

# Complement to: Willmore immersions and Loop groups

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## The Euler–Lagrange equation of the Willmore functional

The derivation of the Euler–Lagrange equation of the Willmore functional was done in [1]. However I found this proof difficult to follow and I present here an alternative redaction.

*Proof* — Using the notations of [2] we know that we may write the Willmore functional as

$$\mathcal{W}(X) = \int_U -\omega_3^1 \wedge \omega_3^2 \equiv \int_U \Omega_X,$$

which is precisely minus the area covered by  $\gamma$ . We start from an immersion  $X : U \longrightarrow S^3$ , not necessarily conformal, and we consider some section  $e$  of the associated bundle  $\mathcal{F}_X^{(\gamma)}$ . We perform a variation of  $X$  induced by

$$e_0(t) = e_0 + t\lambda e_3, \tag{1}$$

where  $\lambda : U \longrightarrow \mathbb{R}$  is some smooth map with compact support in  $U$ . We can construct for each  $t$  sufficiently small the associated conformal Gauss map  $\gamma(t) = e_3(t)$ , and the orthonormal frame  $(e_1(t), e_2(t))$  for instance by the Gram-Schmitt orthonormalisation of  $(\frac{\partial e_0}{\partial x}(t), \frac{\partial e_0}{\partial y}(t))$ . By completing by an adequate vector  $e_4(t)$  in  $\mathcal{C}_+$ , we construct a section  $e(t)$  of  $\mathcal{F}_{t,X}^{(\gamma)}$  for  $t$  sufficiently small. We now introduce the matrix of elements  $\lambda_j^i$  depending smoothly on  $z$  such that if the dot denotes the derivatives with respect to  $t$  at  $t = 0$ , we have

$$\dot{e}_j = e_i \lambda_j^i. \tag{2}$$

We have  $B_{ac}\lambda_b^c + B_{bc}\lambda_a^c = 0$  and by (1)

$$\lambda_0^0 = \lambda_0^1 = \lambda_0^2 = 0 ; \lambda_0^3 = \lambda. \tag{3}$$

We wish to compute the first variation of  $\int_U \Omega_X$  by this deformation.

*First step.* Brutal computation of  $\dot{\Omega}_X$ : Using (2) we get that

$$\begin{aligned} \dot{\omega}_3^1 &= \langle d\dot{e}_3, e_1 \rangle + \langle de_3, \dot{e}_1 \rangle \\ &= d\lambda_3^1 + \lambda_3^0 \omega_0^1 + \lambda_3^2 \omega_2^1 + \lambda_0^3 \omega_1^0 + \lambda_1^2 \omega_3^2 \\ \dot{\omega}_3^2 &= \langle d\dot{e}_3, e_2 \rangle + \langle de_3, \dot{e}_2 \rangle \\ &= d\lambda_3^2 + \lambda_3^0 \omega_0^2 + \lambda_3^1 \omega_1^2 + \lambda_0^3 \omega_2^0 + \lambda_2^1 \omega_3^1. \end{aligned}$$

Thus

$$\begin{aligned}
-\dot{\Omega}_X &= (d\lambda_3^1 \wedge \omega_3^2 + \lambda_3^2 \omega_2^1 \wedge \omega_3^2 + \omega_3^1 \wedge d\lambda_3^2 + \lambda_3^1 \omega_3^1 \wedge \omega_1^2) \\
&+ \lambda_0^3 (\omega_1^0 \wedge \omega_3^2 + \omega_3^1 \wedge \omega_2^0) \\
&+ \lambda_3^0 (\omega_1^0 \wedge \omega_3^2 + \omega_3^1 \wedge \omega_2^0).
\end{aligned} \tag{4}$$

We then use (??) and the fact that  $h_{11} + h_{22} = 0$  to cancel the last term in the right hand side of (4). Moreover using the structure equations

$$\begin{aligned}
d\omega_3^1 + \omega_0^1 \wedge \omega_3^0 + \omega_2^1 \wedge \omega_3^2 &= 0 \\
d\omega_3^2 + \omega_0^2 \wedge \omega_3^0 + \omega_1^2 \wedge \omega_3^1 &= 0
\end{aligned}$$

we can transform the first term in the right hand side of (4) as

$$\begin{aligned}
d\lambda_3^1 \wedge \omega_3^2 - \lambda_3^2 (d\omega_3^1 + \omega_0^1 \wedge \omega_3^0) + \omega_3^1 \wedge d\lambda_3^2 + \lambda_3^1 (d\omega_3^2 + \omega_0^2 \wedge \omega_3^0) \\
= d(\lambda_3^1 \omega_3^2 - \lambda_3^2 \omega_3^1) + (\lambda_3^1 \omega_0^2 - \lambda_3^2 \omega_0^1) \wedge \omega_3^0.
\end{aligned}$$

Thus we obtain that

$$\begin{aligned}
-\dot{\Omega}_X &= d(\lambda_3^1 \omega_3^2 - \lambda_3^2 \omega_3^1) + (\lambda_3^1 \omega_0^2 - \lambda_3^2 \omega_0^1) \wedge \omega_3^0 \\
&+ \lambda_0^3 (\omega_1^0 \wedge \omega_3^2 + \omega_3^1 \wedge \omega_2^0).
\end{aligned} \tag{5}$$

*Second step.* We compute the last term in the right hand side of (5). We set  $\omega_3^0 = h_1 \omega_0^1 + h_2 \omega_0^2$ , and we differentiate this expression. This gives

$$d\omega_3^0 = dh_1 \wedge \omega_0^1 + dh_2 \wedge \omega_0^2 + h_1 d\omega_0^1 + h_2 d\omega_0^2.$$

We develop this relation using the structure equations and (??) as

$$\begin{aligned}
(dh_1 + 2\omega_0^0 h_1 - \omega_1^2 h_2 - h_{11} \omega_1^0 - h_{12} \omega_2^0) \wedge \omega_0^2 \\
+ (dh_2 + 2\omega_0^0 h_2 - \omega_2^1 h_1 - h_{21} \omega_1^0 - h_{22} \omega_2^0) \wedge \omega_0^1 = 0.
\end{aligned} \tag{6}$$

And using Cartan lemma this implies that there exist smooth functions  $p_{11}, p_{12} = p_{21}$  and  $p_{22}$  such that

$$\begin{cases} dh_1 + 2\omega_0^0 h_1 = \omega_1^2 h_2 + h_{11} \omega_1^0 + h_{12} \omega_2^0 + p_{11} \omega_0^1 + p_{12} \omega_0^2 & (a) \\ dh_2 + 2\omega_0^0 h_2 = \omega_2^1 h_1 + h_{21} \omega_1^0 + h_{22} \omega_2^0 + p_{21} \omega_0^1 + p_{22} \omega_0^2 & (b) \end{cases} \tag{7}$$

And a computation of  $(a) \wedge \omega_0^2 - (b) \wedge \omega_0^1$  gives

$$\begin{aligned}
dh_1 \wedge \omega_0^2 - dh_2 \wedge \omega_0^1 + 2\omega_0^0 \wedge (h_1 \omega_0^2 - h_2 \omega_0^1) \\
= \omega_1^2 \wedge (h_2 \omega_0^2 + h_1 \omega_0^1) - (\omega_2^1 \wedge \omega_0^2 + \omega_1^0 \wedge \omega_2^3) + (p_{11} + p_{22}) \omega_0^1 \wedge \omega_0^2.
\end{aligned} \tag{8}$$

Relation (8) gives us an expression for  $\omega_1^3 \wedge \omega_2^0 + \omega_1^0 \wedge \omega_2^3$ , which we can again transform using the structure relations

$$\begin{cases} d\omega_0^1 + \omega_0^1 \wedge \omega_0^0 + \omega_2^1 \wedge \omega_0^2 = 0 \\ d\omega_0^2 + \omega_0^2 \wedge \omega_0^0 + \omega_1^2 \wedge \omega_0^1 = 0 \end{cases} \tag{9}$$

as

$$\begin{aligned} \omega_3^1 \wedge \omega_2^0 + \omega_1^0 \wedge \omega_3^2 &= d(h_1\omega_0^2 - h_2\omega_0^1) + \omega_0^0 \wedge (h_1\omega_0^2 - h_2\omega_0^1) \\ &\quad - (p_{11} + p_{22})\omega_0^1 \wedge \omega_0^2. \end{aligned} \quad (10)$$

*Third step.* We inject the result of step 2 summarized in (10) in the formula for  $\dot{\Omega}_X$  given by (5). It leads to

$$\begin{aligned} -\dot{\Omega}_X &= d(\lambda_3^1\omega_3^2 - \lambda_3^2\omega_3^1) + (\lambda_3^1\omega_0^2 - \lambda_3^2\omega_0^1) \wedge \omega_3^0 \\ &\quad + \lambda_0^3 d(h_1\omega_0^2 - h_2\omega_0^1) + \lambda_0^3\omega_0^0 \wedge (h_1\omega_0^2 - h_2\omega_0^1) \\ &\quad - \lambda_0^3(p_{11} + p_{22})\omega_0^1 \wedge \omega_0^2 \\ &= d(\lambda_3^1\omega_3^2 - \lambda_3^2\omega_3^1) + \lambda_0^3 d(h_1\omega_0^2 - h_2\omega_0^1) \\ &\quad + (\lambda_0^3\omega_0^0 - \lambda_3^1\omega_0^1 - \lambda_3^2\omega_0^2) \wedge (h_1\omega_0^2 - h_2\omega_0^1) \\ &\quad - \lambda_0^3(p_{11} + p_{22})\omega_0^1 \wedge \omega_0^2, \end{aligned} \quad (11)$$

where we used  $\omega_3^0 = h_1\omega_0^1 + h_2\omega_0^2$ .

Lastly we exploit a relation between the coefficients  $\lambda_j^i$  which we did not use before. Since we impose the constraint  $\omega_0^3 = 0$ , for small  $t$ , we have

$$0 = \langle d\dot{e}_0, e_3 \rangle + \langle de_0, \dot{e}_3 \rangle,$$

which leads to

$$d\lambda_0^3 = \lambda_0^3\omega_0^0 - \lambda_3^1\omega_0^1 - \lambda_3^2\omega_0^2. \quad (12)$$

We insert this relation in (11) to get

$$\begin{aligned} \dot{\Omega}_X &= \lambda_0^3(p_{11} + p_{22})\omega_0^1 \wedge \omega_0^2 \\ &\quad + d[\lambda_3^1\omega_3^2 - \lambda_3^2\omega_3^1 + \lambda_0^3(h_1\omega_0^2 - h_2\omega_0^1)]. \end{aligned} \quad (13)$$

*Conclusion.* We obtain that

$$\int_U \dot{\Omega}_X = \int_U \lambda(p_{11} + p_{22})\omega_0^1 \wedge \omega_0^2, \quad (14)$$

and this implies that any Willmore immersion satisfies the equation

$$p_{11} + p_{22} = 0. \quad (15)$$

[1] R. BRYANT, *A duality theorem for Willmore surfaces*, Journal of Differential Geometry 20 (1984), 23–53.

[2] F. HÉLEIN, *Willmore immersions and loop groups*, Journal of Differential Geometry, Vol. 50, n. 2 (1998), 331–388.