q \in \mathbb{N}_{1}$, it is clear that $\theta$ belongs to $\mathcal{T}(r \alpha)$, and (ii) is proved.

To prove property (iv), it is enough to show

$$
\begin{equation*}
\forall \alpha \in \mathbb{R} \backslash \mathbb{Q}: \quad \mathcal{T}(\alpha) \subset \mathcal{T}\left(\alpha^{-1}\right) . \tag{3.13}
\end{equation*}
$$

Fix $\alpha \in \mathbb{R} \backslash \mathbb{Q}$. By $(i)$, we can assume $\alpha>0$. Let $\left(\frac{h_{0}}{k_{0}}, \frac{h_{1}}{k_{1}}, \frac{h_{2}}{k_{2}}, \ldots\right)$ be the sequence of convergents to $\alpha$, and note that every $h_{n}$ and $k_{n}$ is positive. Finally, let $\theta \geqslant 1$ be an arbitrary element of $\mathcal{T}(\alpha)$. For any given $\varepsilon>0$, let $\delta \in\left(0, \frac{1}{2}\right)$ be such that

$$
\forall n \in \mathbb{N}: \quad\left(\frac{h_{n}}{k_{n}}\right)^{\theta} \frac{\delta}{\alpha}<\varepsilon ;
$$

the existence of $\delta$ is a consequence of (3.7). Since $\theta \in \mathcal{T}(\alpha)$, we have $q^{\theta} \llbracket q \alpha \rrbracket<\delta$ for infinitely many $q \in \mathbb{N}_{1}$. For any such $q$, Lemma 3.1 shows that $q=k_{n}$ for some $n \in \mathbb{N}$. Moreover, as in the proof of Lemma 3.2, we have $\left|k_{n} \alpha-h_{n}\right|=\llbracket k_{n} \alpha \rrbracket$ for all large $n$. Therefore,

$$
k_{n}^{\theta}\left|k_{n} \alpha-h_{n}\right| \leqslant k_{n}^{\theta} \llbracket k_{n} \alpha \rrbracket<\delta,
$$

from which we deduce that

$$
h_{n}^{\theta} \llbracket h_{n} \alpha^{-1} \rrbracket \leqslant h_{n}^{\theta}\left|h_{n} \alpha^{-1}-k_{n}\right|=\frac{h_{n}^{\theta}}{\alpha k_{n}^{\theta}} \cdot k_{n}^{\theta}\left|k_{n} \alpha-h_{n}\right|<\left(\frac{h_{n}}{k_{n}}\right)^{\theta} \frac{\delta}{\alpha}<\varepsilon .
$$

Since $\varepsilon$ is arbitrary, and this holds for infinitely many $n$, it follows that $\theta$ belongs to $\mathcal{T}\left(\alpha^{-1}\right)$, completing the proof of (iv).

Proof of Theorem 1.1. Let $G:=G L_{2}(\mathbb{Q})$, and recall the action of $G$ on $\mathbb{R} \backslash \mathbb{Q}$ :

$$
g \alpha:=\frac{a \alpha+b}{c \alpha+d} \quad \text { for any } g=\left(\begin{array}{ll}
a & b \\
c & d
\end{array}\right) \in G \text { and } \alpha \in \mathbb{R} \backslash \mathbb{Q} .
$$

We need to show that $\tau(g \alpha)=\tau(\alpha)$ for all $\alpha \in \mathbb{R} \backslash \mathbb{Q}$ and $g \in G$.
Let $H$ be the subgroup of $G$ consisting of matrices $h$ such that $\mathcal{T}(h \alpha)=\mathcal{T}(\alpha)$ for all $\alpha \in \mathbb{R} \backslash \mathbb{Q}$. To prove the theorem, we must show that $H=G$. Note that the properties $(i),(i i),(i i i)$, and $(i v)$ in Lemma 3.3 imply that $H$ contains all of the matrices

$$
\left(\begin{array}{cc}
-1 & \\
& 1
\end{array}\right), \quad\left(\begin{array}{cc}
r & \\
& 1
\end{array}\right) \quad \text { for all } r \in \mathbb{Q}_{+}^{\times}, \quad\left(\begin{array}{ll}
1 & 1 \\
& 1
\end{array}\right), \quad \text { and } \quad w:=\left(\begin{array}{ll} 
& 1 \\
1 &
\end{array}\right) .
$$

Under the action of $G$ on $\mathbb{R} \backslash \mathbb{Q}$ by Möbius transformations, the center

$$
Z:=\left\{\left(\begin{array}{ll}
z & \\
& z
\end{array}\right): z \in \mathbb{Q} \backslash\{0\}\right\}
$$

acts trivially; hence $Z \subset H$. The set $T$ of diagonal matrices is also contained in $H$, since any diagonal matrix can be decomposed as

$$
\left(\begin{array}{ll}
a & \\
& b
\end{array}\right)=\left(\begin{array}{ll} 
\pm 1 & \\
& 1
\end{array}\right)\left(\begin{array}{ll}
|a / b| & \\
& 1
\end{array}\right)\left(\begin{array}{ll}
b & \\
& b
\end{array}\right)
$$

for some choice of sign. Next, taking into account that

$$
\forall x \in \mathbb{Q} \backslash\{0\}: \quad\left(\begin{array}{ll}
1 & x \\
& 1
\end{array}\right)=\left(\begin{array}{ll}
x & \\
& 1
\end{array}\right)\left(\begin{array}{ll}
1 & 1 \\
& 1
\end{array}\right)\left(\begin{array}{ll}
x^{-1} & \\
& 1
\end{array}\right),
$$

we see that the collection of unipotent matrices

$$
N:=\left\{\left(\begin{array}{ll}
1 & x \\
& 1
\end{array}\right): x \in \mathbb{Q}\right\}
$$

is contained in $H$. To summarize, we have seen that $w \in H, T \subset H$, and $N \subset H$. By the Bruhat decomposition (see, for example, Borel [1, §14.12]), we have $G=T N \cup T N w N$, and so we conclude that $H=G$.

First proof of Theorem 1.2. The map $\tau: \mathbb{R} \backslash \mathbb{Q} \rightarrow[1, \infty]$ is surjective. Indeed, for any given $\mathrm{t} \in[1, \infty]$, using I changed this because now we have $x<y$ when $(x, y)$ lies in $V$ the initial vertex $v:=(1,2)$ in Proposition 2.2 and its proof, we construct a sequence $a=\left(a_{n}\right)_{n \in \mathbb{N}}$ of positive integers and a trail

$$
\mathrm{T}=\operatorname{Tr}(v, a): \quad v \stackrel{a_{0}}{\rightsquigarrow} v_{0} \stackrel{a_{1}}{\rightsquigarrow} v_{1} \stackrel{a_{2}}{\rightsquigarrow} v_{2} \stackrel{a_{3}}{\rightsquigarrow} v_{3} \xrightarrow{a_{4}} \ldots
$$

that has an $\ell$-limit equal to t . Then $\alpha:=\left[a_{0} ; a_{1}, a_{2}, \ldots\right]$ is an irrational number for which $\tau(\alpha)=\ell(\mathrm{T})=\mathrm{t}$. This proves the surjectivity of the map $\tau$. Moreover, for any $x \in \mathbb{Q}$ we have $\tau(\alpha+x)=\tau(\alpha)=\mathrm{t}$ by Theorem 1.1, since

$$
\alpha+x=g \alpha \quad \text { with } \quad g:=\left(\begin{array}{cc}
1 & x \\
& 1
\end{array}\right) \in G .
$$

Therefore, $\alpha+\mathbb{Q} \subset \tau^{-1}(\{t\})$, which implies that $\tau^{-1}(\{t\})$ is dense in $\mathbb{R} \backslash \mathbb{Q}$.
3.4. Trails of an irrational number. For any $\alpha \in \mathbb{R} \backslash \mathbb{Q}$, let the sequences $\left(a_{n}\right)_{n \in \mathbb{N}}$ and $\left(k_{n}\right)_{n \in \mathbb{N}}$ be defined as in $\S 3.1$. Defining

$$
\forall n \in \mathbb{N}_{1}: \quad v_{n}:=\left(k_{n}, k_{n+1}\right),
$$

we obtain a sequence of vertices in the oriented graph $\mathcal{G}$ described in §2.1; in other words, $\left(v_{n}\right)_{n \in \mathbb{N}_{1}} \subset V$. Moreover, by (2.1) and the recursive definition (3.4), each pair of consecutive vertices is connected by a directed edge:

$$
\forall n \in \mathbb{N}_{1}: \quad v_{n} \stackrel{a_{n+2}}{\rightsquigarrow} v_{n+1} .
$$

In this way, we obtain an infinite trail

$$
\mathrm{T}_{\alpha}:=\operatorname{Tr}\left(v_{1},\left(a_{n}\right)_{n \geqslant 3}\right): \quad v_{1} \stackrel{a_{3}}{\rightsquigarrow} v_{2} \stackrel{a_{4}}{\rightsquigarrow} v_{3} \stackrel{a_{5}}{\rightsquigarrow} v_{4} \cdots
$$

of the type described in §2.1. Moreover, using Lemma 3.2 we have

$$
\bar{\ell}\left(\mathrm{T}_{\alpha}\right)=\varlimsup_{n \rightarrow \infty} \ell\left(v_{n}\right)=\varlimsup_{n \rightarrow \infty} \frac{\log k_{n+1}}{\log k_{n}}=\tau(\alpha) .
$$

To sum up, every irrational number $\alpha$ determines an infinite trail $\mathrm{T}_{\alpha}$ with an initial vertex $v_{1}=\left(a_{1}, a_{2} a_{1}+1\right)$ and an $\ell$-limsup $\bar{\ell}\left(\mathrm{T}_{\alpha}\right)=\tau(\alpha)$.

Conversely, for any trail $\mathrm{T}_{\alpha}$ as above, the sequences $\left(a_{n}\right)_{n \in \mathbb{N}}$ and $\left(k_{n}\right)_{n \in \mathbb{N}}$ are uniquely determined by the vertices $\left(v_{n}\right)_{n \in \mathbb{N}_{1}}$, except for $a_{0}$. Thus, the irrational number $\alpha$ is uniquely determined by its trail up to translation by an integer.
3.5. Heads or tails? Let $\alpha=\left[a_{0} ; a_{1}, a_{2}, \ldots\right] \in \mathbb{R} \backslash \mathbb{Q}$ be given. For every $n \in \mathbb{N}$, we define the $n$-th head of $\alpha$ to be the rational number

$$
\alpha_{\leqslant n}:=\left[a_{0} ; a_{1}, a_{2}, \ldots, a_{n}\right],
$$

which is just the $n$-th convergent $h_{n} / k_{n}$ to $\alpha$; see (3.5). Because $\alpha$ is the limit of its convergents (see (3.7)), the various heads of an irrational number determine its location in $\mathbb{R}$. We also have the following result.

Lemma 3.4. For any $\varepsilon>0$, there exists $n_{0}=n_{0}(\varepsilon)>0$ such that

$$
\forall \alpha, \beta \in \mathbb{R} \backslash \mathbb{Q}, \forall n \geqslant n_{0}: \quad \alpha_{\leqslant n}=\beta_{\leqslant n} \quad \Longrightarrow \quad|\alpha-\beta|<\varepsilon
$$

Also, for any $\alpha \in \mathbb{R} \backslash \mathbb{Q}$ and $n \in \mathbb{N}, n \geqslant 2$, there exists $\delta=\delta(\alpha, n)>0$ such that

$$
\forall \beta \in \mathbb{R} \backslash \mathbb{Q}: \quad|\alpha-\beta|<\delta \quad \Longrightarrow \quad \alpha_{\leqslant n}=\beta_{\leqslant n} .
$$

Proof. For any $\alpha, \beta \in \mathbb{R} \backslash \mathbb{Q}$, if $\alpha_{\leqslant n}=h_{n} / k_{n}=\beta_{\leqslant n}$, then by the triangle inequality and (3.6) one has

$$
|\alpha-\beta| \leqslant\left|\alpha-\frac{h_{n}}{k_{n}}\right|+\left|\beta-\frac{h_{n}}{k_{n}}\right|<\frac{2}{k_{n} k_{n+1}} .
$$

On the other hand, by (3.4), the lower bound $k_{n} \geqslant n-1$ holds for all $n \in \mathbb{N}$ regardless of the values of $\alpha$ and $\beta$. This implies the first statement of the lemma.

Our proof of the second statement uses ideas from the proof of [8, Thm. 18]. Given $\alpha \in \mathbb{R} \backslash \mathbb{Q}$ and $n \in \mathbb{N}, n \geqslant 2$, the number $\alpha$ lies strictly between the consecutive convergents $\alpha_{\leqslant n}=h_{n} / k_{n}$ and $\alpha_{\leqslant n+1}=h_{n+1} / k_{n+1}$. Let $\delta>0$ be small enough so that

$$
\delta<\min \left\{\left|\alpha-\frac{h_{n}}{k_{n}}\right|,\left|\alpha-\frac{h_{n+1}}{k_{n+1}}\right|\right\} .
$$

For any $\beta \in \mathbb{R} \backslash \mathbb{Q}$ for which $|\alpha-\beta|<\delta$, the number $\alpha$ lies closer to $\beta$ than it does to either of its convergents $h_{n} / k_{n}$ or $h_{n+1} / k_{n+1}$; therefore $\beta$ lies strictly between $h_{n} / k_{n}$ and $h_{n+1} / k_{n+1}$. Consequently,

$$
\left|\beta-\frac{h_{n}}{k_{n}}\right|+\left|\beta-\frac{h_{n+1}}{k_{n+1}}\right|=\left|\frac{h_{n}}{k_{n}}-\frac{h_{n+1}}{k_{n+1}}\right|=\frac{1}{k_{n} k_{n+1}}<\frac{1}{2 k_{n}^{2}}+\frac{1}{2 k_{n+1}^{2}},
$$

where we used the corollary to [8, Thm. 2] to derive second equality, and we used the arithmetic-geometric mean inequality in the last step. Hence, either

$$
\left|\beta-\frac{h_{n}}{k_{n}}\right|<\frac{1}{2 k_{n}^{2}} \quad \text { or } \quad\left|\beta-\frac{h_{n+1}}{k_{n+1}}\right|<\frac{1}{2 k_{n+1}^{2}} .
$$

Lemma 3.1 now shows that $h_{n} / k_{n}$ or $h_{n+1} / k_{n+1}$ is one of the convergents of $\beta$, and in either case we have $\alpha_{\leqslant n}=\beta_{\leqslant n}$.

Proposition 3.5. The map $\phi: \mathbb{R} \backslash \mathbb{Q} \rightarrow \mathbb{Z} \times \mathbb{N}_{1}^{\omega}$ given by

$$
\alpha=\left[a_{0} ; a_{1}, a_{2}, \ldots\right] \mapsto \phi(\alpha):=\left(a_{n}\right)_{n \in \mathbb{N}}
$$

is a homeomorphism. The inverse of $\phi$ is the map $\psi: \mathbb{Z} \times \mathbb{N}_{1}^{\omega} \rightarrow \mathbb{R} \backslash \mathbb{Q}$ given by

$$
a \mapsto \psi(a):=\lim _{n \rightarrow \infty} \frac{h_{n}}{k_{n}},
$$

where for any given sequence $a=\left(a_{n}\right)$ one uses (3.3) and (3.4) to define the corresponding sequence of convergents $\left(h_{n} / k_{n}\right)_{n \in \mathbb{N}}$.

Proof. Since

$$
\alpha_{\leqslant n}=\left[a_{0} ; a_{1}, a_{2}, \ldots, a_{n}\right]=\frac{h_{n}}{k_{n}},
$$

for all $n \in \mathbb{N}$, one sees that $\phi$ and $\psi$ are inverse maps.
To show that $\phi$ is continuous, it is enough to show that $\phi^{-1}(\mathcal{A})$ is open for every basic open set of the form

$$
\begin{equation*}
\mathcal{A}:=\left\{\left(a_{0}, a_{1}, \ldots, a_{n}\right)\right\} \times \mathbb{N}_{1}^{\omega}, \tag{3.14}
\end{equation*}
$$

where $n \geqslant 2$ and $\left(a_{0}, a_{1}, \ldots, a_{n}\right) \in \mathbb{Z} \times \mathbb{N}_{1}^{n}$. Writing $H:=\left[a_{0} ; a_{1}, \ldots, a_{n}\right]$, the set $\phi^{-1}(\mathcal{A})$ consists of those irrational numbers $\alpha$ for which $\alpha_{\leqslant n}=H$. For any fixed
$\alpha \in \phi^{-1}(\mathcal{A})$, let $\delta=\delta(\alpha, n)>0$ have the property stated in Lemma 3.4. The set

$$
\mathcal{B}:=\{\beta \in \mathbb{R} \backslash \mathbb{Q}:|\alpha-\beta|<\delta\}
$$

is open in $\mathbb{R} \backslash \mathbb{Q}$ and contains $\alpha$, and by Lemma $3.4, \beta_{\leqslant n}=\alpha_{\leqslant n}$ for every $\beta \in \mathcal{B}$, i.e., $\beta_{\leqslant n}=H$ for every $\beta \in \mathcal{B}$. This shows that $\mathcal{B} \subset \phi^{-1}(\mathcal{A})$, and we deduce that $\phi^{-1}(\mathcal{A})$ is open.

Next, we show that $\psi$ is continuous. For this, it suffices to show that $\psi^{-1}(\mathcal{B})$ is open for every basic open set of the form

$$
\mathcal{B}:=(\mathbb{R} \backslash \mathbb{Q}) \cap \mathcal{I},
$$

where $\mathcal{I} \subset \mathbb{R}$ is an open interval. For any fixed $a \in \psi^{-1}(\mathcal{B})$, put $\alpha:=\psi(a)$, which belongs to $\mathcal{B}$. Let $\varepsilon>0$ be small enough so that every $\beta \in \mathbb{R} \backslash \mathbb{Q}$ satisfying $|\alpha-\beta|<\varepsilon$ in contained in $\mathcal{B}$. Let $n_{0}=n_{0}(\varepsilon)>0$ have the property stated in Lemma 3.4. Finally, let $n \geqslant n_{0}$, put $H:=\alpha_{\leqslant n}=\left[a_{0} ; a_{1}, \ldots, a_{n}\right]$, and define $\mathcal{A}$ as in (3.14). Then for every $a \in \mathcal{A}$ we have

$$
\psi(a)_{\leqslant n}=H=\alpha_{\leqslant n} \quad \Longrightarrow \quad|\alpha-\psi(a)|<\varepsilon \quad \Longrightarrow \quad \psi(a) \in \mathcal{B},
$$

and thus $\mathcal{A} \subset \psi^{-1}(\mathcal{B})$. We conclude that $\psi^{-1}(\mathcal{B})$ is open.

Next, for every $n \in \mathbb{N}$, let $\alpha_{\geqslant n} \in \mathbb{R} \backslash \mathbb{Q}$ be the $n$-th tail of $\alpha$ :

$$
\alpha_{\geqslant n}:=\left[a_{n} ; a_{n+1}, a_{n+2}, \ldots\right],
$$

which is also an irrational number. Our next result shows that the type of $\alpha$ is determined by any one of its tails.

Theorem 3.6. We have $\tau\left(\alpha_{\geqslant n}\right)=\tau(\alpha)$ for all $\alpha \in \mathbb{R} \backslash \mathbb{Q}$ and $n \in \mathbb{N}$.
Proof. For every $\alpha \in \mathbb{R} \backslash \mathbb{Q}$ we have

$$
\alpha_{\geqslant 0}=\alpha \quad \text { and } \quad \forall n \in \mathbb{N}: \quad \alpha_{\geqslant n+1}=\left(\alpha_{\geqslant n}\right)_{\geqslant 1} .
$$

Hence, if we demonstrate that

$$
\begin{equation*}
\forall \alpha \in \mathbb{R} \backslash \mathbb{Q}: \quad \tau(\alpha \geqslant 1)=\tau(\alpha), \tag{3.15}
\end{equation*}
$$

then the general result follows via an inductive argument.
To prove (3.15), observe that

$$
\alpha=a_{0}+\frac{1}{a_{1}+\frac{1}{a_{2}+\cdots}}=a_{0}+\frac{1}{\alpha_{\geqslant 1}},
$$

and therefore (as in (1.3)) we have

$$
\alpha_{\geqslant 1}=\frac{1}{\alpha-a_{0}}=g \alpha \quad \text { with } \quad g:=\left(\begin{array}{cc}
1 \\
1 & -a_{0}
\end{array}\right) \in G L_{2}(\mathbb{Q}) .
$$

Now the relation (3.15) follows immediately from Theorem 1.1.
Corollary 3.7. If $\alpha, \beta \in \mathbb{R} \backslash \mathbb{Q}$ and $\alpha_{\geqslant m}=\beta_{\geqslant n}$ for some $m, n \in \mathbb{N}$, then $\alpha$ and $\beta$ have the same type.

Remark. An old result of Serret (see Perron [12, Satz 23]) asserts that two irrational numbers $\alpha$ and $\beta$ are equivalent under the action of $G L_{2}(\mathbb{Z})$ (by Möbius transformations) if and only if $\alpha_{\geqslant m}=\beta_{\geqslant n}$ for some $m, n \in \mathbb{N}$. Using this result, one can simplify some of the arguments above. For example, since $\alpha_{\geqslant n}$ and $\alpha$ are equivalent under $G L_{2}(\mathbb{Z})$, Theorem 3.6 can be proved by combining Serret's result with Theorem 1.1, along with the observation that the scalar matrices in $G L_{2}(\mathbb{Q})$ act trivially.

Remark. In descriptive set theory, for every set $\Omega$ there is an important relation $E_{t}(\Omega)$ known as the tail equivalence relation (see, e.g., Dougherty et al $\left.[3, \S 2]\right)$, which is defined on the collection of sequences $\Omega^{\omega}$ by

$$
x E_{t}(\Omega) y \quad \Longleftrightarrow \quad \exists m, n \in \mathbb{N}, \forall k \in \mathbb{N}: \quad x(m+k)=y(n+k)
$$

In terms of this relation, Proposition 3.5 and Corollary 3.7 together show that if $a_{0}, b_{0} \in \mathbb{Z}$ and $\left(a_{n+1}\right)_{n \in \mathbb{N}} E_{t}\left(\mathbb{N}_{1}\right)\left(b_{n+1}\right)_{n \in \mathbb{N}}$, then $\psi\left(\left(a_{n}\right)_{n \in \mathbb{N}}\right)$ and $\psi\left(\left(b_{n}\right)_{n \in \mathbb{N}}\right)$ have the same type.

Second proof of Theorem 1.2. We have already seen that the map $\tau$ is surjective. Given $\mathrm{t} \in[1, \infty]$, let $\alpha \in \mathbb{R} \backslash \mathbb{Q}$ be such that $\tau(\alpha)=\mathrm{t}$.

Now, let $\beta \in \mathbb{R} \backslash \mathbb{Q}$ be arbitrary. For every $n \in \mathbb{N}$, let $\gamma_{n}$ be the irrational number whose head is $\beta_{\leqslant n}$ and whose tail is $\alpha_{\geqslant n+1}$, i.e.,

$$
\gamma_{n}:=\left[b_{0} ; b_{1}, \ldots, b_{n}, a_{n+1}, a_{n+1}, \ldots\right] .
$$

Since $\left(\gamma_{n}\right)_{\leqslant n}=\beta_{\leqslant n}$ for each $n$, Lemma 3.4 implies that $\gamma_{n} \rightarrow \beta$ as $n \rightarrow \infty$. On the other hand, since $\left(\gamma_{n}\right)_{\geqslant n+1}=\alpha \geqslant n+1$ for each $n$, Corollary 3.7 shows that $\tau\left(\gamma_{n}\right)=\tau(\alpha)=\mathrm{t}$; thus, every number $\gamma_{n}$ lies in $\tau^{-1}(\{\mathrm{t}\})$.

## 4. Examples of complete sets

Our proof of Theorem 1.3 (see $\S 6$ below) ultimately relies on the fact that

$$
\mathcal{N}_{\infty}:=\left\{\beta \in \mathbb{N}_{1}^{\omega}: \lim _{n \rightarrow \infty} \beta(n)=\infty\right\}
$$

is a complete $\Pi_{3}^{0}$, a result that is well-known in descriptive set theory. For the convenience of the reader, we include a proof here, which borrows extensively from the material presented in Kechris [6, §23.A].
Lemma 4.1. Let $2^{\omega}$ be the Cantor space of infinite binary sequences. The set

$$
\mathcal{L}:=\left\{f \in 2^{\omega}: f(n)=0 \text { for all but finitely many } n \in \mathbb{N}\right\} .
$$

is a complete $\boldsymbol{\Sigma}_{2}^{0}$.
Proof. For each $n \in \mathbb{N}$, the set $U_{n}:=\left\{f \in 2^{\omega}: f(n)=0\right\}$ is clopen (closed and open), and therefore

$$
\mathcal{L}=\bigcup_{n_{0} \in \mathbb{N}} \bigcap_{n \geqslant n_{0}} U_{n}
$$

is a $\boldsymbol{\Sigma}_{2}^{0}$ subset of the Polish space $2^{\omega}$. On the other hand, as both $\mathcal{L}$ and $2^{\omega} \backslash \mathcal{L}$ are dense in $2^{\omega}$, the set $\mathcal{L}$ cannot be a $G_{\delta}$ by Baire's theorem (see [6, Thm. 8.4]); in other words, $\mathcal{L} \notin \boldsymbol{\Pi}_{2}^{0}$. Now Wadge's theorem (see [6, Thm. 22.10]) shows that $\mathcal{L}$ is a complete $\boldsymbol{\Sigma}_{2}^{0}$.

Lemma 4.2. Let $2^{\omega \times \omega}$ be the space of infinite binary matrices, and let $\mathcal{M}$ be the subset consisting of infinite binary matrices whose columns each have at most finitely many 1's. Then $\mathcal{M}$ is a complete $\boldsymbol{\Pi}_{3}^{0}$.

Proof. For fixed $m, n \in \mathbb{N}$, the set $U_{m, n}:=\left\{f \in 2^{\omega \times \omega}: f(m, n)=0\right\}$ is clopen, and thus

$$
\mathcal{M}=\bigcap_{m \in \mathbb{N}} \bigcup_{n_{0} \in \mathbb{N}} \bigcap_{n \geqslant n_{0}} U_{m, n}
$$

is a $\Pi_{3}^{0}$ subset of the Polish space $2^{\omega \times \omega}$.
Now let $\mathcal{X}$ be an arbitrary zero-dimensional Polish space. For any $\mathcal{A} \in \Pi_{3}^{0}(\mathcal{X})$, there is a family $\left(\mathcal{A}_{m}\right)_{m \in \mathbb{N}}$ of $\Sigma_{2}^{0}$ subsets of $\mathcal{X}$ such that $\mathcal{A}=\bigcap_{m \in \mathbb{N}} \mathcal{A}_{m}$. Since each $\mathcal{A}_{m} \leqslant_{W} \mathcal{L}$ by Lemma 4.1, there is a continuous map $g_{m}: \mathcal{X} \rightarrow 2^{\omega}$ for which $\mathcal{A}_{m}=g_{m}^{-1}(\mathcal{L})$. We define $g: \mathcal{X} \rightarrow 2^{\omega \times \omega}$ by

$$
\forall x \in \mathcal{X}, \forall m, n \in \mathbb{N}: \quad g(x)(m, n):=g_{m}(x)(n)
$$

Then $g$ is continuous, and

$$
x \in \mathcal{A}=\bigcap_{m \in \mathbb{N}} g_{m}^{-1}(\mathcal{L}) \quad \Longleftrightarrow \quad \forall m \in \mathbb{N}: \quad g_{m}(x) \in \mathcal{L} \quad \Longleftrightarrow \quad g(x) \in \mathcal{M}
$$

Thus we have $\mathcal{A} \leqslant_{W} \mathcal{M}$ as required.
LEmma 4.3. The set $\mathcal{N}_{\infty}:=\left\{\beta \in \mathbb{N}_{1}^{\omega}: \lim _{n \rightarrow \infty} \beta(n)=\infty\right\}$ is a complete $\boldsymbol{\Pi}_{3}^{0}$.
Proof. For any $k \in \mathbb{N}$ the set $U_{k}:=\left\{\beta \in \mathbb{N}_{1}^{\omega} \mid \beta(n) \geqslant k\right\}$ is clopen, and therefore

$$
\mathcal{N}_{\infty}=\bigcap_{k \in \mathbb{N}} \bigcup_{n_{0} \in \mathbb{N}} \bigcap_{n \geqslant n_{0}} U_{k}
$$

is a $\Pi_{3}^{0}$ subset of the Polish space $\mathbb{N}_{1}^{\omega}$.
Fix a bijection $\langle\cdot, \cdot\rangle: \mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$ with the property that $\langle m, n\rangle \geqslant m$ for all $m, n \in \mathbb{N}$ (for instance, one can take $\langle m, n\rangle:=2^{n}(2 m+1)-1$ ). We define a map $f: 2^{\omega \times \omega} \rightarrow \mathbb{N}^{\omega}$ by

$$
\forall \alpha \in 2^{\omega \times \omega}, \forall k \in \mathbb{N}: \quad f(\alpha)(k):= \begin{cases}k & \text { if } k=\langle m, n\rangle \text { and } \alpha(m, n)=0 \\ m & \text { if } k=\langle m, n\rangle \text { and } \alpha(m, n)=1\end{cases}
$$

Then $f$ is continuous, and $\mathcal{M}=f^{-1}\left(\mathcal{N}_{\infty}\right)$.
Now let $\mathcal{X}$ be an arbitrary zero-dimensional Polish space. For any $\mathcal{A} \in \Pi_{3}^{0}(\mathcal{X})$, Lemma 4.2 shows the existence of a continuous map $g: \mathcal{X} \rightarrow 2^{\omega \times \omega}$ such that $\mathcal{A}=g^{-1}(\mathcal{M})$. Then $f \circ g: \mathcal{X} \rightarrow \mathbb{N}^{\omega}$ is continuous, and $\mathcal{A}=(f \circ g)^{-1}\left(\mathcal{N}_{\infty}\right)$. Thus we have $\mathcal{A} \leqslant{ }_{W} \mathcal{N}_{\infty}$.

## 5. Complete functions

The aim of this section is to prove Theorem 1.4.
5.1. Background on trees. Let $A$ be a nonempty set. Following [6, 2.A], for each $n \in \mathbb{N}$ we denote by $A^{n}$ the set of finite sequences $s=\left(s_{0}, \ldots, s_{n-1}\right)$ of length $\operatorname{len}(s)=n$. In particular, $A^{0}=\{\varnothing\}$, where $\varnothing$ is the empty sequence. The set $A^{\omega}$ consists of infinite (countable) sequences $s=\left(s_{0}, s_{1} \ldots\right)$ of length $\operatorname{len}(s)=\infty$. We put

$$
A^{<\omega}:=\bigcup_{n \in \mathbb{N}} A^{n} \quad \text { and } \quad A^{\leqslant \omega}:=A^{<\omega} \cup A^{\omega}
$$

Given $s \in A^{\leqslant \omega}$ and $n \leqslant \operatorname{len}(s)$ we denote $\left.s\right|_{n}:=\left(s_{0}, \ldots, s_{n-1}\right)$, where formally we have $\left.s\right|_{0}=\varnothing$, and $\left.s\right|_{\infty}=s$ in the case that $s \in A^{\omega}$. If $s \in A^{<\omega}$ and $t \in A^{\leqslant \omega}$, we say that $s$ is an initial segment of $t$ and that $t$ is an extension of $s$ (and we write $s \subseteq t$ ) if $s=\left.t\right|_{n}$ with $n=\operatorname{len}(s)$.

A tree on $A$ is a subset $T \subset A^{<\omega}$ that is closed under initial segments, i.e., for any given $t \in T$, every initial segment $s$ of $t$ is also contained in $T$. The body of a tree $T$ is the set

$$
[T]:=\left\{x \in A^{\omega}:\left.x\right|_{n} \in T \text { for all } n \in \mathbb{N}\right\}
$$

A tree $T$ is said to be pruned if every element of $T$ has a proper extension in $T$; equivalently, every element of $T$ is an initial segment of some element of $[T]$.

For any sequence $s \in A^{<\omega}$ we denote

$$
N_{s}:=\left\{x \in A^{\omega}: s \subseteq x\right\}
$$

Then $N_{s}$ is the basic clopen neighborhood of $A^{\omega}$ associated with $s$. If $T$ is a tree on $A$ and $s \in T$, then we denote

$$
T_{s}:=\{t \in T: s \subseteq t \text { or } t \subseteq s\} .
$$

5.2. A key lemma. To establish the universality of the type function, we use a generalization of the Lemma 2.1, the crucial "targeting lemma." Recall that

$$
V:=\left\{(x, y) \in \mathbb{N}_{1}^{2}: x<y\right\}
$$

Let $\mathfrak{B}$ be a fixed subset of

$$
W:=\left\{\left(\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)\right) \in V^{2}: x_{2}=y_{1}\right\},
$$

and put

$$
P=P_{\mathfrak{B}}:=\left\{\left(v_{n}\right)_{n \in \mathbb{N}_{1}} \in V^{\omega}:\left(v_{n}, v_{n+1}\right) \in \mathfrak{B} \text { for all } n \in \mathbb{N}_{1}\right\} .
$$

By [6, Proposition 2.4], since $P$ is a closed subset of $V^{\omega}$, there exists a pruned tree $T$ on $V$ with the property that $P=[T]$; the tree is given by

$$
T=T_{\mathfrak{B}}:=\bigcup_{n \in \mathbb{N}}\left\{\left(v_{1}, \cdots, v_{n}\right) \in V^{n}:\left(v_{m}, v_{m+1}\right) \in \mathfrak{B} \text { for } 1 \leqslant m<n\right\} .
$$

For considerations of density, for each $s \in T$ we use the notation $T_{s}$ defined above, and we write $P_{s}:=P \cap N_{s}=\left[T_{s}\right]$.

Definition. For fixed $\mathfrak{B}$ as above and $\mathfrak{b} \in \mathbb{R} \cup\{-\infty\}$, we say that a map $\mathfrak{L}: V \rightarrow[\mathfrak{b}, \infty)$ is $(\mathfrak{B}, \mathfrak{b})$-target-controlled if it has the following property. For any $\varepsilon \in(0,1)$, there is a positive integer $M=M_{\mathfrak{B}, \mathfrak{b}}(\varepsilon)$ such that for every $\mathrm{t} \in[\mathfrak{b}, \infty) \cap \mathbb{R}$ and $v=(x, y) \in V$ with $y>M$, there exists a vertex $w \in V$ for which $(v, w) \in \mathfrak{B}$ and $\mathfrak{L}(w) \in[\mathrm{t}, \mathrm{t}+\varepsilon)$.

The prototype for this definition is the specific function $\ell$ considered earlier in connection with the type function $\tau$; see (2.3) for the definition. In view of Lemma 2.1, the map $\ell$ is $(B, 1)$-target-controlled, where

$$
B:=\left\{\left(\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)\right) \in V^{2}: x_{2}=y_{1} \text { and } y_{2}=a y_{1}+x_{1} \text { for some } a \in \mathbb{N}_{1}\right\} .
$$

Note that, in this case, every integer larger than $(10 / \varepsilon)^{1 / \varepsilon}$ is an acceptable value of $M_{B, 1}(\varepsilon)$ for any $\varepsilon \in(0,1)$.

In the general case, where $\mathfrak{L}$ is an arbitrary $(\mathfrak{B}, \mathfrak{b})$-target-controlled map, we need the following key lemma. For any $n \in \mathbb{N}_{1}$, let $\varepsilon_{n}:=2^{-n}$, and let $M_{n}$ be an acceptable value of $M_{\mathfrak{B}, \mathfrak{b}}\left(\varepsilon_{n}\right)$. We can assume that the sequence $\left(M_{n}\right)_{n \in \mathbb{N}_{1}}$ is strictly increasing.

Lemma 5.1. Let $s \in T$ such that $s=\varnothing$ or $\operatorname{len}(s)>M_{1}$. For any function $u: T_{s} \rightarrow[\mathfrak{b}, \infty)$, there exists $v=\left(v_{n}\right)_{n \in \mathbb{N}_{1}} \in P_{s}$ such that

$$
\varlimsup_{m \in \mathbb{N}_{1}} u\left(\left.v\right|_{m}\right)=\varlimsup_{n \in \mathbb{N}_{1}} \mathfrak{L}\left(v_{n}\right)
$$

Proof. By induction on $n$, we construct $\mathrm{t}_{n} \in[\mathfrak{b}, \infty) \cap \mathbb{R}$ and $v_{n} \in V$ as follows.
Let $\mathrm{t}_{1} \in[\mathfrak{b}, \infty) \cap \mathbb{R}$ be arbitrary. Put $l_{1}:=\operatorname{len}(s)$. If $s=\varnothing$, then $l_{1}=0$ and we set $v_{0}:=\left(M_{1}, M_{1}+1\right)$. If $s \neq \varnothing$, then $l_{1}>M_{1}$, and writing $s=\left(s_{1}, \ldots, s_{l_{1}}\right)$ we put $v_{m}:=s_{m}$ for $1 \leqslant m \leqslant l_{1}$. In both cases, $v_{l_{1}}:=\left(x_{l_{1}}, y_{l_{1}}\right) \in V$ and we have $y_{l_{1}}>M_{1}$ (since $s \in T$ ).

Since $\mathfrak{L}$ is $(\mathfrak{B}, \mathfrak{b})$-target-controlled, there is a vertex $v_{l_{1}+1}=\left(x_{l_{1}+1}, y_{l_{1}+1}\right) \in V$ such that $\left(v_{l_{1}}, v_{l_{1}+1}\right) \in \mathfrak{B}$ and $\mathfrak{L}\left(v_{l_{1}+1}\right) \in\left[\mathrm{t}_{1}, \mathrm{t}_{1}+\varepsilon_{1}\right)$. Moreover,

$$
y_{l_{1}+1}>x_{l_{1}+1}=y_{l_{1}}>M_{1} .
$$

Iterating this process, for each $j \geqslant 1$ we obtain $v_{l_{1}+j}=\left(x_{l_{1}+j}, y_{l_{1}+j}\right) \in V$ such that $\left(v_{l_{1}+j-1}, v_{l_{1}+j}\right) \in \mathfrak{B}, \mathfrak{L}\left(v_{l_{1}+j}\right) \in\left[\mathrm{t}_{1}, \mathrm{t}_{1}+\varepsilon_{1}\right)$, and

$$
y_{l_{1}+j}>\cdots>y_{l_{1}+1}>y_{l_{1}}>M_{1}
$$

Then, for some sufficiently large $j$, we also have $y_{l_{1}+j}>M_{2}$. Let $l_{2}:=l_{1}+j$ for some such $j$, and put

$$
\mathrm{t}_{2}:= \begin{cases}\max _{l_{1}<m \leqslant l_{2}} u\left(\left(v_{1}, \ldots, v_{m}\right)\right) & \text { if this maximum lies in } \mathbb{R}, \\ -2 & \text { otherwise }\end{cases}
$$

Since $\mathfrak{L}$ is $(\mathfrak{B}, \mathfrak{b})$-target-controlled, there is a vertex $v_{l_{2}+1}=\left(x_{l_{2}+1}, y_{l_{2}+1}\right) \in V$ such that $\left(v_{l_{2}}, v_{l_{2}+1}\right) \in \mathfrak{B}$ and $\mathfrak{L}\left(v_{l_{2}+1}\right) \in\left[\mathrm{t}_{2}, \mathrm{t}_{2}+\varepsilon_{2}\right)$, and the above process can be repeated.

Continuing in this manner, we obtain sequences $l:=\left(l_{n}\right)_{n \in \mathbb{N}_{1}}, v:=\left(v_{n}\right)_{n \in \mathbb{N}_{1}}$, and $\mathrm{t}:=\left(\mathrm{t}_{n}\right)_{n \in \mathbb{N}_{1}}$ such that
(i) $l$ is strictly increasing, with $y_{l_{n}}>M_{n}$ for each $n \in \mathbb{N}_{1}$;
(ii) $v_{n} \in V$ and $\left(v_{n}, v_{n+1}\right) \in \mathfrak{B}$ for all $n \in \mathbb{N}_{1}$, hence $v \in P$;
(iii) t is a real sequence, with $\mathrm{t}_{n}$ for $n \geqslant 2$ defined by

$$
\mathrm{t}_{n}:= \begin{cases}\max _{l_{n-1}<m \leqslant l_{n}} u\left(\left.v\right|_{m}\right) & \text { if this maximum lies in } \mathbb{R}, \\ -n & \text { otherwise } .\end{cases}
$$

(iv) $\mathfrak{L}\left(v_{m}\right) \in\left[\mathrm{t}_{n}, \mathrm{t}_{n}+\varepsilon_{n}\right)$ for $l_{n}<m \leqslant l_{n+1}$.

For any integer $m>l_{1}$, by $(i)$ there is a unique $n \in \mathbb{N}_{1}$ with $l_{n}<m \leqslant l_{n+1}$, and so by (iii) and (iv) we have

$$
u\left(\left.v\right|_{m}\right) \leqslant \mathrm{t}_{n+1} \leqslant \mathfrak{L}\left(v_{l_{n+2}}\right)
$$

which implies that

$$
\varlimsup_{m \in \mathbb{N}_{1}} u\left(\left.v\right|_{m}\right) \leqslant \varlimsup_{n \in \mathbb{N}_{1}} \mathfrak{L}\left(v_{n}\right) .
$$

It remains to establish the inverse inequality

$$
\begin{equation*}
\varlimsup_{n \in \mathbb{N}_{1}} \mathfrak{L}\left(v_{n}\right) \leqslant \varlimsup_{k \in \mathbb{N}_{1}} u\left(\left.v\right|_{k}\right) . \tag{5.1}
\end{equation*}
$$

For this, we can clearly assume that

$$
\varlimsup_{n \in \mathbb{N}_{1}} \mathfrak{L}\left(v_{n}\right)=\lim _{j \in \mathbb{N}} \mathfrak{L}\left(v_{m_{j}}\right) \neq-\infty
$$

with some strictly increasing sequence $\left(m_{j}\right)_{j \in \mathbb{N}} \subset \mathbb{N}_{1}$. Fixing $\varepsilon>0, n \in \mathbb{N}_{1}$ with $\varepsilon_{n}<\varepsilon$, and $j$ such that $l_{n}<m_{j} \leqslant l_{n+1}$, we have

$$
\mathfrak{L}\left(v_{m_{j}}\right)<\mathrm{t}_{n}+\varepsilon_{n}=\varepsilon_{n}+ \begin{cases}\max _{l_{n-1}<k \leqslant l_{n}} u\left(\left.v\right|_{k}\right) & \text { if this maximum lies in } \mathbb{R}, \\ -n & \text { otherwise }\end{cases}
$$

Thus $\mathfrak{L}\left(v_{m_{j}}\right)<u\left(\left.v\right|_{k_{j}}\right)+\varepsilon$ holds with some $k_{j}$ in the range $l_{n-1}<k_{j} \leqslant l_{n}$. This shows that

$$
\varlimsup_{n \in \mathbb{N}_{1}} \mathfrak{L}\left(v_{n}\right) \leqslant \varlimsup_{k \in \mathbb{N}_{1}} u\left(\left.v\right|_{k}\right)+\varepsilon,
$$

and as $\varepsilon$ is arbitrary, we deduce (5.1). This completes the proof.
5.3. Background on games. Let $A$ be a nonempty set, $\mathcal{T}$ be a nonempty pruned tree on $A$, and $\mathcal{X} \subset[\mathcal{T}]$. We consider the game $G(\mathcal{T}, \mathcal{X})$ played as follows:

$$
\begin{array}{llllll}
\text { Player 1: } & a_{0} & & a_{2} & \cdots & \\
\text { Player 2: } & & a_{1} & & a_{3} & \cdots
\end{array}
$$

The two players take turns playing $a_{0}, a_{1}, a_{2}, \ldots \in A$ with the requirement that $\left(a_{0}, \ldots, a_{n}\right) \in \mathcal{T}$ for each $n$ (thus, $\mathcal{T}$ is understood to be the set of "rules" of the game). Player 1 wins if and only if the final sequence $\left(a_{n}\right)_{n \in \mathbb{N}}$ belongs to $\mathcal{X}$. A strategy for Player 1 is a map $\varphi: A^{<\omega} \rightarrow A$, with Player 1 playing $a_{0}=\varphi(\varnothing)$, followed by $a_{2}=\varphi\left(\left(a_{1}\right)\right), a_{4}=\varphi\left(\left(a_{1}, a_{3}\right)\right)$, etc., in response to Player 2 playing $a_{1}, a_{3}$, etc. The notion of a strategy for Player 2 is defined similarly. A strategy is called winning if the relevant player always wins the game while following her strategy. The game $G(\mathcal{T}, \mathcal{X})$ is determined if one of the two players has a winning strategy. We equip $A^{\omega}$ with the product topology of the discrete topology on $A$, and we equip $[\mathcal{T}]$ with the relative topology. By Martin's theorem, if $\mathcal{X}$ is a Borel subset of $[\mathcal{T}]$, then $G(\mathcal{T}, \mathcal{X})$ is determined (see [6, Theorem 20.5]).
5.4. The main theorem. We now come to the main result of the paper. As in $\S 5.2$, for a given subset $\mathfrak{B}$ of $W$, we define the trees $T=T_{\mathfrak{B}}$ and $P=P_{\mathfrak{B}}$, and we fix $\mathfrak{b} \in \mathbb{R} \cup\{-\infty\}$. In what follows, we suppose that $\mathfrak{L}: V \rightarrow[\mathfrak{b}, \infty)$ is a $(\mathfrak{B}, \mathfrak{b})$-target-controlled map.

Theorem 5.2. The map $f: P \rightarrow[\mathfrak{b}, \infty]$ defined by

$$
\begin{equation*}
f\left(\left(v_{n}\right)_{n \in \mathbb{N}_{1}}\right):=\varlimsup_{n \in \mathbb{N}_{1}} \mathfrak{L}\left(v_{n}\right) \tag{5.2}
\end{equation*}
$$

is densely onto and $[\mathfrak{b}, \infty]$-upper semi-Baire class 1 complete.
Proof. Let $\left(M_{n}\right)_{n \in \mathbb{N}_{1}}$ be defined as in $\S 5.2$. Let $s \in T$ of length $l_{1}:=\operatorname{len}(s)$, and assume that $l_{1}=0$ or $l_{1}>M_{1}$. Let $g: 2^{\omega} \rightarrow[\mathfrak{b}, \infty]$ be upper semi-Baire class 1. In the style of the proof of [13, Theorem 5.1], we consider the following game, which is of the type $G(\mathcal{T}, \mathcal{X})$ if we code both $2:=\{0,1\}$ and $V$ (which is countably infinite) as subsets of $A:=\mathbb{N}$ :

with each $x_{n} \in\{0,1\}$ and each $v_{n} \in V$; hence the game produces two sequences $x:=\left(x_{n}\right)_{n \in \mathbb{N}} \in 2^{\omega}$ and $v:=\left(v_{n}\right)_{n \in \mathbb{N}_{1}} \in V^{\omega}$. The only rule of the game is that each $\left.v\right|_{m}:=\left(v_{1}, \cdots, v_{m}\right)$ must lie in $T_{s}$. Player 1 wins the game if and only if $g(x) \neq f(v)$.

Since $f, g$ are Borel maps, the collection $\mathcal{X}$ of winning outcomes for Player 1 is Borel, so the game is determined by Martin's theorem. A winning strategy for Player 2 induces a continuous function $\phi: 2^{\omega} \rightarrow P_{s}$ such that $g=f \circ \phi$. Let us prove that Player 1 cannot have a winning strategy.

Suppose, on the contrary, that Player 1 has a winning strategy, i.e., that there is a continuous function $\psi: P_{s} \rightarrow 2^{\omega}$ such that $g(\psi(v)) \neq f(v)$ for every $v \in P_{s}$. Note that $g \circ \psi: P_{s} \rightarrow[\mathfrak{b}, \infty]$ is upper semi-Baire class 1 , and for any increasing homeomorphism $h:[\mathfrak{b}, \infty] \rightarrow[0,1]$, the map $c:=h \circ g \circ \psi: P_{s} \rightarrow[0,1]$ is also upper semi-Baire class 1. By [4, Theorem 2.1], there is a map $\tilde{u}: T_{s} \rightarrow \mathbb{R}$ such that

$$
\forall v \in P_{s}: \quad c(v)=\varlimsup_{m \in \mathbb{N}_{1}} \tilde{u}\left(\left.v\right|_{m}\right)
$$

Define $u^{\prime}: T_{s} \rightarrow[0,1)$ by

$$
\forall t \in T_{s}: \quad u^{\prime}(t):= \begin{cases}\tilde{u}(t) & \text { if } \tilde{u}(t) \in[0,1) \\ 0 & \text { if } \tilde{u}(t)<0 \\ 1-2^{-\operatorname{len}(t)} & \text { if } \tilde{u}(t) \geqslant 1\end{cases}
$$

Note that

$$
\forall v \in P_{s}: \quad c(v)=\varlimsup_{m \in \mathbb{N}_{1}} u^{\prime}\left(\left.v\right|_{m}\right) .
$$

Finally, defining $u: T_{s} \rightarrow[\mathfrak{b}, \infty)$ by $u:=h^{-1} \circ u^{\prime}$, we see that

$$
\forall v \in P_{s}: \quad g(\psi(v))=h^{-1}(c(v))=\varlimsup_{m \in \mathbb{N}_{1}} u\left(\left.v\right|_{m}\right)
$$

On the other hand, Lemma 5.1 provides $v \in P_{s}$ such that

$$
g(\psi(v))=\varlimsup_{m \in \mathbb{N}_{1}} u\left(\left.v\right|_{m}\right)=\varlimsup_{n \in \mathbb{N}_{1}} \mathfrak{L}\left(v_{n}\right)=f(v),
$$

which is the desired contradiction.
Note that the function $\bar{L}:[\mathfrak{b}, \infty)^{\omega} \rightarrow[\mathfrak{b}, \infty]$ given by

$$
\forall x=\left(x_{n}\right)_{n \in \mathbb{N}_{1}}: \quad \bar{L}(x):=\varlimsup_{n \in \mathbb{N}_{1}} x_{n}
$$

is upper semi-Baire class 1 . Indeed, for any $t \in \mathbb{R}$ we have

$$
\varlimsup_{n \in \mathbb{N}_{1}} x_{n}<\mathrm{t} \quad \Longleftrightarrow \quad \exists m, k \in \mathbb{N}, \forall n \geqslant m: \quad x_{n} \leqslant \mathrm{t}-2^{-k}
$$

and the latter is a $\Sigma_{2}^{0}$ condition. Noting that $P$ is Polish (for it is a closed subset of the Polish space $V^{\omega}$ ), and $f$ is the composition of the continuous map $\left(\left(v_{n}\right)_{n \in \mathbb{N}_{1}}\right) \mapsto\left(\mathfrak{L}\left(v_{n}\right)\right)_{n \in \mathbb{N}_{1}}$ with $\bar{L}$, it follows that $f$ is upper semi-Baire class 1. Taking $s=\varnothing$, we deduce that $f$ is $[\mathfrak{b}, \infty]$-upper semi-Baire class 1 complete.

To finish the proof, let $\mathrm{t} \in[\mathfrak{b}, \infty]$, and let $O$ be an arbitrary nonempty open subset of $P$. Fix an element $s \in T$ such that $\operatorname{len}(s)>M_{1}$ and $P_{s} \subset O$. Since $[\mathfrak{b}, \infty]$ is a nonempty metrizable compact space, [ $\mathbf{6}$, Theorem 4.18] yields a continuous surjection $g: 2^{\omega} \rightarrow[\mathfrak{b}, \infty]$; in particular, $g$ is upper semi-Baire class 1 . By the above argument, there is a continuous function $\phi: 2^{\omega} \rightarrow P_{s}$ such that $g=f \circ \phi$. Now, let $x \in 2^{\omega}$ with $g(x)=\mathrm{t}$. Then $\phi(x) \in P_{s} \subset O$ and $f(\phi(x))=\mathrm{t}$, which shows that $f$ is densely onto.

Proof of Theorems 1.2 and 1.4. Let $\ell: V \rightarrow[1, \infty)$ be the map given by (2.3), and let

$$
B:=\left\{\left(\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)\right) \in V^{2}: x_{2}=y_{1} \text { and } y_{2}=a y_{1}+x_{1} \text { for some } a \in \mathbb{N}_{1}\right\}
$$

As noted previously, $\ell$ is $(B, 1)$-target-controlled in view of Lemma 2.1.
To facilitate the proofs, consider the following commutative diagram:


In what follows, we describe the various maps shown in the diagram and study the interplay between them. First of all, we have the type function $\tau: \mathbb{R} \backslash \mathbb{Q} \rightarrow[1, \infty]$, which is the subject of the present paper. Next, the map $\phi: \mathbb{R} \backslash \mathbb{Q} \rightarrow \mathbb{Z} \times \mathbb{N}_{1}^{\omega}$ given by

$$
\alpha=\left[a_{0} ; a_{1}, a_{2}, \ldots\right] \mapsto \phi(\alpha):=\left(a_{n}\right)_{n \in \mathbb{N}}
$$

is the homeomorphism given in Proposition 3.5. To every $\left(a_{n}\right)_{n \in \mathbb{N}}$ we associate a sequence $\left(k_{n}\right)_{n \in \mathbb{N}}$ of positive integers using the definition (3.4) (so the $k_{n}$ are
the denominators of the continued fractions for $\alpha$ ). Then, defines a sequence $\left(v_{n}\right)_{n \in \mathbb{N}_{1}}$ of vertices in $V$ as follows:

$$
\forall n \in \mathbb{N}_{1}: \quad v_{n}:=\left(k_{n}, k_{n+1}\right) .
$$

Recall that in $\S 3.4$ we have seen that

$$
\tau(\alpha)=\varlimsup_{n \rightarrow \infty} \frac{\log k_{n+1}}{\log k_{n}}=\varlimsup_{n \rightarrow \infty} \ell\left(v_{n}\right) .
$$

For each $n \in \mathbb{N}_{1}$ we have $v_{n} \stackrel{a_{n+2}}{\sim} v_{n+1}$, which implies $\left(v_{n}, v_{n+1}\right) \in B$; thus we deduce that $\left(v_{n}\right)_{n \in \mathbb{N}_{1}}$ lies in $P$. We let $f: P \rightarrow[1, \infty]$ be the map given by

$$
\forall v=\left(v_{n}\right)_{n \in \mathbb{N}_{1}} \in P: \quad f(v):=\varlimsup_{n \in \mathbb{N}_{1}} \ell\left(v_{n}\right)=\tau(\alpha) .
$$

Next, observe that the map $\Phi: \mathbb{N}_{1}^{\omega} \rightarrow P$ given by

$$
\forall a=\left(a_{n}\right)_{n \in \mathbb{N}_{1}} \in \mathbb{N}_{1}^{\omega}: \quad \Phi(a):=\left(v_{n}\right)_{n \in \mathbb{N}_{1}}
$$

is continuous. Moreover, setting $a_{1}:=k_{1}$ and $a_{n+2}:=\left(k_{n+2}-k_{n}\right) / k_{n+1}$ for all $n \in \mathbb{N}$ and $\left(v_{n}\right)_{n \in \mathbb{N}_{1}} \in P$, it is clear that the inverse map $\Phi^{-1}: P \rightarrow \mathbb{N}_{1}^{\omega}$ given by

$$
\forall v=\left(v_{n}\right)_{n \in \mathbb{N}_{1}} \in P: \quad \Phi^{-1}(v):=\left(a_{n}\right)_{n \in \mathbb{N}_{1}}
$$

is also continuous. Therefore, $\Phi$ is a homeomorphism of $\mathbb{N}_{1}^{\omega}$ onto $P$. Finally, we let $\pi: \mathbb{Z} \times \mathbb{N}_{1}^{\omega} \rightarrow \mathbb{N}_{1}^{\omega}$ be the projection given by $\pi\left(\left(a_{n}\right)_{n \in \mathbb{N}}\right):=\left(a_{n}\right)_{n \in \mathbb{N}_{1}}$.

Let $\lambda: \mathbb{R} \backslash \mathbb{Q} \rightarrow P$ be the composition $\Phi \circ \pi \circ \phi$; it is a continuous map. Note that $\tau=f \circ \lambda$. By Theorem 5.2, $f$ is densely onto, and so for any $\mathrm{t} \in[1, \infty]$ :
$f^{-1}(\{\mathrm{t}\})$ is dense in $P \Longrightarrow(f \circ \Phi)^{-1}(\{\mathrm{t}\})$ is dense in $\mathbb{N}_{1}^{\omega}$
$\Longrightarrow \quad(f \circ \Phi \circ \pi)^{-1}(\{\mathrm{t}\})$ is dense in $\mathbb{Z} \times \mathbb{N}_{1}^{\omega}$
$\Longrightarrow \tau^{-1}(\{\mathrm{t}\})=(f \circ \lambda)^{-1}(\{\mathrm{t}\})$ is dense in $\mathbb{R} \backslash \mathbb{Q}$,
which completes our third proof of Theorem 1.2.
We turn to the proof of Theorem 1.4. By Theorem 5.2, $f$ is $[1, \infty]$-upper semi-Baire class 1 complete. If $g: 2^{\omega} \rightarrow[1, \infty]$ is also upper semi-Baire class 1 , then there is a continuous map $\varphi: 2^{\omega} \rightarrow P$ for which $g=f \circ \varphi$ (see the diagram). Let $\rho: 2^{\omega} \rightarrow \mathbb{R} \backslash \mathbb{Q}$ be defined by

$$
\forall x \in 2^{\omega}: \quad \rho(x):=\phi^{-1}\left(0, \Phi^{-1}(\varphi(x))\right) .
$$

Then $\rho$ is continuous, and

$$
\forall x \in 2^{\omega}: \quad \tau(\rho(x))=f(\varphi(x))=g(x)
$$

The theorem follows.

## 6. COMPLEXITY AND BAIRE CATEGORY

In this section, we give general conditions ensuring the descriptive set theoretic property of the type mentioned in Theorem 1.3. We also provide Baire category properties.

Recall that a subset of a topological space is said to be nowhere dense if its closure has an empty interior, meager if it is a countable union of nowhere dense sets, and comeager if its complement is meager. Meagerness is a very useful notion of smallness in any completely metrizable space (cf. [6, §8.B]) since the class of meager sets is a $\sigma$-ideal, i.e., it is closed under taking subsets and countable unions. A property that holds for a comeager set of points intuitively holds topologically "almost everywhere" in such spaces. Of course, a set can be large in the sense of topology and small in the sense of measure. Consider, for example, the set of Liouville numbers. The proof of Theorem 1.3 shows that the Liouville numbers form a comeager subset of $\mathbb{R} \backslash \mathbb{Q}$, whereas the same set is well known to have Lebesgue measure zero; see Oxtoby [9, §2] (we also refer the reader to [9] for general background on measure and topology).

Theorem 6.1. The function $f: P \rightarrow[\mathfrak{b}, \infty]$ defined by (5.2) is upper semi-Baire class 1 and Baire class 2, but it is not Baire class 1. More precisely, $f$ has the properties outlined in the following table.

|  | $\mathrm{t}=\mathfrak{b}$ | $\mathrm{t} \in(\mathfrak{b}, \infty)$ | $\mathrm{t}=\infty$ |
| :---: | :---: | :---: | :---: |
| $v: f(v)<\mathrm{t}$ | $\varnothing$ | meager $\boldsymbol{\Sigma}_{2}^{0}$-complete | meager $\boldsymbol{\Sigma}_{2}^{0}$-complete |
| $v: f(v) \geqslant \mathrm{t}$ | $P$ | comeager $\boldsymbol{\Pi}_{2}^{0}$-complete | comeager $\boldsymbol{\Pi}_{2}^{0}$-complete |
| $v: f(v)>\mathrm{t}$ | comeager $\boldsymbol{\Sigma}_{3}^{0}$-complete | comeager $\boldsymbol{\Sigma}_{3}^{0}$-complete | $\varnothing$ |
| $v: f(v) \leqslant \mathrm{t}$ | meager $\boldsymbol{\Pi}_{3}^{0}$-complete | meager $\boldsymbol{\Pi}_{3}^{0}$-complete | $P$ |
| $v: f(v)=\mathrm{t}$ | meager $\boldsymbol{\Pi}_{3}^{0}$-complete | meager $\boldsymbol{\Pi}_{3}^{0}$-complete | comeager $\boldsymbol{\Pi}_{2}^{0}$-complete |

Proof. First, note that $f$ is upper semi-Baire class 1, by Theorem 5.2. This implies that $f$ is Baire class 2 because

$$
\begin{array}{rlll}
f(v)<\infty & \Longleftrightarrow \exists n \in \mathbb{N}: \quad f(v)<n & \left(\Sigma_{2}^{0} \text { condition }\right) \\
f(v)>\mathrm{t} & \Longleftrightarrow \exists k \in \mathbb{N}: \quad f(v) \geqslant \mathrm{t}+2^{-k} & \left(\Sigma_{3}^{0} \text { condition }\right) \\
f(v)>-\infty & \Longleftrightarrow \exists n \in \mathbb{Z}: \quad f(v) \geqslant n & \left(\Sigma_{3}^{0} \text { condition }\right) .
\end{array}
$$

On the other hand, we show below that the condition $f(v)>\mathrm{t}$ is not $\boldsymbol{\Pi}_{3}^{0}$ for any real $\mathbf{t} \geqslant \mathfrak{b}$ (hence not a $\boldsymbol{\Sigma}_{2}^{0}$ condition), and thus $f$ is not Baire class 1 .

As above, the set $f^{-1}(\{\infty\})$ is in $\Pi_{2}^{0}$, and by Theorem 5.2, the map $f$ is densely onto; therefore, $f^{-1}(\{\infty\})$ is a dense $\Pi_{2}^{0}$, and thus it is a countable intersection of dense open sets. The complement of $f^{-1}(\{\infty\})$ is a countable union of closed sets with an empty interior, and so $f^{-1}(\{\infty\})$ is comeager, a fact that implies all of the meagerness and comeagerness properties listed in the table.

Again, since $f$ is densely onto, both $f^{-1}(\{\infty\})$ and its complement are dense in $P$. As in the proof of Lemma 4.1, we deduce that $f^{-1}(\{\infty\})$ is $\boldsymbol{\Pi}_{2}^{0}$-complete. Using similar arguments, we find that the set $f^{-1}([-\infty, \mathrm{t}))$ is $\boldsymbol{\Sigma}_{2}^{0}$-complete for any
$\mathrm{t} \in(\mathfrak{b}, \infty)$, This proves our assertions for the rows $v: f(v)<\mathrm{t}$ and $v: f(v) \geqslant \mathrm{t}$ in the table, as well as the column $t=\infty$.

From now on, let $\mathrm{t} \in[\mathfrak{b}, \infty)$ be fixed. We have seen that $f^{-1}([-\infty, \mathrm{t}])$ is $\boldsymbol{\Pi}_{3}^{0}$ and $f^{-1}([\mathrm{t}, \infty])$ is $\boldsymbol{\Pi}_{2}^{0}$, which implies that $f^{-1}(\{\mathrm{t}\})$ is $\boldsymbol{\Pi}_{3}^{0}$. To finish the proof, we need to prove that $f^{-1}([-\infty, t])$ and $f^{-1}(\{t\})$ are $\boldsymbol{\Pi}_{3}^{0}$-complete.

In view of Lemma 4.3, it is enough to show that $\mathcal{N}_{\infty} \leqslant W f^{-1}([-\infty, \mathrm{t}])$ and $\mathcal{N}_{\infty} \leqslant{ }_{W} f^{-1}(\{\mathrm{t}\})$, and for this, it suffices to find a continuous map

$$
F: \mathbb{N}_{1}^{\omega} \rightarrow P
$$

with the following property:

$$
\begin{equation*}
\beta \in \mathcal{N}_{\infty} \quad \Longleftrightarrow \quad f(F(\beta))=\mathrm{t} \quad \Longleftrightarrow \quad f(F(\beta)) \leqslant \mathrm{t} \tag{6.1}
\end{equation*}
$$

One such map $F$ can be constructed as follows.
Fix once and for all two strictly decreasing sequences $\left(\mathrm{t}_{j}\right)_{j \in \mathbb{N}}$ and $\left(\varepsilon_{j}\right)_{j \in \mathbb{N}}$ of real numbers with

$$
\begin{equation*}
\lim _{j \rightarrow \infty} \mathrm{t}_{j}=\mathrm{t} \quad \text { and } \quad \lim _{j \rightarrow \infty} \varepsilon_{j}=0 \tag{6.2}
\end{equation*}
$$

We further assume that $\varepsilon_{j}<1$ for all $j \in \mathbb{N}$, and that the intervals

$$
\forall j \in \mathbb{N}: \quad U_{j}:=\left[\mathrm{t}_{j}, \mathrm{t}_{j}+\varepsilon_{j}\right)
$$

are pairwise disjoint (equivalently, $\mathrm{t}_{i}+\varepsilon_{i} \leqslant \mathrm{t}_{j}$ for all $i>j$ ). Let $\left(y_{j}\right)_{j \in \mathbb{N}}$ be a (strictly increasing) sequence of positive integers with the property that

$$
\forall j \in \mathbb{N}: \quad y_{j} \geqslant M_{\mathfrak{B}, \mathfrak{b}}\left(\varepsilon_{j}\right) .
$$

This definition is motivated by the fact that $\mathfrak{L}$ is $(\mathfrak{B}, \mathfrak{b})$-target-controlled, which implies that if $v=(x, y)$ lies in $V$ and $y>y_{j}$, then there is a vertex $w \in V$ such that $(v, w) \in \mathfrak{B}$ and $\mathfrak{L}(w) \in U_{j}$.

To define $F$, let $\beta \in \mathbb{N}_{1}^{\omega}$ be given. Regardless of the value $\beta(0)$, let

$$
k_{0}:=1, \quad k_{1}:=y_{1}+1, \quad \text { and } \quad v_{0}:=\left(k_{0}, k_{1}\right) .
$$

Using induction on $n$, we now construct a sequence $\left(k_{n}\right)_{n \in \mathbb{N}}$ of positive integers and a sequence $\left(v_{n}\right)_{n \in \mathbb{N}_{1}}$ in $V$. Indeed, suppose that $v_{n-1}=\left(k_{n-1}, k_{n}\right) \in V$ has already been defined for some $n \in \mathbb{N}_{1}$. Let $j(n)$ be the largest integer satisfying both inequalities

$$
\begin{equation*}
j(n) \leqslant \beta(n) \quad \text { and } \quad y_{j(n)}<k_{n} . \tag{6.3}
\end{equation*}
$$

Note that $j(n) \geqslant 1$. Since $\mathfrak{L}$ is $(\mathfrak{B}, \mathfrak{b})$-target-controlled, there exists a vertex $v_{n}=\left(k_{n}, k_{n+1}\right) \in V$ such that

$$
\begin{equation*}
\left(v_{n-1}, v_{n}\right) \in \mathfrak{B} \quad \text { and } \quad \mathfrak{L}\left(v_{n}\right) \in U_{j(n)}, \tag{6.4}
\end{equation*}
$$

which completes the induction. Note that the resulting sequence $\left(k_{n}\right)_{n \in \mathbb{N}}$ is strictly increasing. We define $F: \mathbb{N}_{1}^{\omega} \rightarrow P$ according to the rule

$$
\beta \mapsto F(\beta):=\left(v_{n}\right)_{n \in \mathbb{N}_{1}} .
$$

The map $F$ is continuous since, for every $n \in \mathbb{N}$, the choice of $v_{n}$ is made using only the values $\beta(m)$ with $m \leqslant n$.

Next, let $\beta \in \mathbb{N}_{1}^{\omega}$ be fixed. With the notation above, let $v:=F(\beta)$. By (5.2) we have

$$
\begin{equation*}
f(v)=\varlimsup_{n \in \mathbb{N}_{1}} \mathfrak{L}\left(v_{n}\right) \tag{6.5}
\end{equation*}
$$

and each $\mathfrak{L}\left(v_{n}\right)$ lies in the interval $U_{j(n)}=\left[\mathrm{t}_{j(n)}, \mathrm{t}_{j(n)}+\varepsilon_{j(n)}\right)$. Putting everything together, we have

$$
\begin{array}{rlrl}
\beta \in \mathcal{N}_{\infty} & \Longrightarrow \lim _{n \rightarrow \infty} \beta(n)=\infty & & \left(\text { definition of } \mathcal{N}_{\infty}\right) \\
& \Longrightarrow \lim _{n \rightarrow \infty} j(n)=\infty & & (\text { see }(6.3)) \\
& \Longrightarrow \lim _{n \rightarrow \infty} \mathrm{t}_{j(n)}=\mathrm{t} \text { and } \lim _{n \rightarrow \infty} \varepsilon_{j(n)}=0 & (\text { see }(6.2)) \\
& \Longrightarrow \lim _{n \rightarrow \infty} \mathfrak{L}\left(v_{n}\right)=\mathrm{t} & & \left(\text { definition of } U_{j(n)}\right) \\
& \Longrightarrow f(v)=\mathrm{t} & & (\text { see }(6.5))
\end{array}
$$

On the other hand,

$$
\beta \notin \mathcal{N}_{\infty} \quad \Longrightarrow \quad \underline{\lim }_{n \rightarrow \infty} \beta(n)<\infty \quad \Longrightarrow \quad \underline{\lim }_{n \rightarrow \infty} j(n)<\infty .
$$

The last condition implies that there is a positive integer $j_{0}$ such that $j(n)=j_{0}$ for infinitely many $n$; therefore,

$$
f(v)=\varlimsup_{n \rightarrow \infty} \mathfrak{L}\left(v_{n}\right) \geqslant \mathrm{t}_{j_{0}}>\mathrm{t} .
$$

Since $v=F(\beta)$, we have established (6.1), and we are done.
We are now ready to prove Theorem 1.3.
Proof of Theorem 1.3. As in the proof of Theorems 1.2 and 1.4 (see §5.4), we have the commutative diagram:


For every subset $S \subset \mathbb{N}_{1}^{\mathbb{N}_{1}}$, we have $\mathbb{Z} \times S \leqslant W S$ with witness $(z, a) \mapsto a$, and $S \leqslant W \mathbb{Z} \times S$ with witness $a \mapsto(0, a)$. Since $\phi$ and $\Phi$ are homeomorphisms, the topological properties of $f$ given by Theorem 6.1 imply the properties of $\tau$ stated in Theorem 1.3.

Remark. In Theorem 6.1, one can replace $\overline{\mathbb{R}}$ with a dense complete lattice whose order topology is metrizable. However, such an ordered topological space is isomorphic to $\overline{\mathbb{R}}$, so this is not really a generalization.

## Appendix A. Some equivalent definitions of Type

The type function can be defined in various ways, and our aim is to show that the definition in our abstract is consistent with the definition given in §1.1. Here, we define type functions $\tau_{1}, \tau_{2}$, and $\tau_{3}$ in three different ways, showing that $\tau_{1}=\tau_{2}=\tau_{3}$.

In the abstract, we define $\tau:=\tau_{1}$ with $\tau_{1}(\alpha):=\inf \left\{t \in \mathbb{R}:|\alpha-h / k|<k^{-t-1}\right.$ for only finitely many $\left.(h, k) \in \mathbb{Z} \times \mathbb{N}_{1}\right\}$.
On the other hand, in $\S 1.1$ we define $\tau:=\tau_{2}$ with

$$
\tau_{2}(\alpha):=\sup \left\{\theta \in \mathbb{R}: \lim _{k \in \mathbb{N}} k^{\theta} \llbracket k \alpha \rrbracket=0\right\} .
$$

Finally, a useful intermediate definition is $\tau:=\tau_{3}$ with

$$
\tau_{3}(\alpha):=\sup \left\{\theta \in \mathbb{R}: \frac{\lim _{k \in \mathbb{N}}}{} k^{\theta} \llbracket k \alpha \rrbracket<1\right\}
$$

We have trivially

$$
\varliminf_{k \in \mathbb{N}} k^{\theta} \llbracket k \alpha \rrbracket=0 \quad \Longrightarrow \quad \lim _{k \in \mathbb{N}} k^{\theta} \llbracket k \alpha \rrbracket<1,
$$

and in the opposite direction,

$$
\forall \varepsilon>0: \quad \frac{\lim }{k \in \mathbb{N}} k^{\theta} \llbracket k \alpha \rrbracket<1 \quad \Longrightarrow \quad \lim _{k \in \mathbb{N}} k^{\theta-\varepsilon} \llbracket k \alpha \rrbracket=0 .
$$

These implications imply that $\tau_{2}=\tau_{3}$.
Next, we show $\tau_{1}=\tau_{3}$. If $\tau_{3}(\alpha)<\infty$, then from the chain of implications

$$
\begin{aligned}
t>\tau_{3}(\alpha) & \Longrightarrow \frac{\lim _{k \in \mathbb{N}}}{} k^{t} \llbracket k \alpha \rrbracket \geqslant 1 \\
& \Longrightarrow \exists k_{0} \forall k \geqslant k_{0}: \quad k^{t} \llbracket k \alpha \rrbracket \geqslant 1 \\
& \Longrightarrow \exists k_{0} \forall k \geqslant k_{0}: \quad k^{t} \min _{h \in \mathbb{Z}}|k \alpha-h| \geqslant 1 \\
& \Longrightarrow \exists k_{0} \forall k \geqslant k_{0} \forall h: \quad|\alpha-h / k| \geqslant k^{-t-1} \\
& \Longrightarrow t \geqslant \tau_{1}(\alpha),
\end{aligned}
$$

thus $\tau_{1}(\alpha)$ is also finite, and

$$
\begin{equation*}
\tau_{1}(\alpha) \leqslant \tau_{3}(\alpha) \tag{A.1}
\end{equation*}
$$

Note that (A.1) is trivial when $\tau_{3}(\alpha)=\infty$. In the other direction, we have

$$
\begin{aligned}
t<\tau_{3}(\alpha) & \Longrightarrow \forall \varepsilon>0: \quad \lim _{k \in \mathbb{N}} k^{t-\varepsilon} \llbracket k \alpha \rrbracket<1 \\
& \Longrightarrow \forall \varepsilon>0 \exists^{\infty} k: \quad k^{t-\varepsilon} \llbracket k \alpha \rrbracket<1 \\
& \Longrightarrow \forall \varepsilon>0 \exists^{\infty} k: \quad k^{t-\varepsilon} \min _{h \in \mathbb{Z}}|k \alpha-h|<1 \\
& \Longrightarrow \forall \varepsilon>0 \exists^{\infty} k \exists h: \quad|\alpha-h / k|<k^{-t-\varepsilon-1} \\
& \Longrightarrow \quad \forall \varepsilon>0: \quad t-\varepsilon \leqslant \tau_{1}(\alpha) .
\end{aligned}
$$

If $\tau_{3}(\alpha)=\infty$, then taking $t \rightarrow \infty$ we deduce that $\tau_{1}(\alpha)=\infty$ as well; in particular,

$$
\begin{equation*}
\tau_{3}(\alpha) \leqslant \tau_{1}(\alpha) \tag{A.2}
\end{equation*}
$$

If $\tau_{3}(\alpha)<\infty$, we see that $\tau_{3}(\alpha) \leqslant \tau_{1}(\alpha)+\varepsilon$ for every $\varepsilon>0$, which implies (A.2) in this case. Finally, combining (A.1) and (A.2), we have $\tau_{1}=\tau_{3}$.

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[^1]:    ${ }^{1}$ Due to the interdisciplinary nature of this work, we have included many basic definitions throughout the paper to keep the exposition fairly self-contained and accessible to readers from both areas of mathematics.
    ${ }^{2}$ This definition of the type is equivalent to the definition given in our abstract; proof of the equivalence is given in the appendix.

[^2]:    ${ }^{3}$ Dirichlet's approximation theorem asserts that for any $\alpha, Q \in \mathbb{R}, Q \geqslant 1$, there is a rational number $p / q$ with $1 \leqslant q \leqslant Q$ such that $|\alpha-p / q|<1 /(q Q)$; see, e.g., Bugeaud [2, Thm 1.1]. From this, it follows that for any irrational $\alpha$ one has $q \llbracket q \alpha \rrbracket<1$ for infinitely many $q \in \mathbb{N}$.

[^3]:    ${ }^{4}$ We emphasize that the target space $K$ is an essential part of the definition. For example, if $f, g$ are constant functions taking different values, no function $\phi$ has the stated property.

