

Topologies and sheaves on causal manifolds

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Abstract

A causal manifold (M, γ) is a manifold M endowed with a closed proper cone γ in the tangent bundle TM such that the projection $TM \rightarrow M$ is surjective when restricted to $\text{Int}(\gamma)$. Let $\lambda = \gamma^{\circ a} \subset T^*M$ be the antipodal of the polar cone of γ . An open set U of M is called γ -open if its Whitney normal cone contains $\text{Int}\gamma$. Similarly, U is called λ -open if the micro-support of the constant sheaf on U is contained in λ . We begin by proving that the two notions coincide.

Next, we prove that if (M, γ) admits a “future time function” (in particular if it is globally hyperbolic) the functor of direct images establishes an equivalence of triangulated categories between the derived category of sheaves on M micro-supported by λ and the derived category of sheaves on M_γ , the manifold M endowed with the γ -topology. This generalizes a result of [KS90] which dealt with the case of a constant cone in a vector space.

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Introduction

We choose a commutative unital ring $\mathbf{k}$ of finite global dimension and we shall consider sheaves of $\mathbf{k}$ -modules (in the derived setting). Our main reference on this subject is the book [KS90].

Consider first a real finite dimensional vector space $\mathbb{V}$ and a closed convex proper cone $\theta \subset \mathbb{V}$ with vertex at 0. Set $\gamma = \mathbb{V} \times \theta$. The γ -topology was first defined in loc. cit. § 3.5: an open subset V of $\mathbb{V}$ is γ -open if $V = V + \theta$. Denote by $\mathbb{V}_\gamma$ the set $\mathbb{V}$

endowed with the γ -topology and denote by $\varphi_\gamma: \mathbb{V} \rightarrow \mathbb{V}_\gamma$ the continuous map associated with the identity. Denote by $D_{\gamma^{oa}}^b(\mathbf{k}_\mathbb{V})$ the bounded derived category of sheaves on $\mathbb{V}$ micro-supported by γ^{oa} , the antipodal of the polar cone to γ . It is proved in loc. cit. that the functor of direct image $R\varphi_{\gamma*}$ induces an equivalence of this triangulated category with the derived category $D^b(\mathbf{k}_{\mathbb{V}_\gamma})$.

The aim of this paper is to generalize this result to causal manifolds.

There is a vast body of literature on spacetimes and Lorentzian manifolds, particularly concerning the wave equation and its solutions. Usually, such spacetimes are defined through a quadratic form of signature $(+, -, \dots, -)$ but, following [JS16], we prefer a weaker formulation which only makes use of a cone in the tangent space.

A causal manifold (M, γ) is a manifold M endowed with a closed convex proper cone γ in the tangent bundle TM with the property that the projection $\tau_M: TM \rightarrow M$ is surjective when restricted to $\text{Int}(\gamma)$. In other words, for any $x_0 \in M$, $\text{Int}(\gamma_{x_0})$ is non-empty. One also naturally defines the notion of a morphism of causal manifolds.

The γ -topology M_γ on M and the map $\varphi_\gamma: M \rightarrow M_\gamma$ were extended to causal manifolds in [JS16]. A subset Z of M is a γ -set if its Whitney normal cone contains $\text{Int}\gamma$. A γ -open subset is an open subset of M which is a γ -set. Our first result asserts that U is γ -open if and only if $\text{SS}(\mathbf{k}_U)$, the micro-support of the constant sheaf on U , is contained in $\lambda = \gamma^{oa}$, the antipodal of the polar cone to γ .

One can then define the λ -future $L_\lambda^+(x_0)$ of $x_0 \in M$ as the smallest closed subset of M containing x_0 and whose micro-support is contained in λ^a . This set is also the closure of $I_\gamma^+(x_0)$, the smallest γ -set of M containing x_0 . We get two preorders $\preceq_\lambda$ and $\preceq_\gamma$ on M and $x \preceq_\gamma y$ implies $x \preceq_\lambda y$.

Next we introduce the notion of a future time function $q: M \rightarrow \mathbb{R}$, a variant of the classical notion of a time function. This is a causal submersive morphism with the property that, for any $x_0 \in M$, it is proper on the sets $L_\lambda^+(x_0)$ and $q^{-1}q_*(x_0) \cap L_\lambda^+(x_0) = \{x_0\}$. Recall that globally hyperbolic manifolds admit time functions (see [Ger70, MS08, FS11] among others). Also recall that we have used time functions in [JS16] to obtain global propagation results for sheaves whose micro-support satisfy suitable conditions. As a by-product, we globally solve in loc. cit. the Cauchy problem for hyperbolic $\mathcal{D}$ -modules with hyperfunctions solution.

Here, we use future time functions to prove our main result: for a causal manifold (M, γ) endowed with a future time function q , the functor of direct images $R\varphi_{\gamma*}: D_{\gamma^{oa}}^b(\mathbf{k}_M) \rightarrow D^b(\mathbf{k}_{M_\gamma})$ is an equivalence of triangulated categories with quasi-inverse φ_γ^{-1} .

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1 Notations and background

Unless otherwise specified, a manifold means a real C^∞ -manifold and a morphism of manifolds $f: M \rightarrow N$ is a map of class C^∞ .

Vector bundles

Let $p: E \rightarrow M$ be a real (finite-dimensional) vector bundle over M .

- As usual, one denotes by $a: E \rightarrow E$ the antipodal map, $(x; \xi) \mapsto (x; -\xi)$. For a subset $A \subset E$, one sets $A^a = a(A)$.
- A subset γ of E is *conic* (or is a cone) if it is invariant by the action of $\mathbb{R}_{>0}$, that is, $\gamma_x \subset E_x$ is a cone for each $x \in M$. Here, γ_x is the restriction of γ to the fibre E_x . If γ is closed and conic, then its projection by p on M coincides with its intersection with the zero-section of E and we identify the zero-section of E with M .
- A cone γ is proper if γ_x contains no line for any $x \in M$.
- For a cone $\gamma \subset E$, one defines the polar cone $\gamma^\circ \subset E^*$ by

$$(1.1) \quad \gamma_x^\circ = \{\eta \in E_x^*; \langle \eta, \xi \rangle \geq 0 \text{ for all } \xi \in \gamma_x\}.$$

One shall be aware that for a cone $\gamma \subset E$, its closure $\bar{\gamma}$ may be different from the union $\bigcup_{x \in M} \bar{\gamma}_x$ and similarly with its interior $\text{Int}(\gamma)$.

Cotangent bundle

Let M be a real manifold of class C^∞ . We shall use the classical notations below.

- $\tau_M: TM \rightarrow M$ is the tangent bundle, $\pi_M: T^*M \rightarrow M$ the cotangent bundle,
- for N a submanifold of M , $T_N M$ is the normal bundle, $T_N^* M$ the conormal bundle,
- M is identified with $T_M^* M$, (resp. $T_M M$) the zero-section of $T^* M$ (resp. of TM),
- Δ_M , or simply Δ , is the diagonal of $M \times M$,
- for two manifolds M and N one denotes by q_1 and q_2 the first and second projections defined on $M \times N$,
- one denotes by p_1 and p_2 the first and second projections defined on $T^*(M \times N) \simeq T^*M \times T^*N$. One also uses the notation p_2^a for the composition of p_2 and the antipodal map on T^*N .

To a morphism $f: M \rightarrow N$ of manifolds, one associates the maps

$$(1.2) \quad \begin{array}{ccccc} TM & \xrightarrow{f'} & M \times_N TN & \xrightarrow{f_\tau} & TN \\ & \searrow \tau & \downarrow \tau & & \downarrow \tau \\ & & M & \xrightarrow{f} & N, \end{array} \quad \begin{array}{ccccc} T^*M & \xleftarrow{f_d} & M \times_N T^*N & \xrightarrow{f_\pi} & T^*N \\ & \searrow \pi & \downarrow \pi & & \downarrow \pi \\ & & M & \xrightarrow{f} & N. \end{array}$$

We set

$$(1.3) \quad Tf := f_\tau \circ f': TM \rightarrow TN,$$

and call Tf the tangent map to f .

One denotes by Γ_f the graph of f and sets

$$(1.4) \quad \Lambda_f := T_{\Gamma_f}^*(M \times N).$$

Then there is a commutative diagram:

$$(1.5) \quad \begin{array}{ccccc} & & \Lambda_f & & \\ & \swarrow p_1 & \downarrow \sim & \searrow p_2^a & \\ T^*M & \xleftarrow{f_d} & M \times_N T^*N & \xrightarrow{f_\pi} & T^*N. \end{array}$$

Sheaves

We shall mainly follow the notations of [KS90] and use some of the main results of this book. Here, $\mathbf{k}$ denotes a commutative unitary ring with finite global dimension. One denotes by $Derb(\mathbf{k}_M)$ the bounded derived category of sheaves on $\mathbf{k}$ -modules on M and calls an object of this category, a sheaf. For a sheaf F , we shall in particular use its micro-support $SS(F)$, a closed $\mathbb{R}^+$ -conic subset of T^*M .

2 The linear case

Let $\mathbb{V}$ be a finite dimensional real vector space and let θ be a closed convex proper cone with non-empty interior. We set $\gamma = \mathbb{V} \times \theta$.

Let $V \subset \mathbb{V}$ be an open subset of $\mathbb{V}$. Recall, after [KS90, §3.5] with slightly different notations, that V is γ -open if $V = V + \theta$. The family of γ -open subsets of $\mathbb{V}$ defines the γ -topology $\mathbb{V}_\gamma$ on the set $\mathbb{V}$. One denotes by $\varphi_\gamma: \mathbb{V} \rightarrow \mathbb{V}_\gamma$ the continuous map associated with the identity of the set $\mathbb{V}$.

Definition 2.1. Let $\mathbb{V}$ and γ be as above, let U be open in $\mathbb{V}$ and let $x_0 \in \partial U$. We say that U is γ -open in a neighborhood of x_0 if there exists a γ -open set V and an open neighborhood U_0 of x_0 such that $U \cap U_0 = V \cap U_0$.

Lemma 2.2. Let $\mathbb{V}$ and γ be as above. Let U be open in $\mathbb{V}$ and let $x_0 \in \partial U$. Assume that for an open neighborhood U_0 of x_0 , $U_0 \times_{\mathbb{V}} SS(\mathbf{k}_U) \subset U_0 \times \theta^{\circ a}$. Then there exists an open subset W of $\mathbb{V}$ which coincides with U in a neighborhood of x_0 and such that $SS(\mathbf{k}_W) \subset \mathbb{V} \times \theta^{\circ a}$.

Proof. We may assume that $\mathbb{V}$ is the Euclidian space $\mathbb{R}^n$ and $x_0 = 0$. We denote by $B_\varepsilon(x)$ the open ball of center x and radius $\varepsilon > 0$. We may assume that, setting $\xi_0 = (1, 0, \dots, 0)$, $\xi_0 \in \text{Int}(\theta)$. Also set $y_\varepsilon = (\varepsilon, 0, \dots, 0)$ so that x_0 belongs to the boundary of $B_\varepsilon(y_\varepsilon)$. For $\eta \in \mathbb{R}$, set

$$H_\eta = \{x \in \mathbb{V}; x_1 \leq \eta\}, \quad L_\eta = \{x \in \mathbb{V}; x_1 = \eta\}.$$

Let $Z_{\varepsilon, \eta}$ be the lens

$$Z_{\varepsilon, \eta} = B_{\varepsilon+\eta}(y_\varepsilon) \cap H_\eta,$$

and set

$$U_{\varepsilon,\eta} = U \cap Z_{\varepsilon,\eta}.$$

We fix $\varepsilon > 0$. For $0 < \eta < \varepsilon$, $x_0 \in \text{Int} Z_{\varepsilon,\eta}$. Moreover, for η small enough, $\text{SS}(\mathbf{k}_{Z_{\varepsilon,\eta}}) \subset \mathbb{V} \times \theta^{\circ a}$. Since $U_0 \times_{\mathbb{V}} \text{SS}(\mathbf{k}_U) \subset U_0 \times \theta^{\circ a}$, it follows (see [KS90, Prop. 5.4.14]) that for η small enough,

$$\text{SS}(\mathbf{k}_{U_{\varepsilon,\eta}}) \subset \mathbb{V} \times \theta^{\circ a},$$

and $U_{\varepsilon,\eta} = U$ in a neighborhood of x_0 .

Now set

$$W_{\varepsilon,\eta} = \bigcup_{x \in L_{\eta} \cap U} x + \text{Int} \theta.$$

Then $W_{\varepsilon,\eta}$ is open, $\text{SS}(\mathbf{k}_{W_{\varepsilon,\eta}}) \subset \mathbb{V} \times \theta^{\circ a}$ and $U_{\varepsilon,\eta} \cup W_{\varepsilon,\eta}$ satisfies the requested properties.
Q.E.D.

Lemma 2.3. *Let $\mathbb{V}$ and γ be as above and let U be open in $\mathbb{V}$. Then U is γ -open in $\mathbb{V}$ if and only if $\text{SS}(\mathbf{k}_U) \subset \mathbb{V} \times \theta^{\circ a}$.*

Proof. (i) Assume that U is θ -open. Then $N(U)^{\circ} \subset \mathbb{V} \times \theta^{\circ}$ by [KS90, Prop. 5.3.7 (ii)] and thus $\text{SS}(\mathbf{k}_U) \subset \mathbb{V} \times \theta^{\circ a}$ by [KS90, Prop. 5.3.8].

(ii) Assume that $\text{SS}(\mathbf{k}_U) \subset \mathbb{V} \times \theta^{\circ a}$. It follows from [KS90, Prop. 5.2.3] that $\mathbf{k}_U \simeq \varphi_{\theta}^{-1} \text{R} \varphi_{\theta*} \mathbf{k}_U$. By Proposition 3.5.3 (i) of loc. cit., for V open and convex, we have the isomorphism $\Gamma((V + \theta); \text{R} \varphi_{\theta*} \mathbf{k}_U) \simeq \Gamma(V; \varphi_{\theta}^{-1} \text{R} \varphi_{\theta*} \mathbf{k}_U)$. Therefore, $\Gamma((V + \theta); \mathbf{k}_U) \simeq \Gamma(V; \mathbf{k}_U)$, hence $\Gamma((V + \theta); \mathbf{k}_U) \neq 0$ for any open set $V \subset U$. This last condition implies $(V + \theta) \subset U$ hence $U = U + \theta$.
Q.E.D.

Let $\mathbb{V}$ and γ be as above.

Lemma 2.4. *Let $U \subset \mathbb{V}$ be an open subset and let $x_0 \in \partial U$. Then U is γ -open in a neighborhood of x_0 if and only if there exists an open neighborhood W of x_0 such that $W \times_{\mathbb{V}} \text{SS}(\mathbf{k}_U) \subset W \times \theta^{\circ a}$.*

Proof. Since both properties are local on the boundary of U in W , we may assume by Lemma 2.2 that $W = \mathbb{V}$. Then apply Lemma 2.4.
Q.E.D.

Definition 2.5. Let U be a convex open subset of $\mathbb{V}$. One denotes by U_{γ} the set U endowed with the topology induced by $\mathbb{V}_{\gamma}$ and by $\varphi_{U_{\gamma}}: U \rightarrow U_{\gamma}$ the continuous map associated with the identity map of U .

Note that an open subset V of U is open in U_{γ} if and only if $V = (V + \theta) \cap U$. Indeed, if W is open and $V = (W + \theta) \cap U$, then $V \subset (V + \theta) \cap U \subset (W + \theta) \cap U$.

One has a commutative diagram of topological spaces

$$(2.1) \quad \begin{array}{ccc} \mathbb{V} & \xrightarrow{\varphi_{\gamma}} & \mathbb{V}_{\gamma} \\ i_U \uparrow & & \uparrow i_{\gamma} \\ U & \xrightarrow{\varphi_{U_{\gamma}}} & U_{\gamma} \end{array}$$

One shall be aware that U and $\mathbb{V}$ are locally compact spaces Hausdorff contrarily to U_γ and $\mathbb{V}_\gamma$ which are not Hausdorff and the classical results on proper direct images do not apply to these spaces.

Lemma 2.6. *Let U be a convex open subset of $\mathbb{V}$. The functor $\varphi_{U_\gamma}^{-1}: D^b(\mathbf{k}_{U_\gamma}) \rightarrow D^b(\mathbf{k}_U)$ takes its values in $D_{U \times \theta^{\circ a}}^b(\mathbf{k}_U)$.*

Proof. Let $G \in D^b(\mathbf{k}_{U_\gamma})$. Consider Diagram (2.1). Then

$$\varphi_{U_\gamma}^{-1}G \simeq \varphi_{U_\gamma}^{-1}i_\gamma^{-1}\mathrm{R}i_{\gamma*}G \simeq i_U^{-1}\varphi_\gamma^{-1}(\mathrm{R}i_{\gamma*}G).$$

Since $\mathrm{SS}(\varphi_\gamma^{-1}(\mathrm{R}i_{\gamma*}G)) \subset \mathbb{V} \times \theta^{\circ a}$ by [KS90, Prop. 5.2.3], we get the result. Q.E.D.

Proposition 2.7. *Let U be a convex open subset of $\mathbb{V}$. The functor $\mathrm{R}\varphi_{U_\gamma*}: D_{U \times \theta^{\circ a}}^b(\mathbf{k}_U) \rightarrow D^b(\mathbf{k}_{U_\gamma})$ is an equivalence of triangulated categories with quasi-inverse $\varphi_{U_\gamma}^{-1}$.*

When $U = \mathbb{V}$, this result is an immediate consequence of [KS90, Prop. 3.5.3, Prop. 5.2.3]. A careful reading of these propositions shows that the proofs extend verbatim to the case where $\mathbb{V}$ is replaced with a convex open subset.

Note that we shall not use Proposition 2.7 and that Theorem 5.5 will generalize it.

3 Topologies on causal manifolds

Causal manifolds

Consider first a real manifold M (of class C^∞) endowed with a closed convex proper cone $\gamma \subset TM$ containing the zero-section.

Definition 3.1. (a) A causal manifold (M, γ) is a manifold M equipped with a closed convex proper cone $\gamma \subset TM$ with the property that the projection $\tau_M: \mathrm{Int}(\gamma) \rightarrow M$ is surjective.

- (b) To a causal manifold (M, γ) one associates the cone $\lambda = \gamma^{\circ a} \subset T^*M$.
- (c) A morphism of causal manifolds $f: (M, \gamma_M) \rightarrow (N, \gamma_N)$ is a morphism of manifolds $f: M \rightarrow N$ such that the map $Tf: TM \rightarrow TN$ satisfies $Tf(\gamma_M) \subset \gamma_N$.
- (d) Equivalently, a morphism of causal manifolds $f: (M, \lambda_M) \rightarrow (N, \lambda_N)$ is a morphism of manifolds $f: M \rightarrow N$ such that $f_d f_\pi^{-1} \lambda_N \subset \lambda_M$.
- (e) For I an open interval of $\mathbb{R}$, we denote by $(I, +)$ the causal manifold (I, γ) where $\gamma = \{(t; v) \in TI; v \geq 0\}$.

The equivalence of (c) and (d) is proved in [JS16, Prop. 1.12].

Also note that the cone λ satisfies

$$(3.1) \quad \lambda \cap \lambda^a = M, \quad \lambda + \lambda = \lambda.$$

Definition 3.2. (i) A constant cone contained in γ is a triple (φ, U, θ) where U is open in M , $\varphi: U \rightarrow \mathbb{R}^d$ is a chart, $\theta \subset \mathbb{R}^d$ is a closed convex proper cone with non-empty interior such that in this chart $U \times \theta \subset \gamma$ (that is, $\varphi(U) \times \theta \subset T\varphi(U \times_M \gamma)$). A constant cone (φ, U, θ) will often simply be denoted by $U \times \theta$.

(ii) A *basis of constant cones* for γ is a family of constant cones $\{U_i \times \theta_i\}_i$ contained in γ such that $\bigcup_i U_i = M$ and for any $x_0 \in M$, $\text{Int}(\gamma_{x_0}) = \bigcup_{x_0 \in U_i} \theta_i$.

Remark 3.3. For a constant cone (φ, U, θ) , we shall often identify U with its image by φ in $\mathbb{R}^d$.

One shall be aware that in [JS16, Def 1.13] the cone γ was open.

Lemma 3.4. *Let (M, γ) be a manifold M equipped with a closed convex proper cone $\gamma \subset TM$. Then (M, γ) is a causal manifold if and only if there exists a basis of constant cones.*

Proof. (i) Assume that there exists a basis of constant cones $\{U_i \times \theta_i\}_i$. Then $\text{Int}(\gamma_{x_0}) \neq \emptyset$ since $\bigcup_i U_i = M$, $\text{Int}(\gamma_{x_0}) = \bigcup_{x_0 \in U_i} \theta_i$ and θ_i has non-empty interior.

(ii) Conversely, assume that $\text{Int}(\gamma_{x_0}) \neq \emptyset$ for all $x_0 \in M$. We may assume that M is open in $\mathbb{R}^d$. Then for any open convex cone θ with $\bar{\theta} \subset \text{Int}(\gamma_{x_0})$, there exists an open neighborhood U of x_0 such that $U \times \theta \subset \text{Int}(\gamma)$. Q.E.D.

γ -topology

Let (M, γ) be a causal manifold and recall that we have set $\lambda = \gamma^{\circ a}$.

For two subsets $A, B \subset M$ and $x \in M$, the normal cone $C_x(A, B) \subset T_x X$ is defined in [KS90, Def 4.1.1]. In a local coordinate system

$$(x_0; v_0) \in C_{x_0}(A, B) \Leftrightarrow \text{there exists a sequence } \{(x_n, y_n, c_n)\}_n \subset A \times B \times \mathbb{R}^+ \\ \text{with } c_n(x_n - y_n) \xrightarrow{n} v_0, x_n \xrightarrow{n} x_0, y_n \xrightarrow{n} x_0.$$

The strict normal cone $N(A) \subset TM$ is defined in [KS90, Def 5.3.6] by

$$N_x(A) = T_x X \setminus C_x(M \setminus A, A), \\ N(A) = \bigcup_{x \in M} N_x(A).$$

The cone $N(A)$ is open and convex.

Definition 3.5 ([JS16, Def 1.18]). Let (M, γ) be a causal manifold.

(a) A subset $A \subset M$ is a γ -set if $\gamma \subset N(A)$.

(b) A subset $U \subset M$ is γ -open if it is both an open subset and a γ -set.

It follows from [KS90, (5.3.3)] that

$$(3.2) \quad A \text{ is a } \gamma\text{-set} \Leftrightarrow \begin{cases} \text{there exists a basis of constant cones } U \times \theta \text{ for } \gamma \\ \text{such that } U \cap (U \cap A + \text{Int}\theta) \subset A. \end{cases}$$

Remark that the property of being γ -open is a local property on the boundary ∂U .

One needs to check that this definition is in accordance with the previous definition of § 2.

Lemma 3.6. *Assume that $M = \mathbb{V}$ is a finite dimensional vector space and $\gamma = \mathbb{V} \times \theta$ for an open convex proper cone θ with non-empty interior. Then an open subset $U \subset \mathbb{V}$ is γ -open if and only if $U = U + \theta$.*

Proof. (i) Assume that $U = U + \theta$. Let us choose $U \times \theta$ as a basis of constant cones. Then $U = U + \text{Int}\theta$. Therefore, U is γ -open by (3.2).

(ii) Conversely, assume that U is γ -open. This implies that for any $x_0 \in \partial U$ and any closed convex cone $\lambda \subset \text{Int}\theta$, there exists an open neighborhood V of x_0 such that $V \cap (V \cap U + \lambda) \subset U$. Hence, $U = U + \lambda$ for any any closed convex cone $\lambda \subset \text{Int}\theta$, which implies $U = U + \theta$. Q.E.D.

Proposition 3.7 ([JS16, Prop 1.19, 1.21]). *Let (M, γ) be a causal manifold.*

- (i) *A set A is a γ -set if and only if $\gamma_x \subset N_x(A)$ for every $x \in \partial A$.*
- (ii) *A set A is a γ -set if and only if $M \setminus A$ is a γ^a -set.*
- (iii) *The family of γ -sets is closed under arbitrary unions and intersections.*
- (iv) *The family of γ -sets is closed under taking closure and interior.*
- (v) *If A is a γ -set, then $\overline{\text{Int}A} = \overline{A}$ and $\text{Int}\overline{A} = \text{Int}A$.*
- (vi) *If A is a γ -set and $\text{Int}A \subset B \subset \overline{A}$, then B is a γ -set.*

The γ -topology on M was first defined in [KS90, § 3.5] when $M = \mathbb{V}$ is a vector space and $\gamma = M \times \theta$ for a closed convex cone $\theta \subset \mathbb{V}$.

Definition 3.8 ([KS90, § 3.5] and [JS16, Def 1.23]). *Let (M, γ) be a causal manifold.*

- (a) *The γ -topology on M is the topology for which the open sets are the γ -open sets.*
- (b) *One denotes by M_γ the space M endowed with the γ -topology and by $\varphi_\gamma: M \rightarrow M_\gamma$ the continuous map associated with the identity of the set M .*

One shall be aware that the closed sets for the γ -topology are not γ -sets in general. They are γ^a -sets. That is why it is better to avoid the terminology “a closed γ -set” whose meaning could be a set which is closed for the γ -topology as well as a closed set which is a γ -set.

Remark 3.9. When $\mathbb{V}$ is a vector space, $U \subset \mathbb{V}$ is a convex open subset and θ is a closed convex proper cone, Definition 3.8 gives $U_\theta = U_{U \times \theta}$ and $\varphi_{U_\theta} = \varphi_{U \times \theta}$. As far as there is no risk of confusion, we keep the notations U_θ and φ_θ .

γ -topology and λ -topology

Definition 3.10. Let (M, γ) be a causal manifold and let $\lambda = \gamma^{\circ a}$.

- (a) A locally closed set $A \subset M$ is a λ -set if $\text{SS}(\mathbf{k}_A) \subset \lambda$.
- (b) A λ -open set (resp. a λ -closed set) is an open set (resp. a closed set) which is also a λ -set.

Note that U is λ -open if and only if $M \setminus U$ is λ -closed.

Remark 3.11. In [JS16, Not. 1.10] we have set $\lambda = \gamma^\circ$, contrarily to the above notation.

Proposition 3.12. Let (M, γ) be a causal manifold.

- (a) The family of λ -open sets is closed under arbitrary unions and finite intersections. In particular, the family of λ -open subsets of M defines a topology on M .
- (b) Similarly, the family of λ -closed sets is closed under arbitrary intersections and finite unions.

Proof. Since an open set U is λ -open if and only if $M \setminus U$ is λ -closed, it is enough to prove (a).

(i) If U_1 and U_2 are λ -open, so is $U_1 \cap U_2$ since $\mathbf{k}_{U_1 \cap U_2} \simeq \mathbf{k}_{U_1} \otimes \mathbf{k}_{U_2}$ and $\text{SS}(\mathbf{k}_{U_1} \otimes \mathbf{k}_{U_2}) \subset \lambda$ by (3.1).

(ii) If U_1 and U_2 are λ -open, so is $U_1 \cup U_2$. This follows from (i) and the distinguished triangle $\mathbf{k}_{U_1 \cap U_2} \rightarrow \mathbf{k}_{U_1} \oplus \mathbf{k}_{U_2} \rightarrow \mathbf{k}_{U_1 \cup U_2} \xrightarrow{+1}$.

(iii) Let $\{U_i\}_{i \in I}$ be a family of λ -open subsets. Let us order I by the relation $i \leq j$ if $U_i \subset U_j$. We may assume that I is non empty and by (ii) we may assume that $(I, \leq)$ is directed. It then follows from [KS90, Exe. 5.7] that, setting $U = \bigcup_{i \in I} U_i$, $\text{SS}(\mathbf{k}_U) \subset \lambda$.

(iv) Since $\text{SS}(\mathbf{k}_M) = T_M^* M \subset \lambda$ and $\text{SS}(\mathbf{k}_\emptyset) = \emptyset$, both M and $\emptyset$ are λ -open and the proof is complete. Q.E.D.

Theorem 3.13. Let (M, γ) be a causal manifold and recall that we have set $\lambda = \gamma^{\circ a}$.

- (a) An open set U of M is a γ -set if and only if it is a λ -set.
- (b) A closed subset Z of M is a γ^a -set if and only if it is a λ -set. In particular, a closed λ -set is closed for the γ -topology.

Proof. (a)–(i) We know by [KS90, Prop. 5.3.8] that $\text{SS}(\mathbf{k}_U) \subset N(U)^{\circ a}$. If U is a γ -set, then $\text{Int} \gamma \subset N(U)$ and thus $\text{SS}(\mathbf{k}_U) \subset N(U)^{\circ a} \subset \gamma^{\circ a} = \lambda$.

(a)–(ii) Now assume that $\text{SS}(\mathbf{k}_U) \subset \gamma^{\circ a}$. The problem is local on M and we may assume that M is open in a vector space $\mathbb{V}$. Let $U \subset M$ be an open subset and assume that $\text{SS}(\mathbf{k}_U) \subset \lambda$. Let W be an open and convex set and θ a open convex cone with $W \times_M \lambda \subset W \times \theta^{\circ a}$. Then $U \cap W$ is γ -open by Lemma 2.4. It follows that U is γ -open by (3.2).

(b) Set $U = M \setminus Z$. Then Z is a λ -set if and only if so is U . On the other-hand, U is a γ -set if and only if Z is a γ^a -set. Q.E.D.

Definition 3.14. Let (M, γ) be a causal manifold. The λ -topology on M is the topology for which the open sets are the λ -open sets. Hence, the closed sets are the closed λ^a -sets.

It follows from Theorem 3.13 that the γ -topology and the λ -topology coincide.

4 Preorders on causal manifolds

Preorders

Consider a preorder $\preceq$ on a manifold M and its graph $\Delta_{\preceq} \subset M \times M$. Then

$$\Delta \subset \Delta_{\preceq} \quad \Delta_{\preceq} \circ \Delta_{\preceq} = \Delta_{\preceq}.$$

For a subset $A \subset M$, one sets

$$(4.1) \quad \begin{cases} J_{\preceq}^+(A) = q_2(q_1^{-1}(A) \cap \Delta_{\preceq}) = \{x \in M; \text{ there exists } y \in A \text{ with } y \preceq x\}, \\ J_{\preceq}^-(A) = q_1(q_2^{-1}(A) \cap \Delta_{\preceq}) = \{x \in M; \text{ there exists } y \in A \text{ with } x \preceq y\}. \end{cases}$$

For $x \in M$, we write $J_{\preceq}^+(x)$ and $J_{\preceq}^-(x)$ instead of $J_{\preceq}^+(\{x\})$ and $J_{\preceq}^-(\{x\})$ respectively. One calls $J_{\preceq}^+(A)$ the future of A and $J_{\preceq}^-(A)$ the past of A (for the preorder $\preceq$).

Note that $J_{\preceq}^+(A) = \bigcup_{x \in A} J_{\preceq}^+(x)$ and $J_{\preceq}^-(A) = \bigcup_{x \in A} J_{\preceq}^-(x)$.

By its definition, one has

$$(4.2) \quad \Delta_{\preceq} = \bigcup_{x \in M} J_{\preceq}^-(x) \times J_{\preceq}^+(x) = \bigcup_{x \in M} \{x\} \times J_{\preceq}^+(x).$$

Definition 4.1. Let $\preceq$ be a preorder on M .

- (a) The preorder is closed if $\Delta_{\preceq}$ is closed in $M \times M$.
- (b) The preorder is proper if q_{13} is proper on $\Delta_{\preceq} \times_M \Delta_{\preceq}$. Equivalently, the preorder is proper if for any two compact subsets A and B of M , the so-called causal diamond $J_{\preceq}^+(A) \cap J_{\preceq}^-(B)$ is compact.

If the preorder $\preceq$ is closed, then for any compact subset A of M the sets $J_{\preceq}^-(A)$ and $J_{\preceq}^+(A)$ are closed. If the preorder is proper, then it is closed. A preorder is proper as soon as $J_{\preceq}^+(x) \cap J_{\preceq}^-(y)$ is compact for any two $x, y \in M$.

The γ -preorder

This subsection is, with some modifications, extracted from [JS16, § 1.4].

Let (M, γ) be a causal manifold.

Definition 4.2. For $A \subset M$, we denote by $I_{\gamma}^+(A)$ the intersection of all the γ -sets which contain A and call it the γ -future of A . We set $I_{\gamma}^+(x) = I_{\gamma}^+(\{x\})$.

Note that a set A is a γ -set if and only if $I_{\gamma}^+(A) = A$.

Let us set

$$x \preceq_{\gamma} y \text{ if and only if } y \in I_{\gamma}^+(x).$$

Lemma 4.3. (a) *The relation $x \preceq_\gamma y$ is a preorder.*

(b) *For $A \subset M$, $I_\gamma^+(A) = \bigcup_{x \in A} I_\gamma^+(x)$. In other words, with the preceding notations, $I_\gamma^+(A) = J_{\preceq_\gamma}^+(A)$.*

Proof. (a) Let $y \in I_\gamma^+(x)$ and $z \in I_\gamma^+(y)$. Then $I_\gamma^+(x)$ is a γ -set which contains y and $I_\gamma^+(y)$ is the smallest γ -set which contains y . Therefore, $I_\gamma^+(y) \subset I_\gamma^+(x)$ and $z \in I_\gamma^+(x)$.
(b) The term on the right-hand side is a γ -set, contains A and is contained in $I_\gamma^+(A)$ (since $I_\gamma^+(x) \subset I_\gamma^+(A)$ for $x \in A$), whence the equality. It follows that $y \in I_\gamma^+(A)$ if and only if there exists $x \in A$ such that $x \preceq_\gamma y$. Q.E.D.

According to (4.1), one has

$$(4.3) \quad \begin{aligned} I_\gamma^+(x) &= J_{\preceq_\gamma}^+(x), \\ J_{\preceq_\gamma}^-(y) &= \bar{J}_{\preceq_\gamma}^-(\{y\}) := \{x; x \preceq_\gamma y\}, \quad \bar{J}_{\preceq_\gamma}^-(A) = \bigcup_{y \in A} \bar{J}_{\preceq_\gamma}^-(y). \end{aligned}$$

Remark 4.4. Recall the causal manifold $(I, +)$ of Definition 3.1 (e). On $(I, +)$ the preorder $\preceq_\gamma$ is the usual order $\leq$.

Proposition 4.5. *Let $A \subset M$ be a closed subset of M . Then $I_\gamma^+(A) \setminus A$ is open.*

Proof. One has $\text{Int}(I_\gamma^+(A)) \subset \text{Int}(I_\gamma^+(A)) \cup A \subset I_\gamma^+(A)$. Applying Proposition 3.7 (iv), we get that $\text{Int}(I_\gamma^+(A)) \cup A$ is a γ -set. Since it contains A , it contains $I_\gamma^+(A)$. Therefore $\text{Int}(I_\gamma^+(A)) \cup A = I_\gamma^+(A)$ and $I_\gamma^+(A) \setminus A = \text{Int}(I_\gamma^+(A)) \setminus A$ is open. Q.E.D.

Corollary 4.6. *Let U be open in M . Then $I_\gamma^+(U)$ is γ -open.*

Proof. One has $I_\gamma^+(U) = \bigcup_{x \in U} (I_\gamma^+(x) \setminus \{x\}) \cup U$. Q.E.D.

Definition 4.7. (a) Let $I = [0, 1]$. If a function $c: I \rightarrow M$ is left (resp. right) differentiable, we denote its left (resp. right) differential by c'_l (resp. c'_r).

(b) A path $c: I \rightarrow M$ is a piecewise smooth map.

(c) A path c is causal if $c'_l(t), c'_r(t) \in \gamma_{c(t)}$ for any $t \in I$ and is strictly causal if $c'_l(t), c'_r(t) \in (\text{Int}\gamma)_{c(t)}$ for any $t \in I$.

Note that if c_1 and c_2 are two causal (resp. strictly causal) paths on I with $c_1(1) = c_2(0)$, the concatenation $c = c_1 \cup c_2$ (defined by glueing the two paths as usual) is causal (resp. strictly causal).

The next result is obvious (see also [JS16, Lem. 1.30]).

Lemma 4.8. *Let (M, γ) be a causal manifold and consider a constant cone $U \times \theta$ contained in γ . Then, for $y, z \in U$ with $z - y \in \theta$, we have $z \in I_\gamma^+(y)$.*

Lemma 4.9 (see [JS16, Lem. 1.34]). *Let $c: I \rightarrow M$ be a strictly causal path. Then for $t_1 \leq t_2$ with $t_1, t_2 \in I$ we have $c(t_1) \preceq_\gamma c(t_2)$.*

Proof. It is enough to prove that for any $t_0 \in I$, there exists $\alpha > 0$ such that $c(t_0) \preceq_\gamma c(t)$ for $t \in (t_0, t_0 + \alpha)$ and similarly $c(t) \preceq_\gamma c(t_0)$ for $t \in (t_0 - \alpha, t_0)$. We may assume $t_0 = 0$. There exists a constant cone $U \times \theta$ contained in γ and containing $(c(0), c'_r(0))$. There exists $\alpha > 0$ such that $c(t) - c(0) \in \theta$ for $t \in (0, \alpha)$. By Lemma 4.8, this implies $c(0) \preceq_\gamma c(t)$ for $t \in (0, \alpha)$. The other case is similar, using $c'_l(0)$. Q.E.D.

Proposition 4.10 (see [JS16, Lem. 1.35]). *Let $A \subset M$. One has $y \in I_\gamma^+(A)$ if and only if $y \in A$ or there exists a strictly causal path $c: I \rightarrow M$ such that $c(0) \in A$, $c(1) = y$.*

Proof. Let B be the union of A with the set of points that can be reached from A by a strictly causal path. We shall prove that $I_\gamma^+(A) = B$.

(i) To prove that $B \supset I_\gamma^+(A)$, it is enough to check that B is a γ -set. Choose a constant cone $U \times \theta$ contained in γ with U convex. By (3.2), it is enough to prove that $U \cap (B \cap U + \theta) \subset B$. Let $y' \in B \cap U$ and $v' \in \theta$ with $y' + v' \in U$. Since U is convex, $c: I \rightarrow U, t \mapsto y' + tv'$ is a strictly causal path for I a small enough neighborhood of $[0, 1]$. Since $y' \in B$, there exists a strictly causal path $\tilde{c}$ with $\tilde{c}(0) \in A$ and $\tilde{c}(1) = y'$. Therefore, concatenating $\tilde{c}$ and c proves that $y' + v' \in B$.

(ii) Let us prove that $B \subset I_\gamma^+(A)$. Let $y \in B, y \notin A$. There exist $x \in A$ and a strictly causal curve c going from x to y . Then $y \in I_\gamma^+(x)$ by Lemma 4.9. Hence, $y \in I_\gamma^+(A)$. Q.E.D.

Corollary 4.11 (see [JS16, Lem. 1.41]). *One has $J_{\preceq_\gamma}^-(y) = I_{\gamma^a}^+(y)$.*

Proof. This follows immediately from Proposition 4.10. Q.E.D.

The λ -preorder

Let (M, γ) be a causal manifold. Recall that $\lambda = \gamma^{\circ a}$.

Definition 4.12. (a) For $A \subset M$, we denote by $L_\lambda^+(A)$ the intersection of all closed λ^a -sets which contain A :

$$L_\lambda^+(A) = \bigcap \{Z \mid A \subset Z \text{ and } Z \text{ is a closed } \lambda^a\text{-set}\}.$$

(b) For $x \in M$, we set $L_\lambda^+(x) = L_\lambda^+(\{x\})$.

In other words, $L_\lambda^+(A)$ is the closure of A for the λ -topology, hence, for the γ -topology. In particular, $L_\lambda^+(A) = L_\lambda^+(\bar{A})$. Let us set

$$x \preceq_\lambda y \text{ if and only if } y \in L_\lambda^+(x).$$

Lemma 4.13. *The relation $x \preceq_\lambda y$ is a preorder.*

Proof. If $y \in L_\lambda^+(x)$, then $L_\lambda^+(y) \subset L_\lambda^+(x)$. Indeed, $L_\lambda^+(x)$ is a closed λ^a -set which contains y . Hence, it contains $L_\lambda^+(y)$. Q.E.D.

Notation 4.14. We call $\preceq_\gamma$ the γ -preorder and $\preceq_\lambda$ the λ -preorder.

According to (4.1), one has

$$(4.4) \quad \begin{aligned} J_{\preceq_\gamma}^+(x) &= I_\gamma^+(x) \\ J_{\preceq_\lambda}^-(y) &= J_{\preceq_\lambda}^-(\{y\}) := \{x; x \preceq_\lambda y\}, \quad J_{\preceq_\lambda}^-(A) = \bigcup_{y \in A} J_{\preceq_\lambda}^-(y). \end{aligned}$$

Proposition 4.15. *For $A \subset M$, one has $L_\lambda^+(A) = \overline{I_\gamma^+(A)}$. In particular, for $x, y \in M$, $L_\lambda^+(x) = \overline{I_\gamma^+(x)}$ and $x \preceq_\gamma y$ implies $x \preceq_\lambda y$.*

Proof. (i) Let us prove the inclusion $\overline{I_\gamma^+(A)} \subset L_\lambda^+(A)$. The closed set $L_\lambda^+(A)$ contains A and being a λ^a -set, it is a γ -set by Theorem 3.13. Therefore, $I_\gamma^+(A) \subset L_\lambda^+(A)$ and the result follows.

(ii) Let us prove the inclusion $L_\lambda^+(A) \subset \overline{I_\gamma^+(A)}$. The closed set $\overline{I_\gamma^+(A)}$ is a γ -set by Proposition 3.7, hence a λ^a -set by Theorem 3.13. Q.E.D.

Corollary 4.16. *One has $\bigcup_{x \in A} L_\lambda^+(x) = L_\lambda^+(A)$.*

Proof. (i) The inclusion $L_\lambda^+(x) \subset L_\lambda^+(A)$ implies the inclusion $\subset$ in the statement.

(ii) The left-hand side is a γ -set thanks to Propositions 3.7 and 4.15. It is thus a λ^a -set by Theorem 3.13. Therefore, it contains $L_\lambda^+(A)$ by Definition 4.12. Q.E.D.

In the sequel, we set $\Delta_\gamma = \Delta_{\preceq_\gamma}$ and $\Delta_\lambda = \Delta_{\preceq_\lambda}$.

Corollary 4.17. *One has*

$$\Delta_\gamma = I_{\gamma^a \times \gamma}^+(\Delta) \subset \Delta_\lambda \subset L_{\lambda^a \times \lambda}^+(\Delta) = \overline{\Delta_\gamma}.$$

Proof. (i) $I_{\gamma^a \times \gamma}^+(\Delta) \subset \Delta_\gamma$. Since Δ_γ contains the diagonal, it is enough to prove that it is a $(\gamma^a \times \gamma)$ -set. Each $I_{\gamma^a}^+(x) \times I_\gamma^+(y)$ is a $(\gamma^a \times \gamma)$ -set by [JS16, Prop. 1.19 (iii)]. By using (4.2) we get the result by Proposition 3.7.

(ii) $\Delta_\gamma \subset I_{\gamma^a \times \gamma}^+(\Delta)$. Let $(x, y) \in \Delta_\gamma$, that is $x \preceq_\gamma y$. By Proposition 4.10, there exists a strictly causal path $c: I \rightarrow M$ with $c(0) = x$ and $c(1) = y$. Consider the path $\tilde{c} = (c_1, c_2): I \rightarrow M \times M$ given by $c_1(t) = c(1-t)$ and $c_2(t) = c(t)$. Then $\tilde{c}$ is a strictly causal path in $(M \times M, \gamma^a \times \gamma)$. Since $\tilde{c}(1/2, 1/2) \in \Delta$, we get by Proposition 4.10 that $(x, y) \in I_{\gamma^a \times \gamma}^+(\Delta)$.

(iii) $\Delta_\gamma \subset \Delta_\lambda$ by Proposition 4.15.

(iv) $L_{\lambda^a \times \lambda}^+(\Delta) = \overline{I_{\gamma^a \times \gamma}^+(\Delta)}$ by Proposition 4.15. Hence, $L_{\lambda^a \times \lambda}^+(\Delta) = \overline{\Delta_\gamma}$ by (i)–(ii).

(v) $\Delta_\lambda \subset L_{\lambda^a \times \lambda}^+(\Delta)$. Indeed, $\Delta_\lambda = \bigcup_x (\{x\} \times L_\lambda^+(x))$ by (4.2). Since $\{x\} \times L_\lambda^+(x) = \overline{\{x\} \times I_\gamma^+(x)}$, we get $\{x\} \times L_\lambda^+(x) \subset \overline{\Delta_\gamma}$. Q.E.D.

Remark 4.18. One has $y \in I_\gamma^+(x) \Leftrightarrow x \in I_{\gamma^a}^+(y)$ and $y \in L_\lambda^+(x) \Leftrightarrow y \in \overline{I_\gamma^+(x)}$.

However, the equivalence $y \in \overline{I_\gamma^+(x)} \Leftrightarrow x \in \overline{I_{\gamma^a}^+(y)}$ is false, as shown by the following example well-known to specialists of the field. .

Example 4.19. Let (x_1, x_2) be the coordinates on $\mathbb{R}^2$, $Z = \{(x_1, x_2); x_1 \leq 0, x_2 = 0\}$, $M = \mathbb{R}^2 \setminus Z$. Let $\theta \subset \mathbb{R}^2$ be the closed cone $\theta = \{(x_1, x_2); x_2 \geq |x_1|\}$ and let $\gamma = M \times \theta \subset TM$. Now let $x = (-1, -1) \in M$, $y = (1, 1) \in M$. Then

$$x \in L_{\lambda^a}^+(y) \text{ but } y \notin L_\lambda^+(x).$$

To check this point, use Propositions 4.15 and 4.10

Future time functions

Definition 4.20 is a variation on [JS16, Def. 1.50]. The terminology G-causal below is inspired by the name of Geroch.

- Definition 4.20.** (a) A future time function on a causal manifold (M, γ) is a surjective and submersive causal morphism $q: (M, \gamma) \rightarrow (\mathbb{R}, +)$ which is proper on the sets $L_\lambda^+(K)$ for all compact subsets K of M .
- (b) A future time function q is strict if for any $x_0 \in M$, setting $t_0 = q(x_0)$, the family $\{I_\gamma^+(U) \cap q^{-1}(t_0 - a, t_0 + a)\}_{U,a}$ is a neighborhood system of x_0 when U ranges over a neighborhood system of x_0 and $a \in \mathbb{R}_{>0}$.
- (c) A G^+ -causal manifold (M, γ, q) is a causal manifold endowed with a strict future time function q .

A time function is a function q which is a future time function both for γ and γ^a .

We do not recall here the definition of a globally hyperbolic spacetime and its links with that of G-causal manifold. It is known, after the works (among others) of [Ger70, MS08, FS11] that a globally hyperbolic manifold admits time functions.

Lemma 4.21. *Let (M, γ) be a causal manifold and q a future time function. Then*

- (a) *the function q is strictly causal,*
- (b) *$x \preceq_\gamma y$ implies $q(x) \leq q(y)$.*

Proof. (a) follows from [JS16, Prop. 1.9] and (b) from loc. cit. Lemma 1.46. Q.E.D.

5 An equivalence

Micro-support of inverse images

Let (M, γ) be a causal manifold and consider a constant cone (U, θ) contained in γ . We denote by U_γ the set U endowed with the topology induced by M_γ . We write U_θ instead of $U_{U \times \theta}$ and φ_θ instead of $\varphi_{U \times \theta}$.

We get the commutative diagram of topological spaces:

$$(5.1) \quad \begin{array}{ccccc} U & \xrightarrow{\varphi_\theta} & U_\theta & \xrightarrow{\rho} & U_\gamma \\ i_U \downarrow & & & & i_{U_\gamma} \downarrow \\ M & \xrightarrow{\varphi_\gamma} & & & M_\gamma. \end{array}$$

Thanks to Lemma 2.6, it gives rise to the commutative diagram

$$(5.2) \quad \begin{array}{ccccccc} D^b(\mathbf{k}_M) & \xleftarrow{\varphi_\gamma^{-1}} & & & D^b(\mathbf{k}_{M_\gamma}) \\ i_U^{-1} \downarrow & & & & \downarrow i_{U_\gamma}^{-1} \\ D^b(\mathbf{k}_U) & \xleftarrow{\iota} & D^b_{U \times \theta^{\circ a}}(\mathbf{k}_U) & \xleftarrow{\varphi_\theta^{-1}} & D^b(\mathbf{k}_{U_\theta}) & \xleftarrow{\rho^{-1}} & D^b(\mathbf{k}_{U_\gamma}) \end{array}$$

Proposition 5.1. *Let (M, γ) be a causal manifold. The functor $\varphi_\gamma^{-1}: D^b(\mathbf{k}_{M_\gamma}) \rightarrow D^b(\mathbf{k}_M)$ takes its values in $D_{\gamma^{\circ a}}^b(\mathbf{k}_M)$.*

Proof. The problem is local on M and we may assume that M is open in a vector space. Consider a constant cone (U, θ) contained in γ with U convex so that we may apply Lemma 2.6. Then

$$(5.3) \quad i_U^{-1} \circ \varphi_\gamma^{-1} \simeq \iota \circ \varphi_\theta^{-1} \circ \rho^{-1} \circ i_{U_\gamma}^{-1}$$

It follows that for $G \in D^b(\mathbf{k}_{M_\gamma})$, $\text{SS}(\varphi_\gamma^{-1}G|_U) \subset U \times \theta^{\circ a}$.

Let $(x_0; \xi_0) \in \text{SS}(G)$. There exists a family of constant cones $\{(U_i \times \theta_i)\}_i$ such that $\text{Int}_{\gamma_{x_0}} = \bigcup_i \theta_i$. Hence, $\gamma_{x_0}^{\circ a} = \bigcap_i \theta_i^{\circ a}$ in $T_{x_0}^*M$. Since $(x_0; \xi_0) \in \{x_0\} \times \theta_i^{\circ a}$ for all i , we get that $(x_0; \xi_0) \in \gamma_{x_0}^{\circ a}$. Q.E.D.

Full faithfulness of direct image

Recall that for $x_0 \in M$, the set $L_\lambda^+(x_0)$ is λ^a -closed hence is closed for the γ -topology,

Lemma 5.2. *Let (M, γ, q) be a G^+ -causal manifold and let $F \in D_{\gamma^{\circ a}}^b(\mathbf{k}_M)$. Let $x_0 \in M$, $t_0 = q(x_0)$. Let $a > 0$ and let U be an open relatively compact neighborhood of x_0 such that $q(U) \subset (t_0 - a, t_0 + a)$. Then $\text{R}\Gamma(I_\gamma^+(U); F) \xrightarrow{\simeq} \text{R}\Gamma(I_\gamma^+(U) \cap q^{-1}(t_0 - a, t_0 + a); F)$.*

Proof. (i) Set $U^+ = I_\gamma^+(U)$, $G = \text{R}q_*\text{R}\Gamma_{U^+}F$. Note that, by the hypotheses, the function q is proper on $\overline{I_\gamma^+(U)}$. Moreover, it is increasing for the order $\preceq_\gamma$ by Lemma 4.21, hence $q(U^+) \subset [t_0 - a, +\infty)$.

(ii) The set U^+ being a γ -open subset, we get $\text{SS}(\text{R}\Gamma_{U^+}F) \subset \lambda$. Since q is proper on $\text{supp}(\text{R}\Gamma_{U^+}F)$, $\text{SS}(G) \subset \{(t; \tau); t \geq t_0 - a, \tau \leq 0\}$ and it follows that $\text{R}\Gamma(\mathbb{R}; G) \simeq \text{R}\Gamma((t_0 - a, +\infty); G) \xrightarrow{\simeq} \text{R}\Gamma((t_0 - a, t_0 + a); G)$.

(iii) One has $\text{R}\Gamma(I_\gamma^+(U); F) \simeq \text{R}\Gamma(M; \text{R}\Gamma_{U^+}F) \simeq \text{R}\Gamma(\mathbb{R}; G)$ and $\text{R}\Gamma((t_0 - a, t_0 + a); G) \simeq \text{R}\Gamma(I_\gamma^+(U) \cap q^{-1}(t_0 - a, t_0 + a); F)$. Q.E.D.

Proposition 5.3. *Let (M, γ, q) be a G^+ -causal manifold. Then the functor $\text{R}\varphi_{\gamma_*}: D_{\gamma^{\circ a}}^b(\mathbf{k}_M) \rightarrow D^b(\mathbf{k}_{M_\gamma})$ is fully faithful,*

Proof. It is enough to prove the isomorphisms for all $j \in \mathbb{Z}$ and $x_0 \in M$

$$H^j(\varphi_\gamma^{-1}\text{R}\varphi_{\gamma_*}F)_{x_0} \xrightarrow{\simeq} H^j(F_{x_0}).$$

The left-hand side is obtained by applying H^j and taking the colimit with respect to the open neighborhoods U of x_0 of $\text{R}\Gamma(I_\gamma^+(U); F)$. The right-hand side is similarly obtained when replacing $\text{R}\Gamma(I_\gamma^+(U); F)$ with $\text{R}\Gamma(U; F)$.

Since the family $\{I_\gamma^+(U) \cap q^{-1}(t_0 - a, t_0 + a)\}_{U,a}$ is a basis of open neighborhoods of x_0 by Definition 4.20, the result follows from Lemma 5.2. Q.E.D.

Main theorem

Proposition 5.4. *Let $f: X \rightarrow Y$ be a continuous map. and let $\mathcal{T}$ be a full triangulated subcategory of $D^b(\mathbf{k}_X)$. Assume:*

- (a) *f is surjective,*
- (b) *the functor $f^{-1}: D^b(\mathbf{k}_Y) \rightarrow D^b(\mathbf{k}_X)$ takes its values in $\mathcal{T}$,*
- (c) *the functor $Rf_*: \mathcal{T} \rightarrow D^b(\mathbf{k}_Y)$ is fully faithful.*

Then $Rf_: \mathcal{T} \rightarrow D^b(\mathbf{k}_Y)$ is an equivalence.*

Proof. It is enough to prove that f^{-1} is fully faithful, that is $Rf_* \circ f^{-1} \simeq \text{id}$.

Let $G \in D^b(\mathbf{k}_Y)$ and set $F = f^{-1}G$. Let $y \in Y$ and choose $x \in X$ with $f(x) = y$. By the hypothesis, $(f^{-1}Rf_*F)_x \simeq F_x$, hence $(Rf_*F)_y \simeq F_x$. Therefore, $(Rf_*f^{-1}G)_y \simeq (f^{-1}G)_x$. The result follows since $(f^{-1}G)_x \simeq G_y$. Q.E.D.

Applying Propositions 5.3 and 5.4, we get:

Theorem 5.5. *Let (M, γ, q) be a G^+ -causal manifold. Then the functor $R\varphi_{\gamma*}: D_{\gamma^{oa}}^b(\mathbf{k}_M) \rightarrow D^b(\mathbf{k}_{M_\gamma})$ is an equivalence of categories with quasi-inverse φ_γ^{-1} .*

Example 5.6. Let $M = \mathbb{S}^1$ be the circle and denote by x a coordinate (hence, $x = x + 2\pi$) on M , $(x; \xi)$ a coordinates system on T^*M . Consider the cone $\gamma = \{(x; w); w \geq 0\} \subset TN$. Then (M, γ) is a causal manifold, $\gamma^{oa} = \{(x; \xi); \xi \leq 0\}$. The only γ -open sets are M and $\emptyset$. Therefore, the only sheaves on M_γ are the constant sheaves. The functor φ_γ^{-1} is not essentially surjective. Indeed, the sheaf $\mathbf{k}_I$ belongs to $D_{\gamma^{oa}}^b(\mathbf{k}_M)$ for I the interval $(a, b]$, $|b - a| < 2\pi$. This example does not contradict Theorem 5.5 since (M, γ) is not G^+ -causal.

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